

Tables of Contents



- 2) An analysis of the influence of temperature related weather changes on humans' activities of daily living
- 3) An Ultimate Frisbee App
- 4) Anime Recommender System
- 5) Basketball AI referee
- 6) Brain Cognitive Project
- 7) Control system for reconfiguring straight liquid wiring within advanced communication system
- 8) Design and Evaluation of Learner-Facing Learning Analytics Dashboards
- 9) Design and Implementation of Aspect-based Sentiment Analysis for Game Reviews
- 10) Eye tracking data analysis and visualisation software
- 11)Intelligent-based Prediction Model for the Smart Electricity Grid
- 12)Iterative Development of Market-Compatible Mobile Apps for Local Insurance Company
- 13) Minimal RISC-V Microprocessor Design
- 14) Quantifying and Supporting Students' Learning Behaviour and Engagements
- 15)Real-time LSTM-Autoencoder Behaviour Anomaly Detection for Industrial Robot Arm on Nvidia Jetson Nano
- 16) Research on Brain White Matter Dynamic Functional Connectivity in Patients with Brain Arteriovenous Malformations (AVM)
- 17) Synthetic-to-Realistic Object Rendering for 6D Object Pose Estimation
- 18)Technology Policy Text Analysis Based on Latent Dirichlet Allocation Topic Model
- 19) Tool for Planning and Visualising Traffic Movements
- 20) Trajectory prediction mechanism in VANET for privacy protection





An analysis of the influence of temperature related weather changes on humans' activities of daily living



Ruijie Ni

Project Supervisor: Dr Stefan Poslad

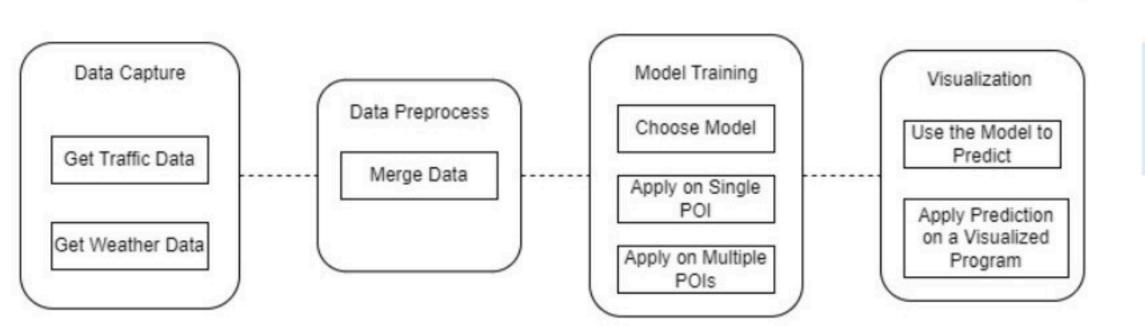
Objective & Background

This study uses Chinese urban traffic data to model how temperature changes affect population activity and distribution in different places of interest (POIs). A deep learning approach is used to predict the population density around POIs based on temperature and POI data. The results are visualized on an interactive map and can help government departments in urban planning and management.

POI: Point of Interest

A POI is a location that is useful or interesting to someone to do something specific. POIs can be used for various applications and have some basic attributes. Different sources may have different POI databases and APIs.

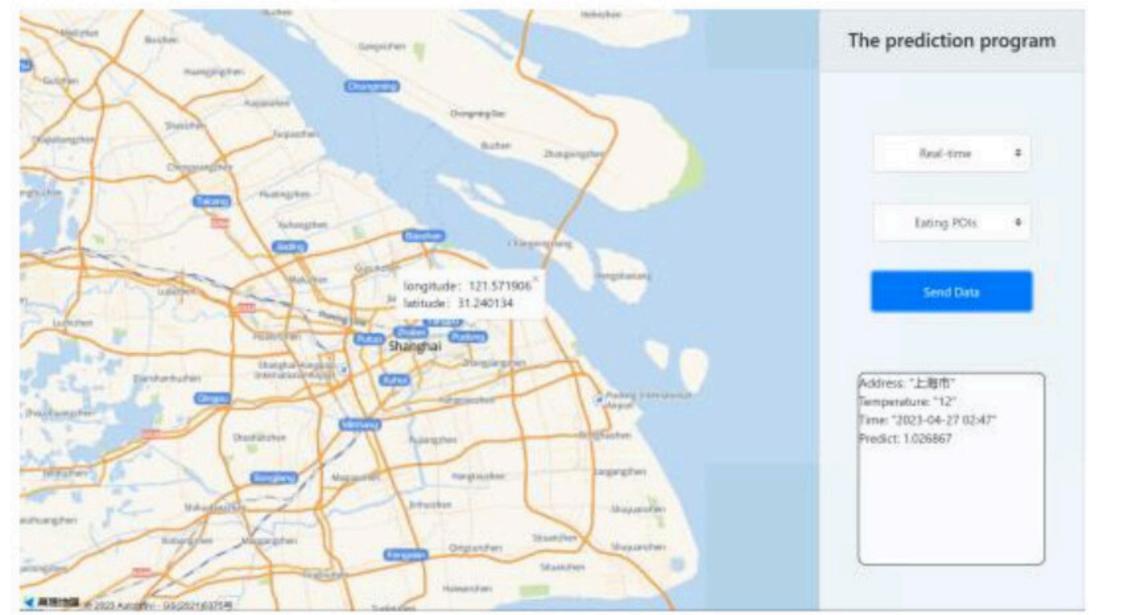
Overall Design



Outcome

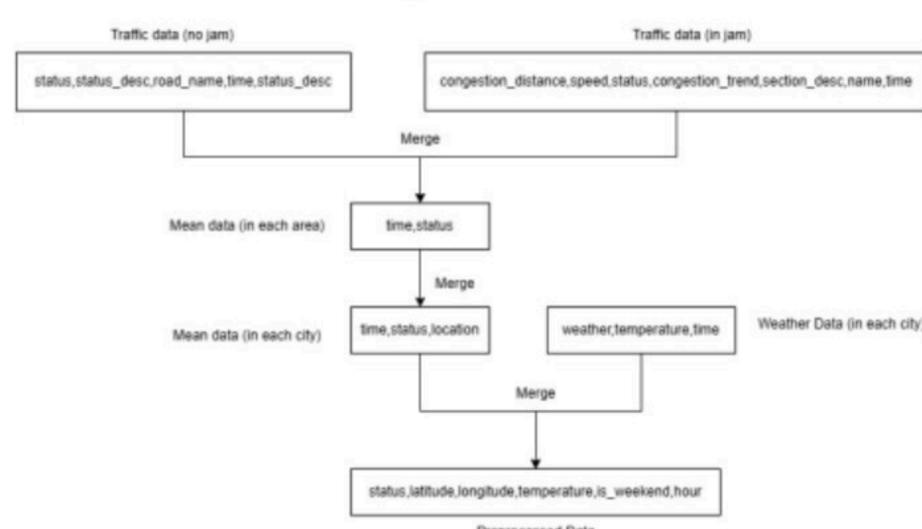
An interactive Population Prediction program Scan the QR code for a video demonstration





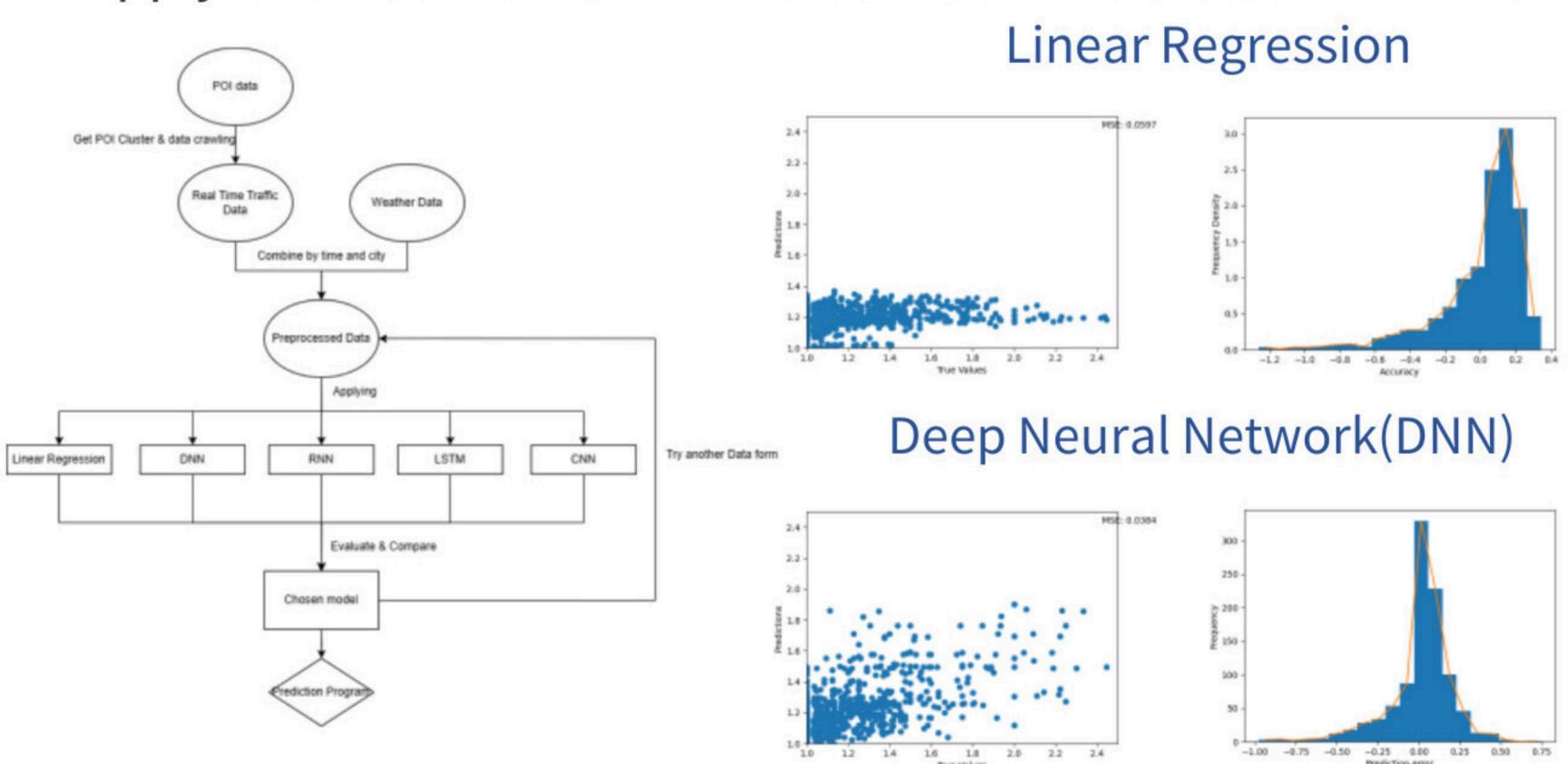
Data Capture & Merge

- No access to real-time population data from data platforms
- Estimate population density from traffic congestion instead
- Traffic status values from 1 to 4, indicating from smooth to congested.
- Data included: POI, Traffic status, Temperature
- Data Platforms: Baidu & Gaode open platform
- Group POIs into clusters by location for analysis



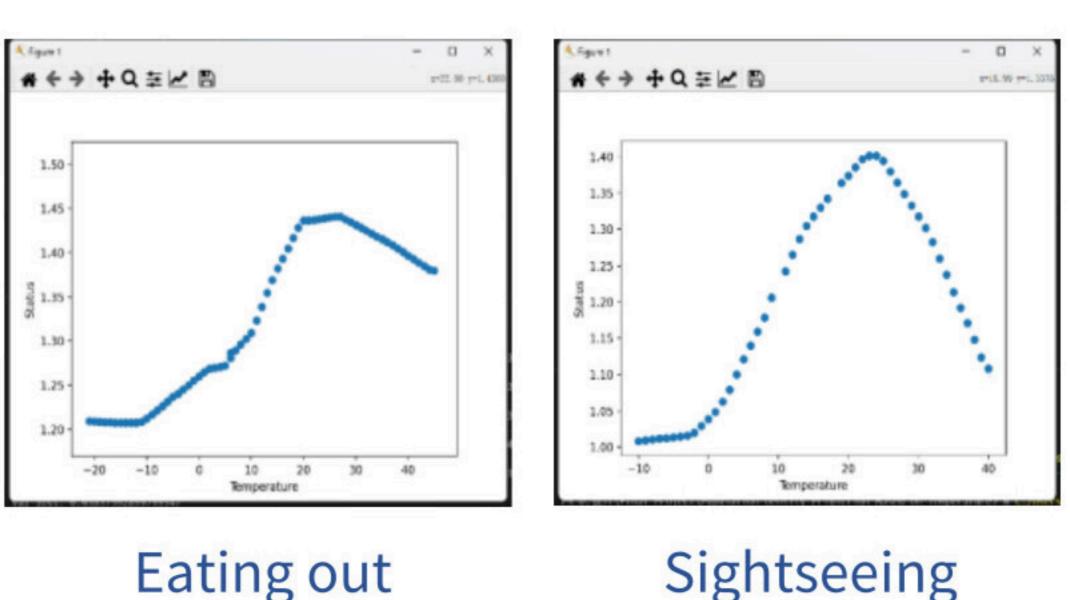
Model Training

- Use Linear Regression as baseline
- Apply different neural networks to find the best one DNN

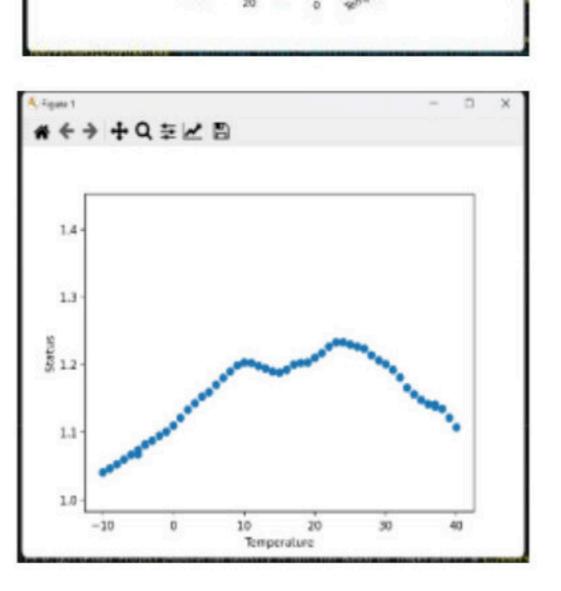


Visualisation & Analysis

- Real data is influenced by multiple factors
- Using prediction model fix other factors
- Analyze the effect on POIs



Sightseeing



Sports

© JP Student Innovation Centre (http://www.eecs.qmul.ac.uk/bupt/jpic/)

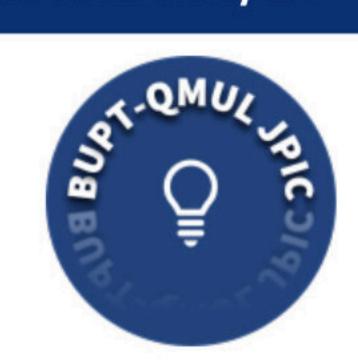




An Ultimate Frisbee App

Mengshi Li Project Leader: Dr Ling Ma

< PLAYBOOK

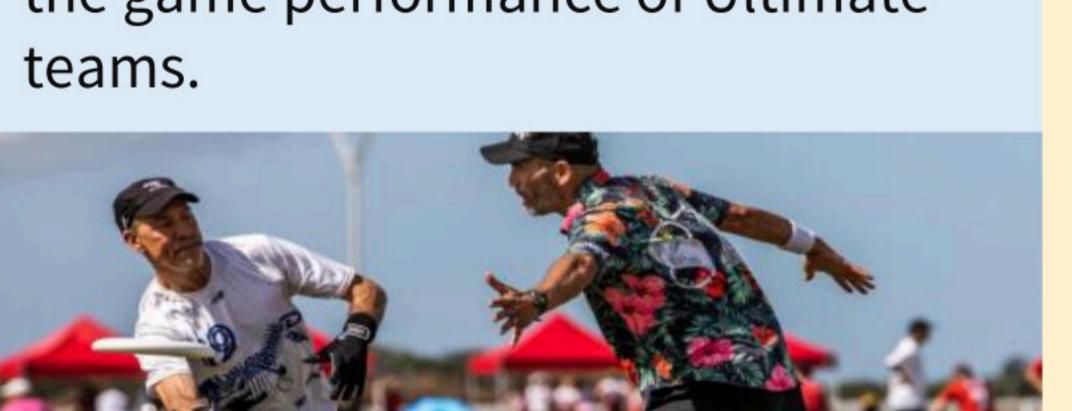


Guides &)

Tutorials

Objective & Background

Ultimate Frisbee is a popular non-contact team sport played with a disc. Tactical arrangements and game analysis are vital for a team to success in this sport. However, traditional paper-based methods are of low intuitiveness and efficiency. The project designed and implemented a smartphone app for Ultimate players and coaches, which provides features like a virtual animated playbook and a digitalized game analysis module, which is verified to have a positive impact on the game performance of Ultimate



Endzone | Special | Speci

GAME TRACKING

Virtual

Playbook

Pre-work & Requirements

- Similar app evaluation
 - 4 Apps
- Potential user interview
 - 7 pro players & coaches
 - Offline interview
- User stories and requirements
 - Summarized from interview records and app evaluation report
- Sketch prototyping
 - Planning basic layouts of the app

Development and Testing

Gadgets & >

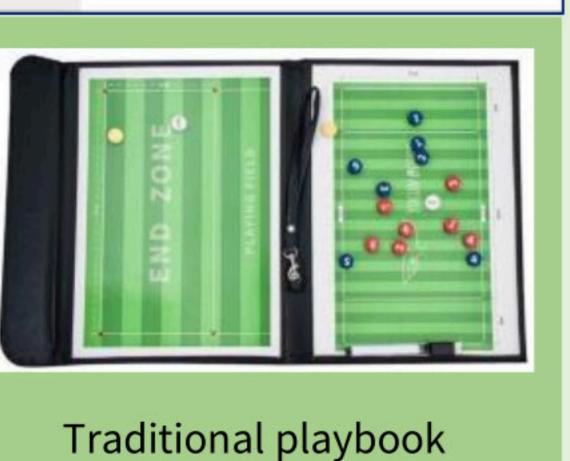
Toolbox

Game

Tracking

- Agile Development Process
 - Iteration based, rapid increment, constant user feedback
 - 3 main iteration
- Android development
 - Android Studio
 - Java, XML
- Version Control
 - Based on Git
- Testing
 - Unit + system testing
 - Real-world testing





Overshoot Drop Simulation

main module #1

the Virtual Playbook

The virtual playbook allows the users to design and deliver Ultimate tactics in an intuitive and efficient way.

The "**Drag and Drop**" feature allows the users to quickly and accurately set up a formation of any nodes in a tactic.

The users can generate a realistic non-linear animation of their tactic with a single click.
They can also switch to any node of a tactic easily or adjust parameters of the simulation.
This helps fast and precise delivery of tactical arrangements to team players.



main module #2

Game Tracking

This module allows the users to record real-time data during the game and provides data analysis with a visualised presentation of multiple useful information.

The users can quickly set the current players on the field before the game.

During the game, the users can record the events occurring on the field and the players.

record the events occurring on the field and the players corresponding to the event, such as passes, turnovers, drops, etc. After the recording is done, the application will automatically generate important data analysis of the game and present it in a visualised way.



Anime Recommender System

Yiran Wang Project Leader: Dr Mona Jaber

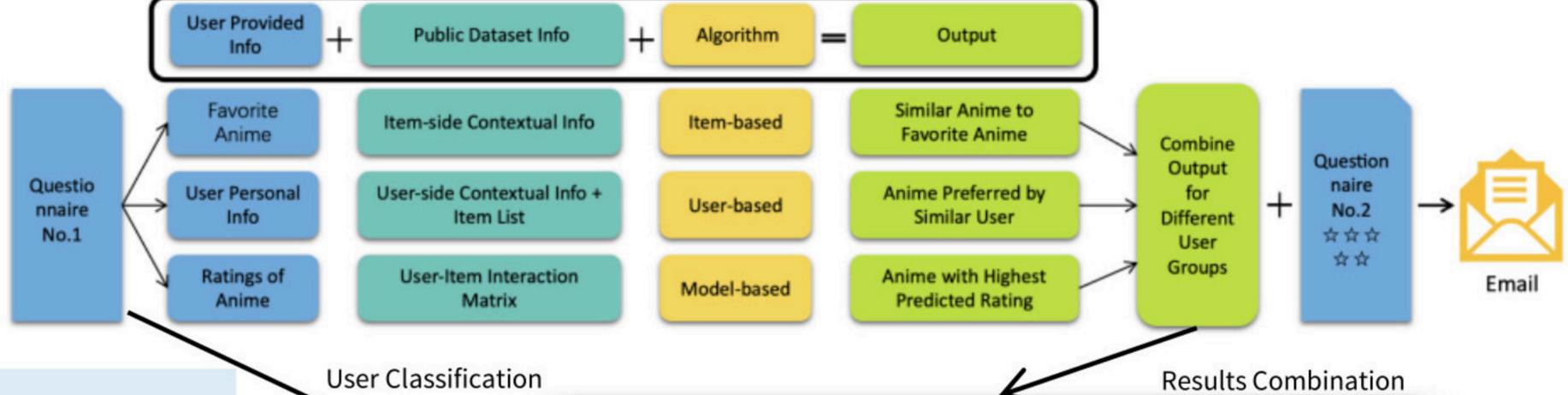


Introduction

The rapid development of the anime industry needs a recommender system that produces satisfied and precise recommendations for anime fans. In this project, a recommender system that combines results from matrix factorization and k-nearest neighbors is developed. The new proposed combined model is evaluated using Root Mean Squared Error (RMSE) and human evaluation, reaching a 1.39 RMSE value and a 4.24 human satisfaction score.

Design & Implementation

We first gather user information through questionnaire no.1 and concatenate it with information from the public datasets. Then we feed the information into the algorithms. Next, we classify users into 3 groups and adopt different result combination policies for different user groups. Finally, we send the results to the user, and ask the user to rate their satisfaction with the results through questionnaire no.2.



Background

There are three categories of recommender system algorithms: contextual methods, collaborative methods and hybrid methods.

Contextual methods are divided into item-based and user-based methods based on features used. Collaborative methods are divided into memory-based and model-based methods based on whether models are used. Hybrid methods mix contextual and collaborative methods.

We proposed a new hybrid method that combines results from the model-based collaborative method, the user-based contextual method, and the itembased contextual method.

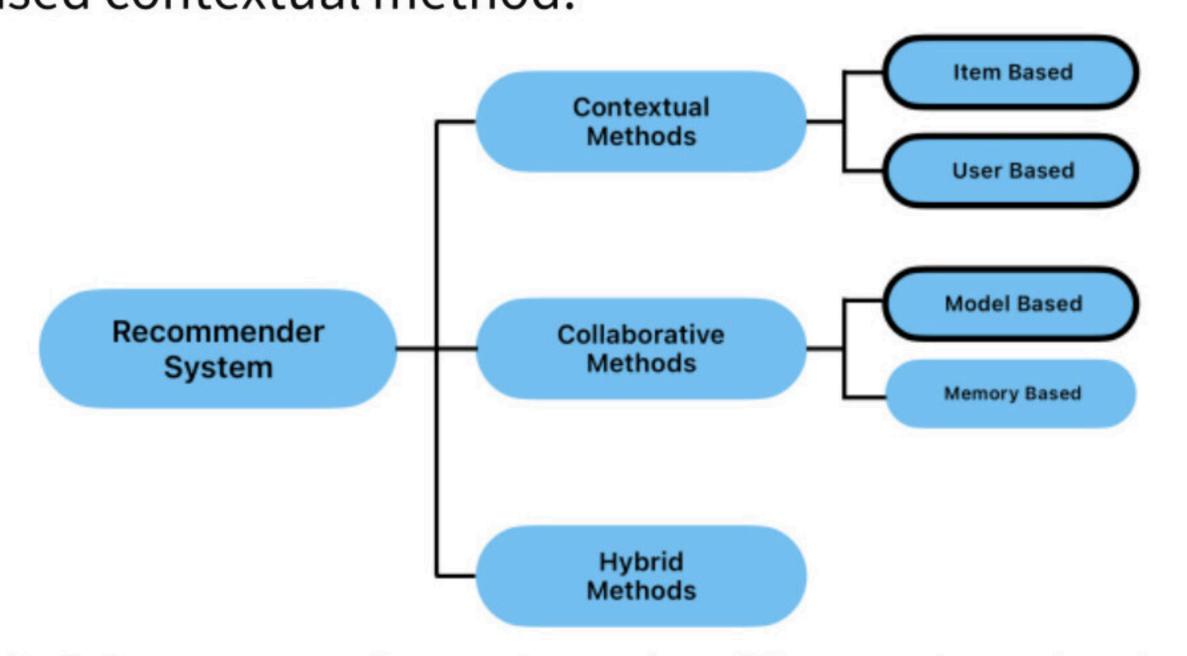


Fig 1 Recommender system algorithms categorization





Fig 2 QR code for questionnaire no.1(left) & questionnaire no.2(right)

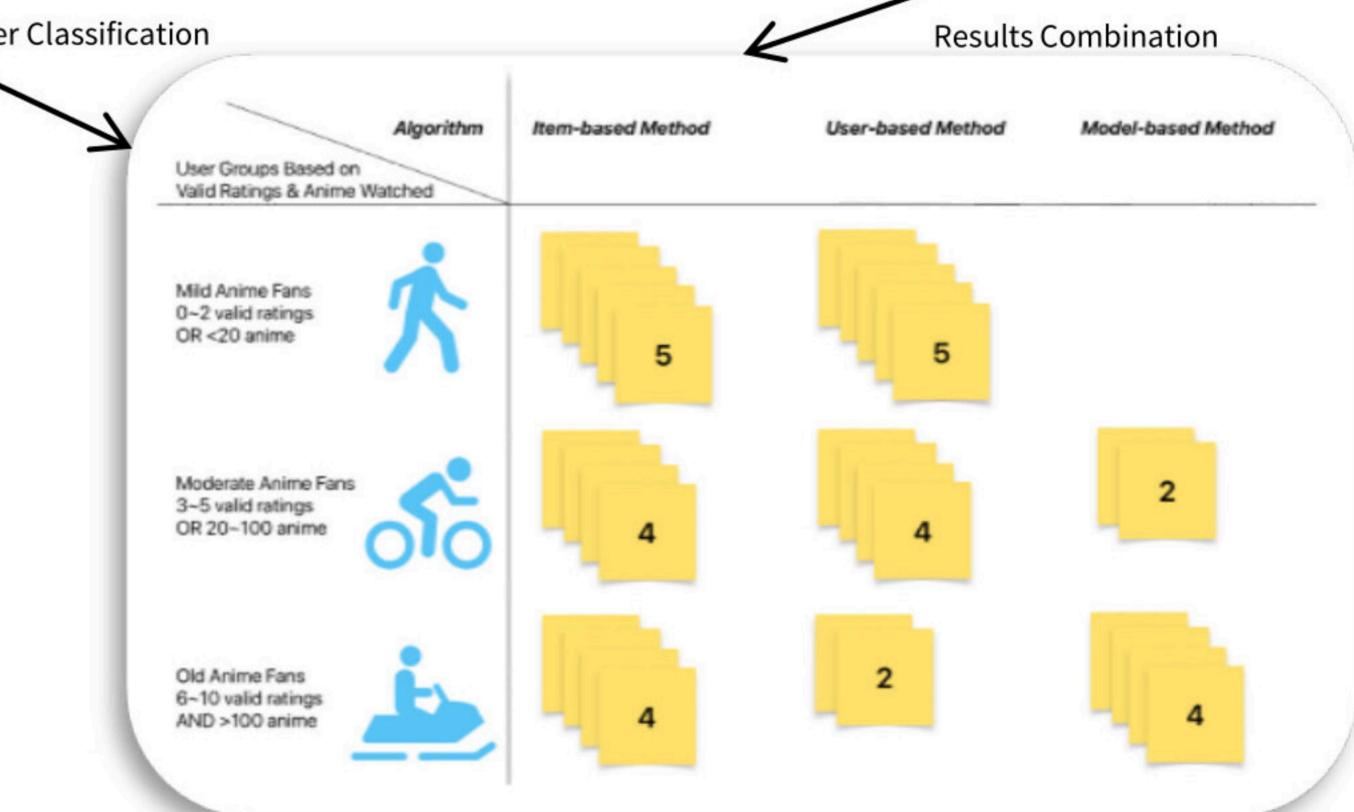


Fig 3 System structure illustration

Results & Conclusions

We evaluate the system from metrics-based evaluation and human-based evaluation. The metrics-based calculates the root mean square error, which represents the distance between the predicted rating and the ground truth and smaller value means better performance. The human-based involves real people to rate their satisfaction with the recommendation results, with '5' meaning very satisfied and '1' meaning very unsatisfied. The system reached a 1.39 RMSE after comparing 3 algorithms and 4.24 human satisfaction score after 2 rounds of testing.



Fig 4 Work conclusions



Basketball AI referee

Jingqing Zhang, Xingtianwen Zhang, Jiahui Cui Project Leader: Mona Jaber



A.Introduction

 This project investigates how Al can be used to referee a basketball game and detect violations such as travelling or double dribble.

B. Three components to this project

- Use an existing dataset with accelerometer data to detect the action of a single player at any time: dribble, pass, shoot, pick up, hold. Next, a sequence of actions will be analyzed to detect violation.
- Use hardware implementation to collect more data from players - the data will be used to improve the AI model for detecting violations.
- Website and database design to detect violations remotely based on sensor data.

C.Dataset (partially displayed)

We used a dataset, which consists of 80 text files collected by three testers.

Accelerometer (x, y, z):Located at the right arm. Gyroscope (R, phi, delta):Located at the right arm.

Same app use, as the accelerometer.

Example:

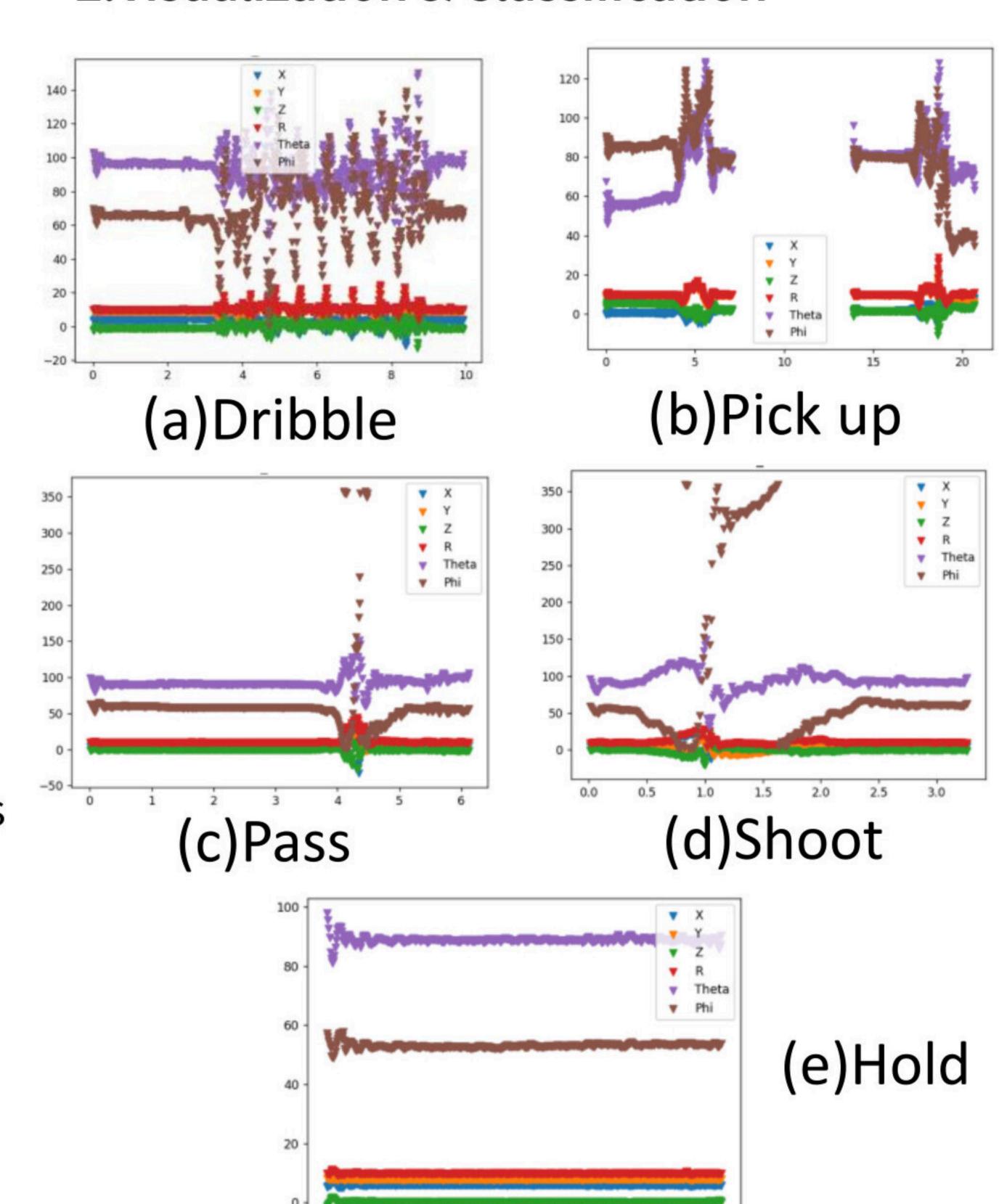
LAGII	ipie.					
Time(s)	X(m/s2)	Y (m/s2)	Z (m/s2)	R (m/s2)	Theta (deg)	Phi (deg)
0.00000	3.4284	9.1123	-2.0470	9.9488	101.87	69.381
0.00970	3.4476	9.2859	-2.3319	10.176	103.24	69.631
0.01973	3.5063	9.2128	-2.2445	10.109	102.82	69.631
0.02970	3.7038	8.9722	-1.9907	9.9087	101.59	67.568
0.03980	3.9025	8.7998	-1.5454	9.7496	99.120	66.083
0.04981	3.9947	8.5975	-1.0845	9.5421	96.526	65.078
0.05997	4.2509	8.7639	-0.7852	9.7721	94.609	64.124

D. The sensors and application we used

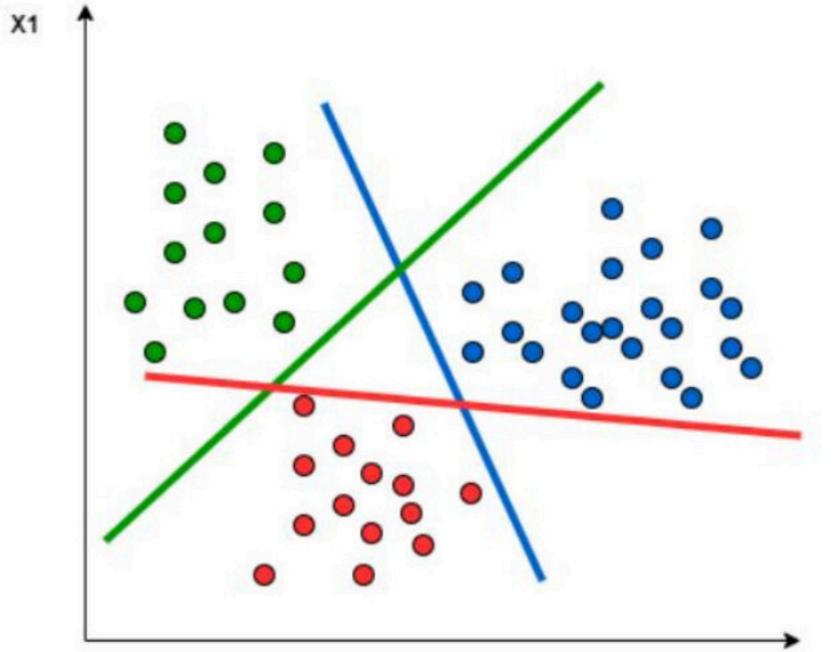




E. Visualization & Classification



F.Support vector machine (SVM)



Accuracy (Polynomial Kernel): 47.97 F1 (Polynomial Kernel): 64.84 TEST IN PICKUPDATA

Accuracy (Polynomial Kernel): 70.55 F1 (Polynomial Kernel): 76.54 TEST IN PASSDATA

Accuracy (Polynomial Kernel): 46.46 F1 (Polynomial Kernel): 63.44 TEST IN DRIBBLEDATA

Accuracy (Polynomial Kernel): 61.85 F1 (Polynomial Kernel): 76.43 TEST IN HOLDDATA

Accuracy (Polynomial Kernel): 99.21 F1 (Polynomial Kernel): 99.61



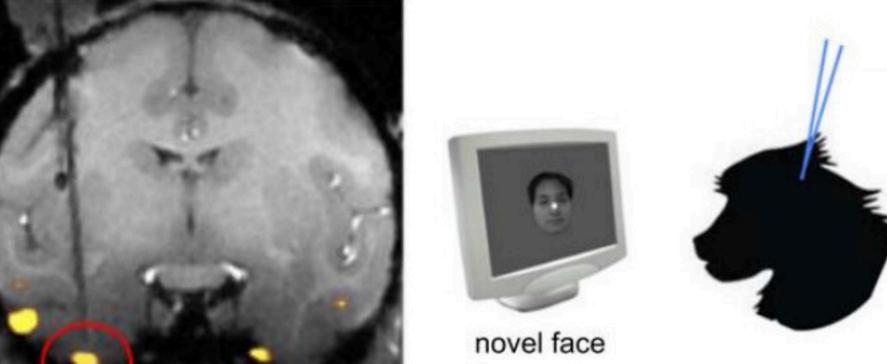
Brain Cognitive Project

Jifeng Xu, Zhixiang Zhang Project Leader: Dr. Cindy Sun



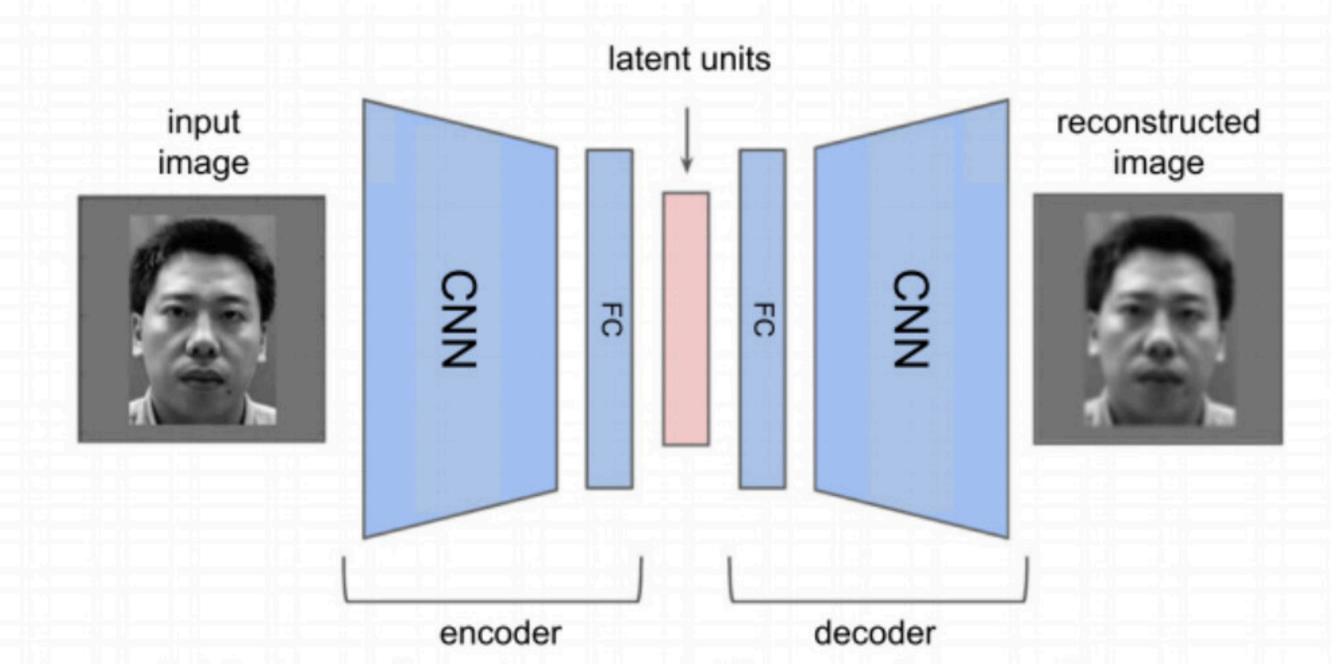
Background

With the development of artificial intelligence image feature recognition, people try to explore the corresponding relationship between human brain neurons and face image features. After acquiring the electric signal data set of ape neurons after observing face images and combining with β -VAE model based on convolutional neural network, our team obtained the correlation matrix between neurons and latent variables of human face after a series of mathematical operations.



Model: β-VAE

β-VAE is a deep learning model based on convolutional neural network.[2] Images are inputed in the form of matrix. After four layers of convolution operation, images are unwrapped, and after four layers of deconvolution operation, images are reconstructed. The sketch map is as follows.[1]



https://github.com/google-research/disentanglement_lib

Dataset

- ① A matrix of electrical signals from neurons in the brains of apes looking at a dataset of faces.[1]
- ② A total of 159 neurons responded to 2,100 pictures of faces. An example of face data set is as follows:



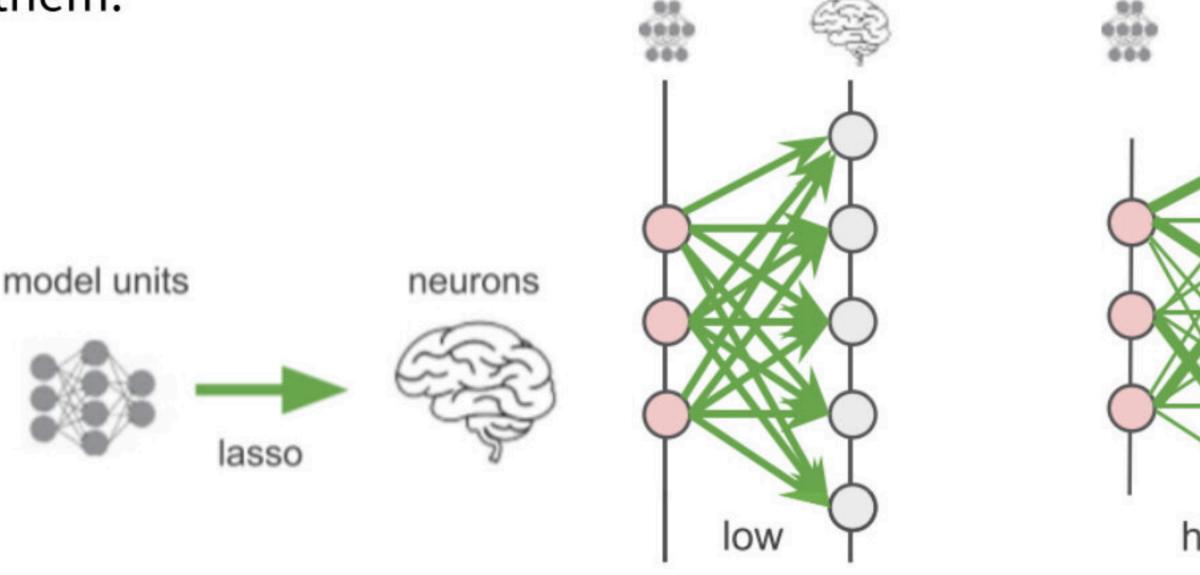




Pictures are from the AR Face Database, CelebA, Chicago Face Database, CVL, FERET, MR, PEAL dataset.

Method

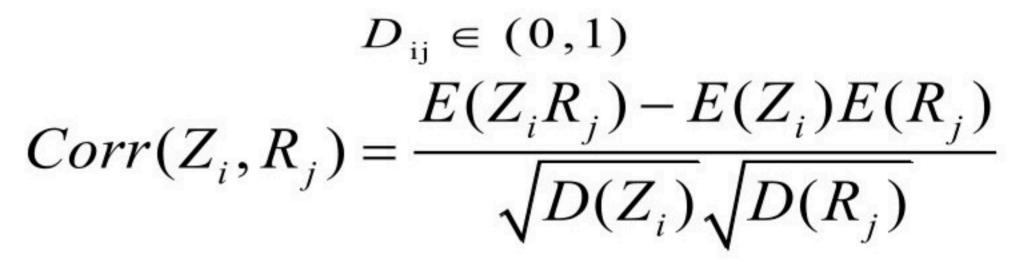
The above face data sets are inputted to β-VAE model[2] in the form of matrix, and latent variable unit matrix is extracted during training model, including its mean and variance. Then take the ape EEG data set, take the average operation and calculate the mean variance. The correlation coefficient between the latent variable unit and the ape EEG signal was calculated, and the Hungarian algorithm was used to match them.



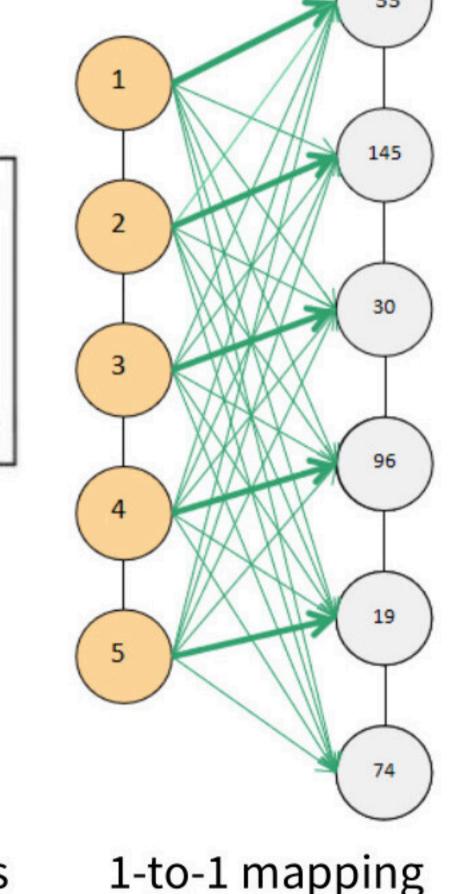
Output

The Pierce correlation coefficient of neurons and latent variables become the elements of the correlation matrix D_{ij}, as shown below.

$$D_{ij} = \begin{bmatrix} Corr(Z_1, R_1) & \cdots & \cdots & Corr(Z_1, R_{159}) \\ \vdots & \cdots & \cdots & \vdots \\ \vdots & \cdots & \cdots & \vdots \\ Corr(Z_{50}, R_1) & \cdots & \cdots & Corr(Z_{50}, R_{159}) \end{bmatrix}$$



Correlation matrix of neurons and latent variables



latent

neuron

Conclusion & Next Step

By applying the Hungarian algorithm to the correlation coefficient matrix, we observe 7/50 neuron-latent pair with correlation value above 50%.

How to interprete the meaning of latent regarding face recognization?

neurons	latent	Correlation
3	18	0.9477
10	34	0.8658
96	4	0.8477
104	45	0.7628
109	17	0.6711
110	28	0.6595

Reference

[1]Zhang, Y., Chen, Y., Zhu, X., et al. (2021). Deep learning for high-throughput quantification of oligodendrocyte ensheathment at single-cell resolution. Nature Communications, 12(1), 5427. https://doi.org/10.1038/s41467-021-26751-5 [2]Higgins, I. et al. β -VAE: learning basic visual concepts with a constrained variational framework. In Proceedings of the 5th International Conference on Learning Representations, ICLR (ICLR, 2017).



Control system for reconfiguring straight liquid wiring within advanced communication system

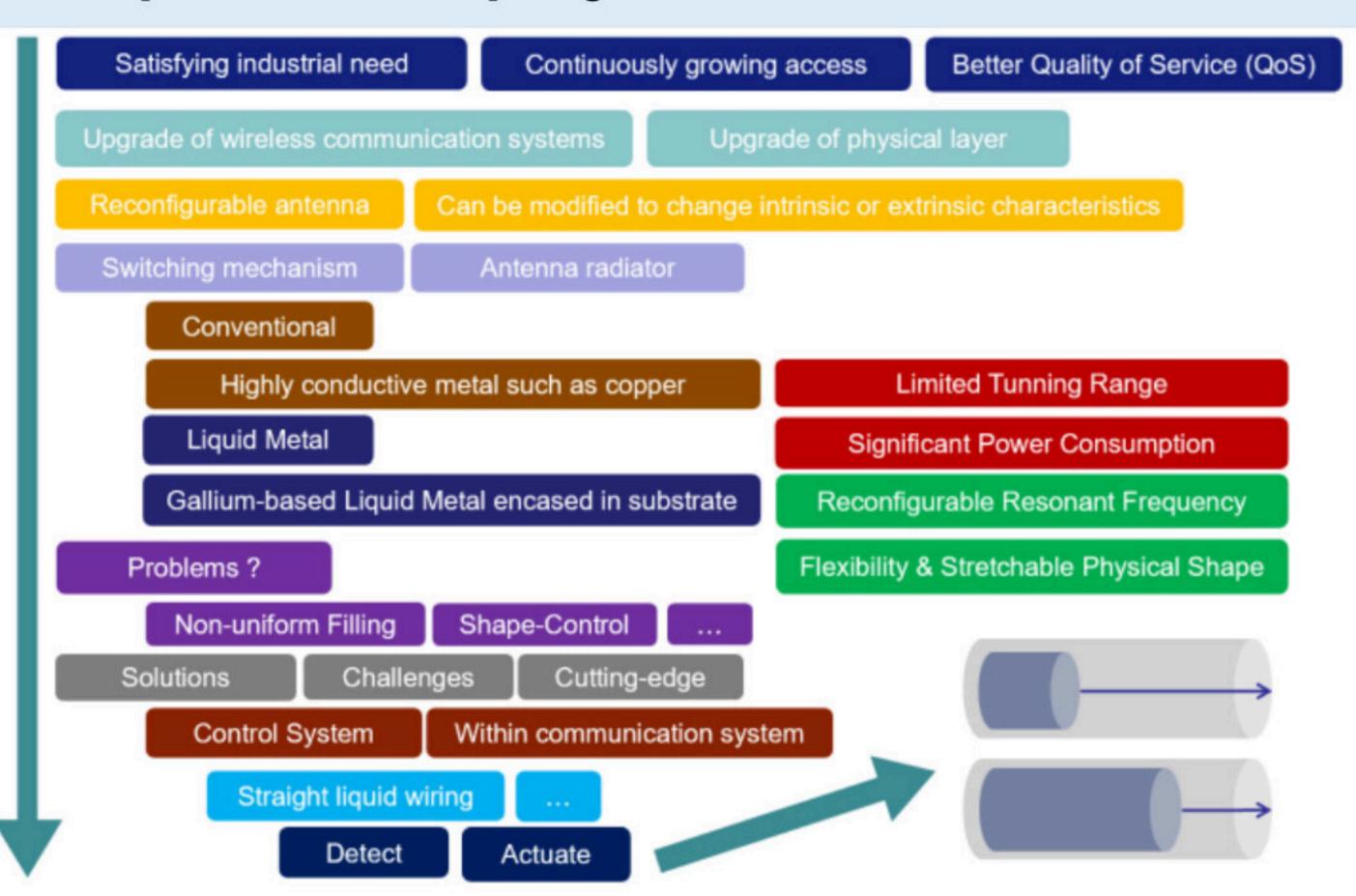


Yuanxin Xu

Project Leader: Dr James Kelly

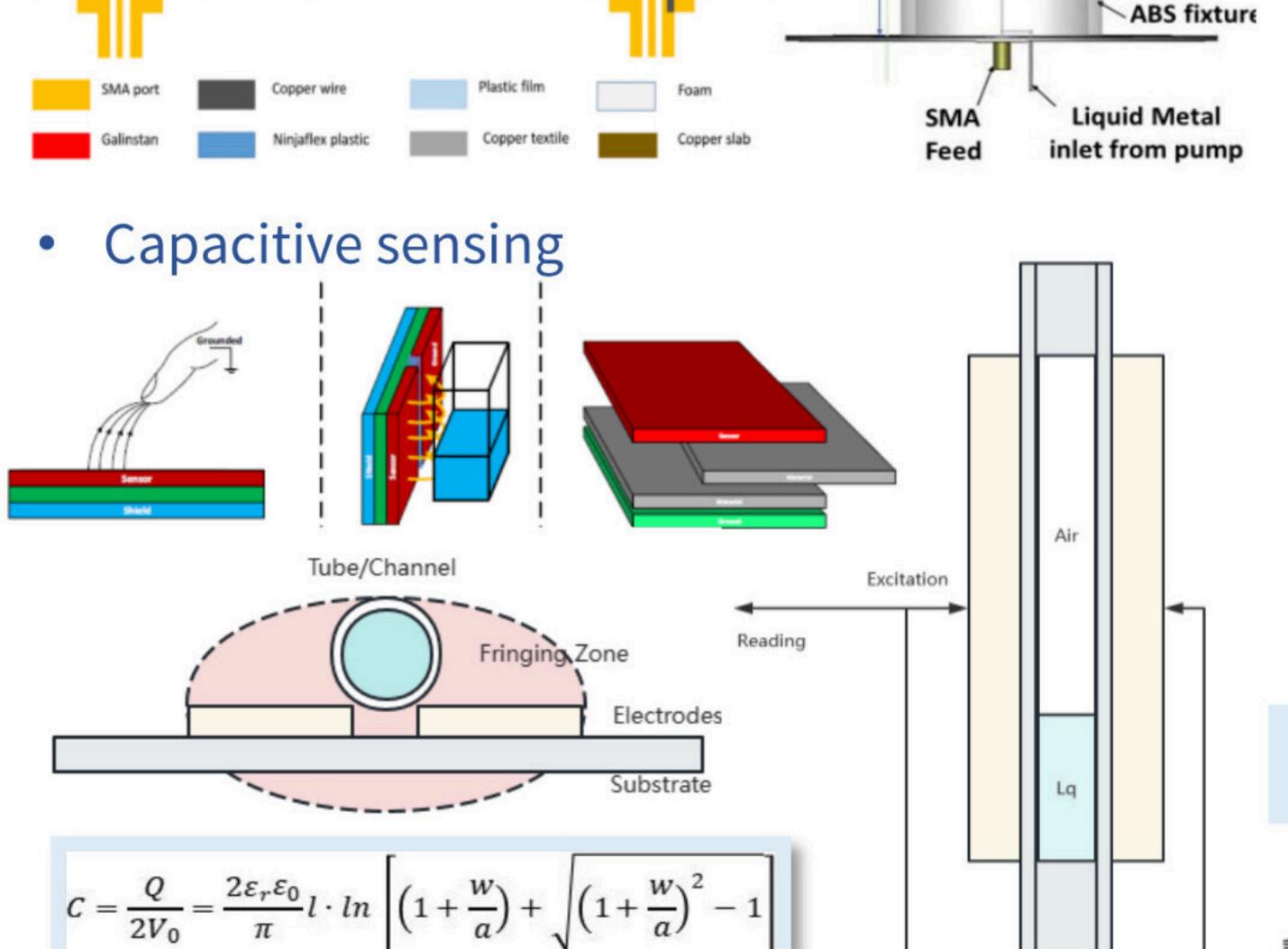
GalnSn

Purpose of the project

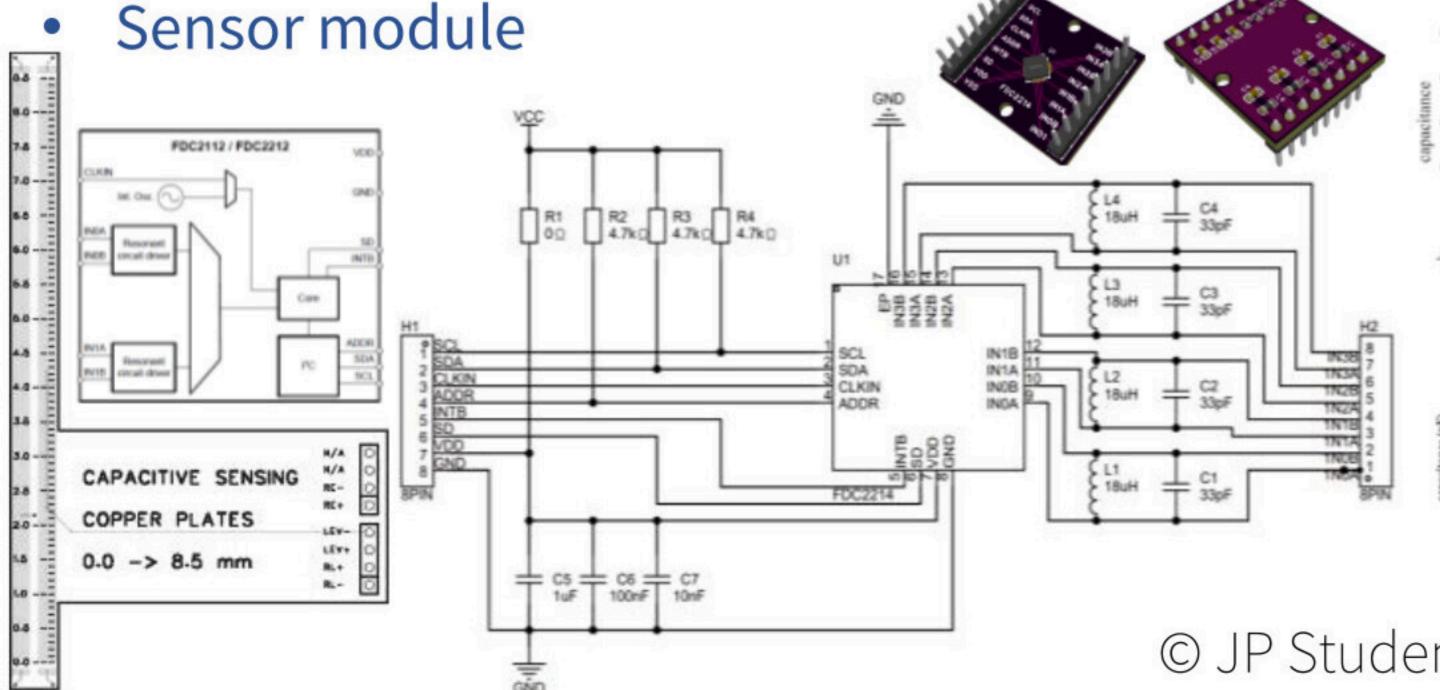


Background

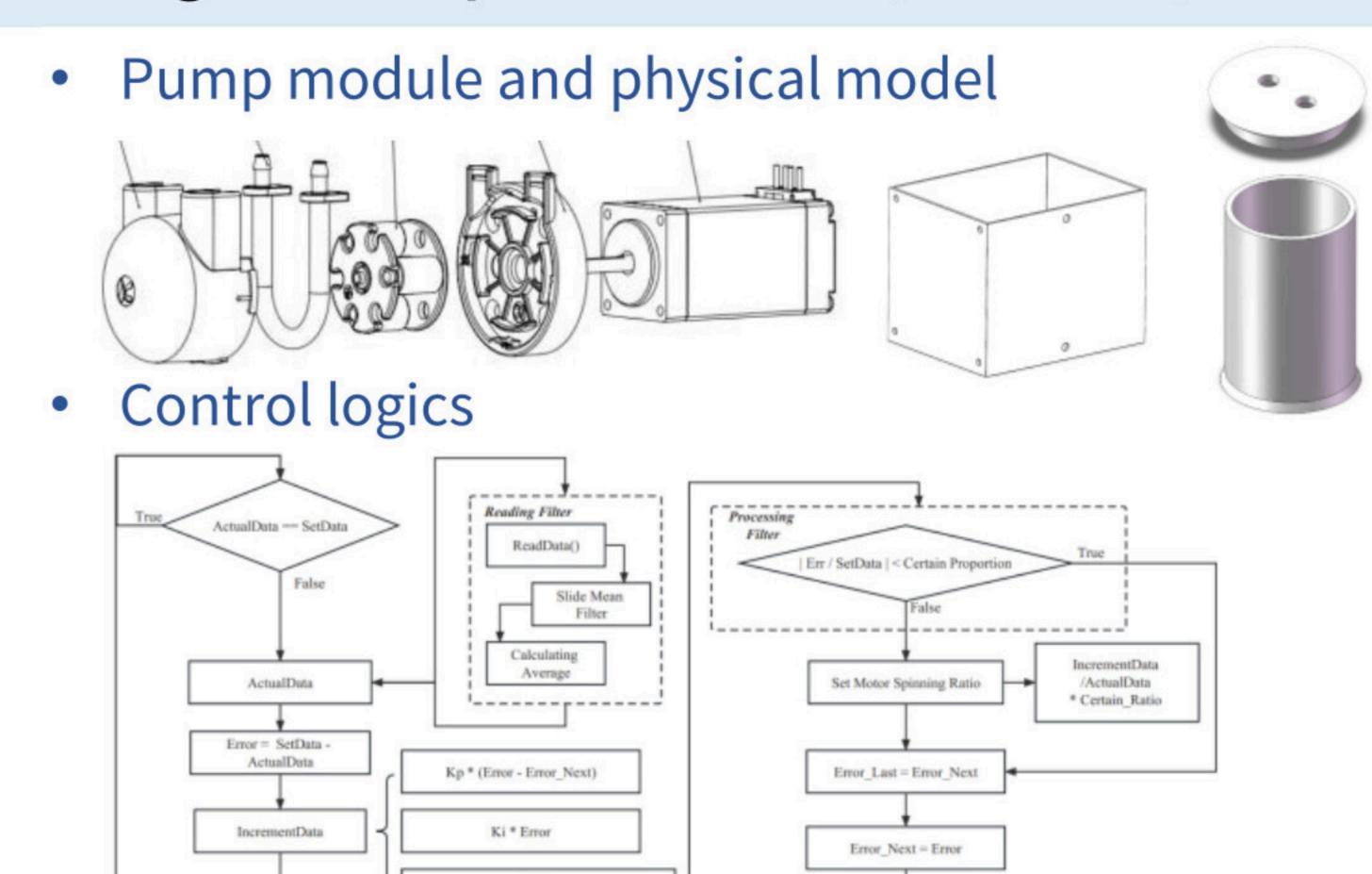
Reconfigurable antenna



Design and implementation

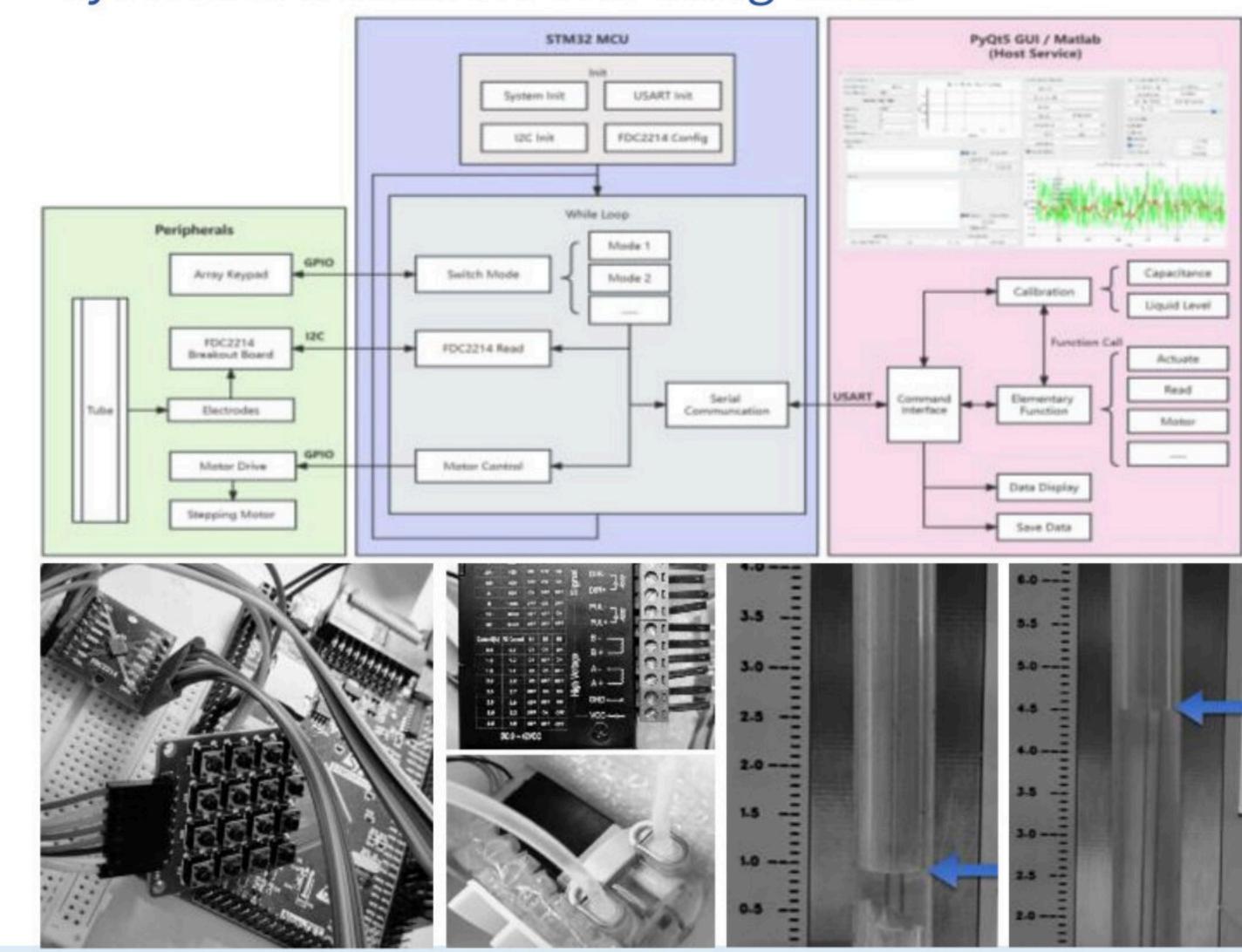


Design and implementation (Continue)



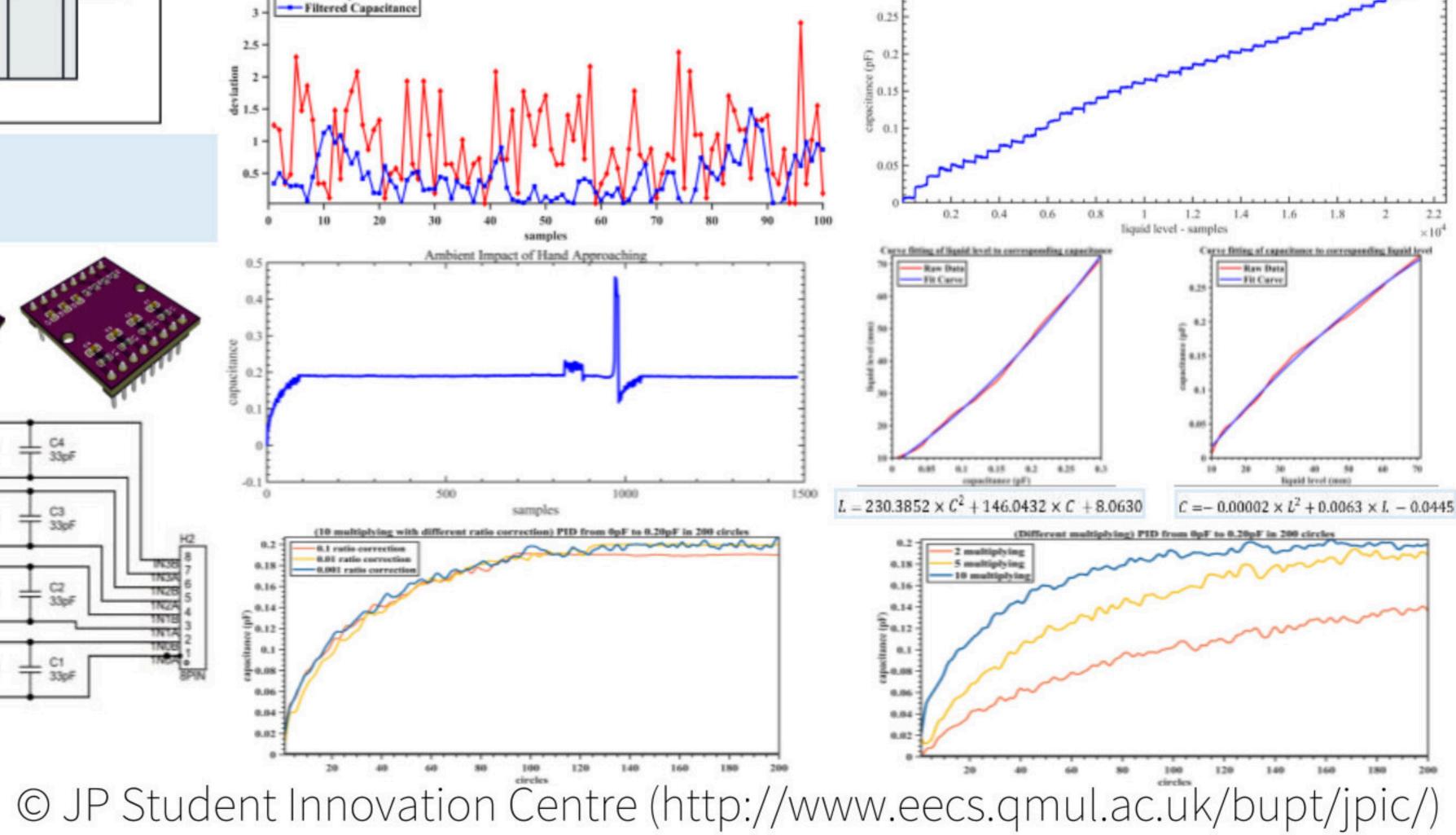
System architecture and integration

(Error - 2 * Error Next + Error Last)



Performance and analysis

Raw Capacitance







Design and Evaluation of Learner-Facing Learning Analytics Dashboards

Yingting Hao

Project Leader: Dr Marie-Luce Bourguet



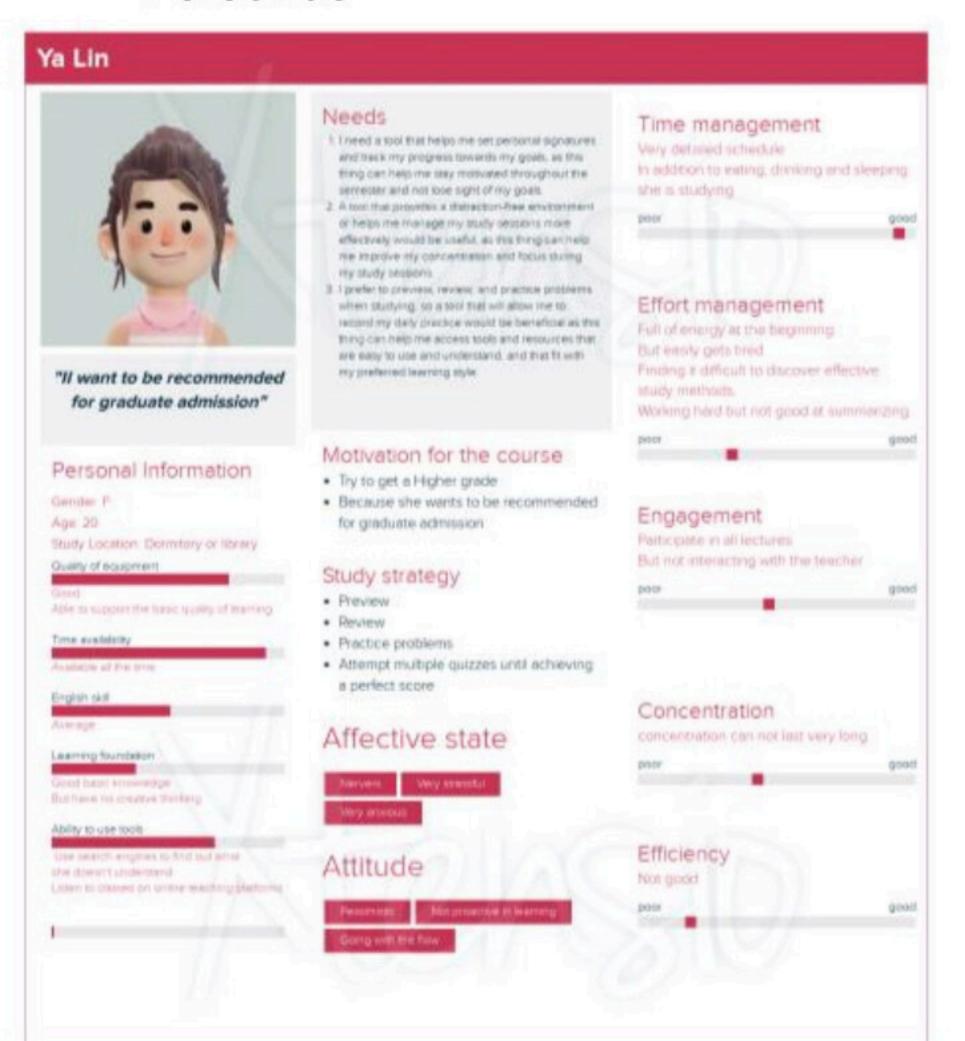
Intruduce

This project aims to design, develop, and evaluate Learner-Facing Learning Analytics Dashboards (LADs) for learners to better understand their learning progress. To achieve Student-Staff Co-creation, participatory design methods were used to collaboratively develop design documents with student users through a series of meetings. Three different layouts of LADs were implemented using Python. The effectiveness of LADs were evaluated through methods such as surveys, eye-tracking, and think-aloud protocols, indicating that it is an effective learning support tool that can improve learning outcomes and enhance the overall learning experience. This project provides new ideas and methods for the field of learning analytics and offers better learning support tools for students, making significant contributions.

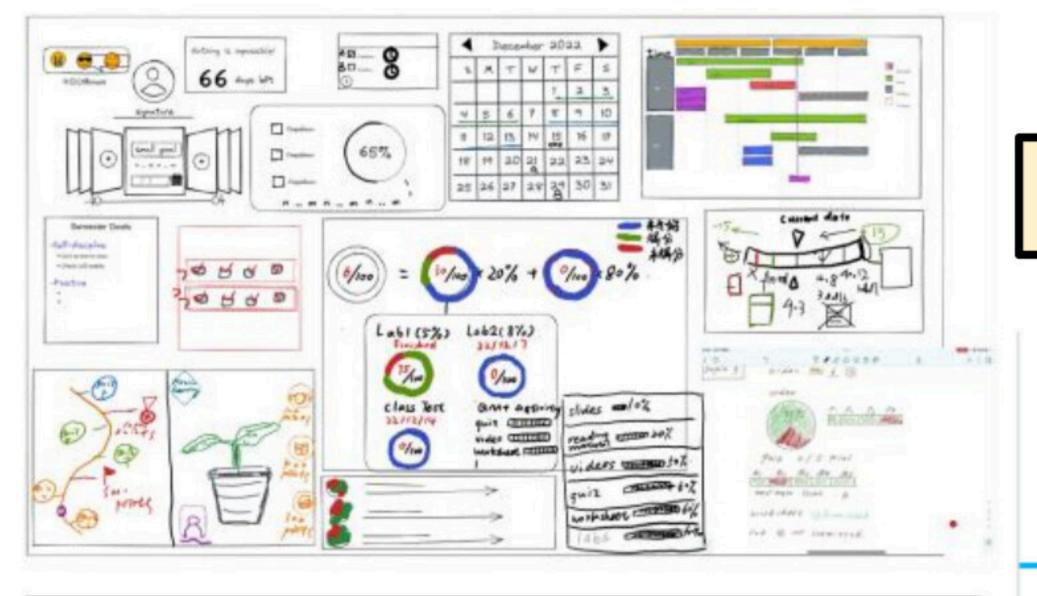
Design

Participatory design of the LAD

Personas

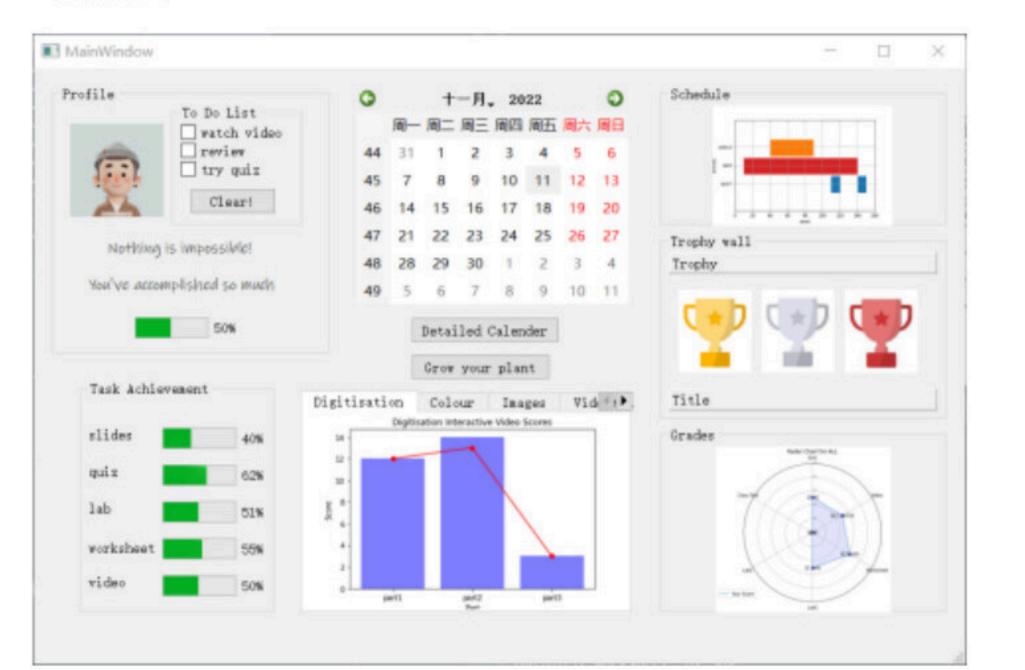


Paper prototypes

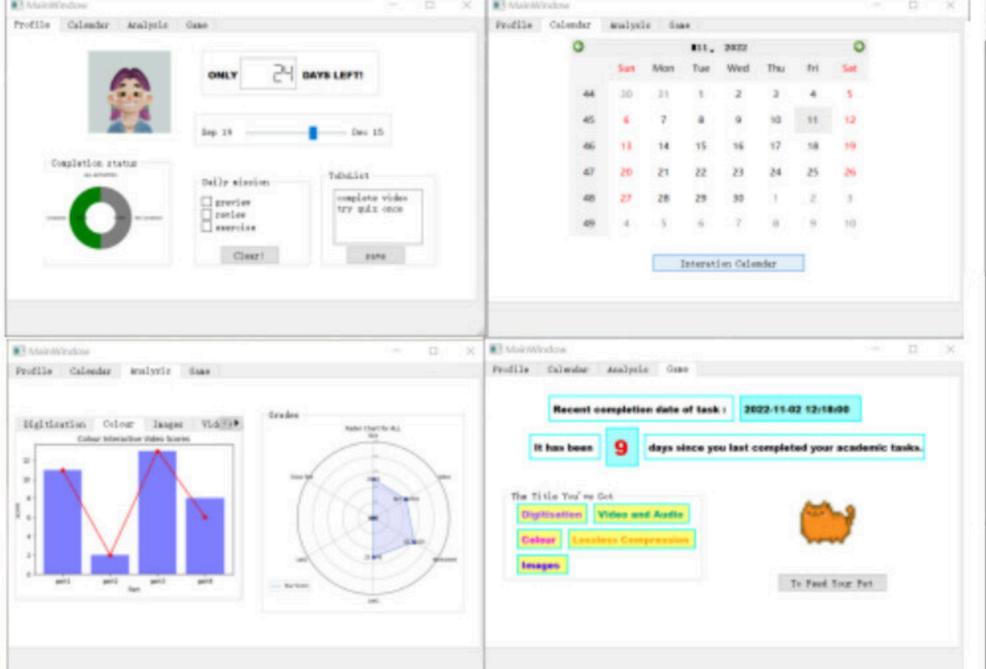


Implementation

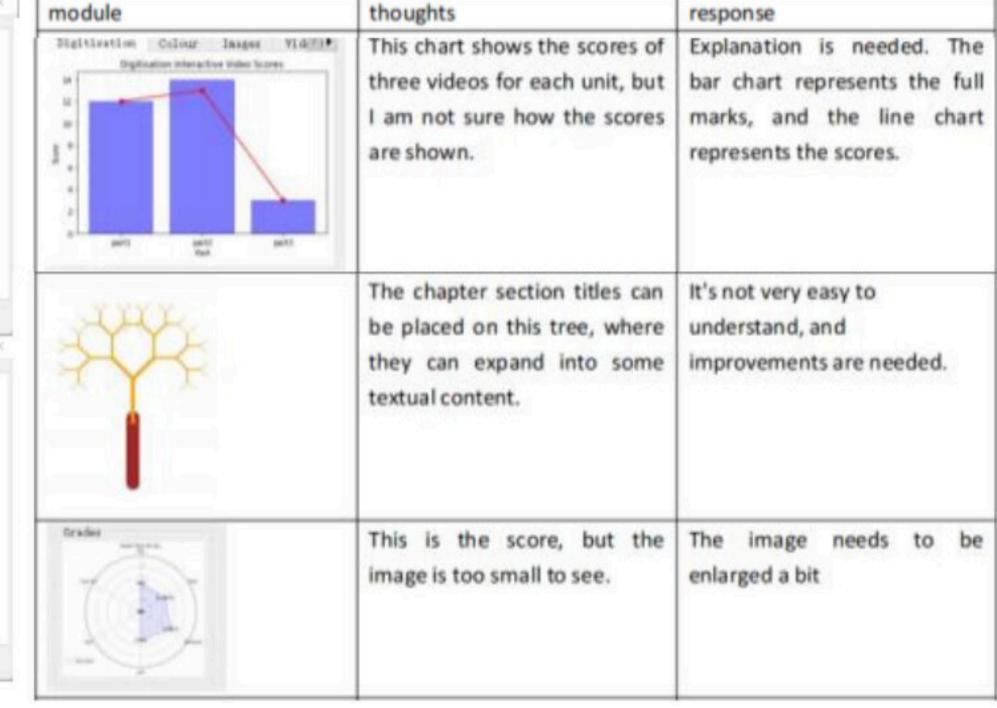
LAD1



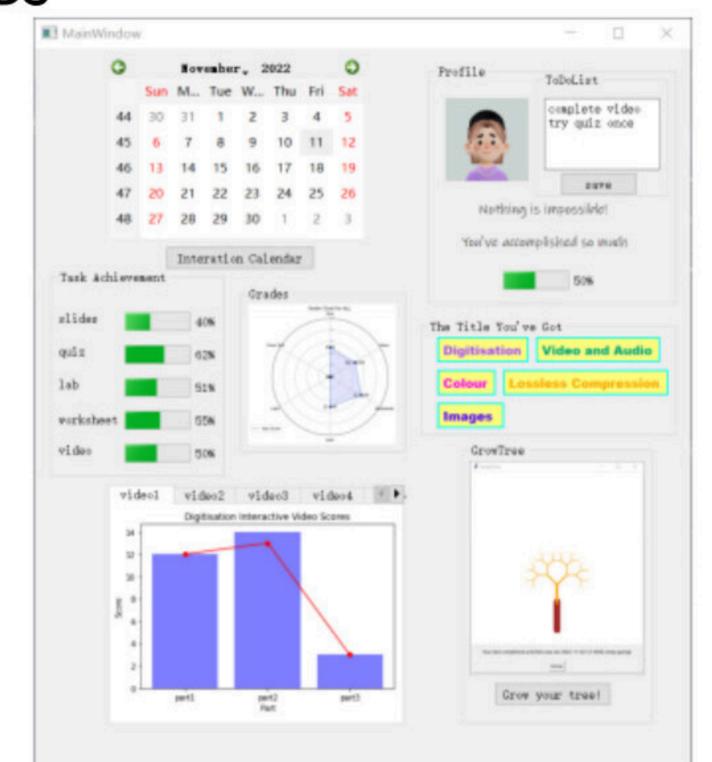
LAD2



Evaluation by think aloud protocols



LAD3



Optimized LAD design

You can scan this QR code to see the demonstration.

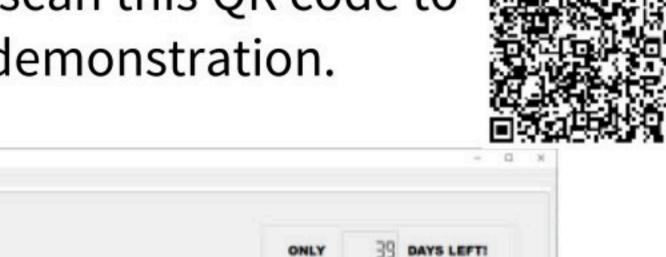
Nothing is impossible!

You've accomplished so muc

Completion status for all activities

Profile Galender Amalysis Game

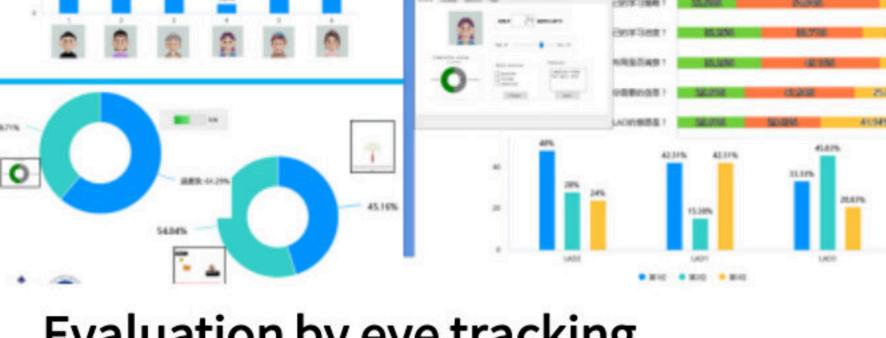
ToDoList.



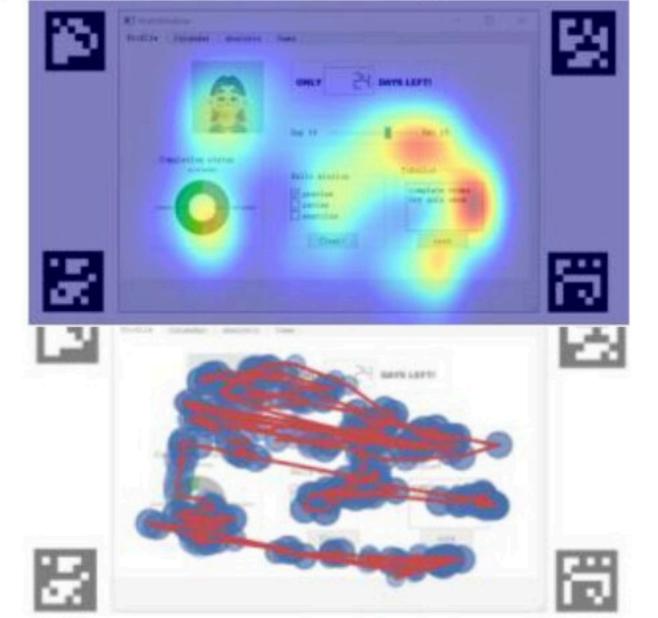
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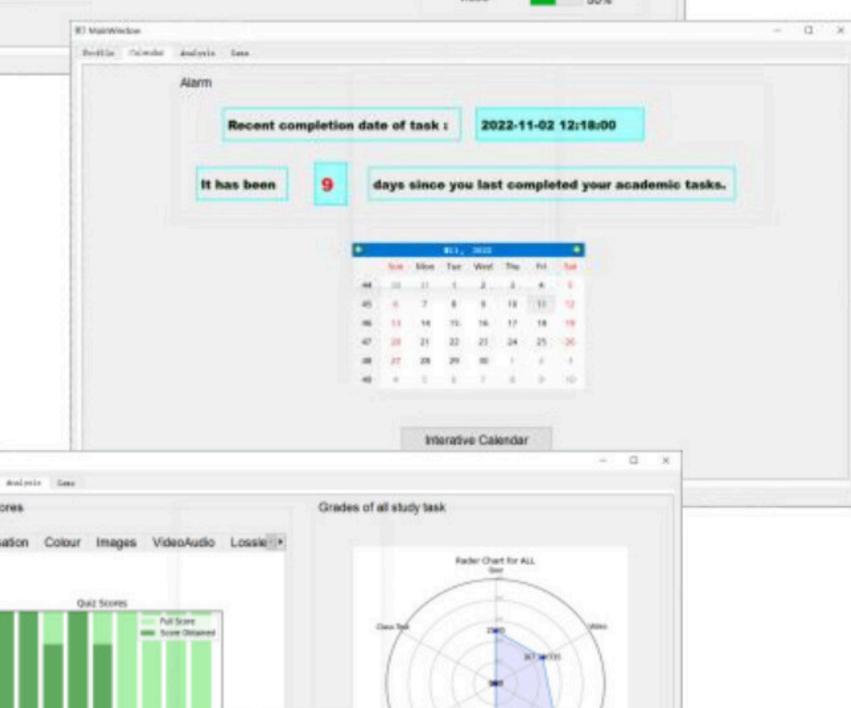
Evaluation

Evaluation by questionnaire



Evaluation by eye tracking









Design and Implementation of Aspect-based Sentiment Analysis for Game Reviews



Songyun Yang Project Leader: Prof. Li Ruifan

Problem Definition

The aspect base sentiment analysis is the subtask of NLP task, which aiming to find the fine-grain aspect and the attitude towards it in reviews.

The graphics are nice although the weapon is poor -- game comment

input

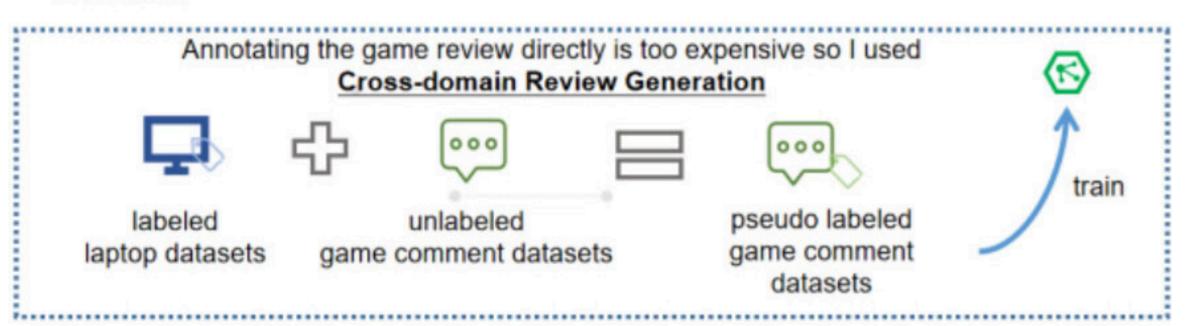
opinion
postive
negative

output

An example of ABSA task.

Major Work

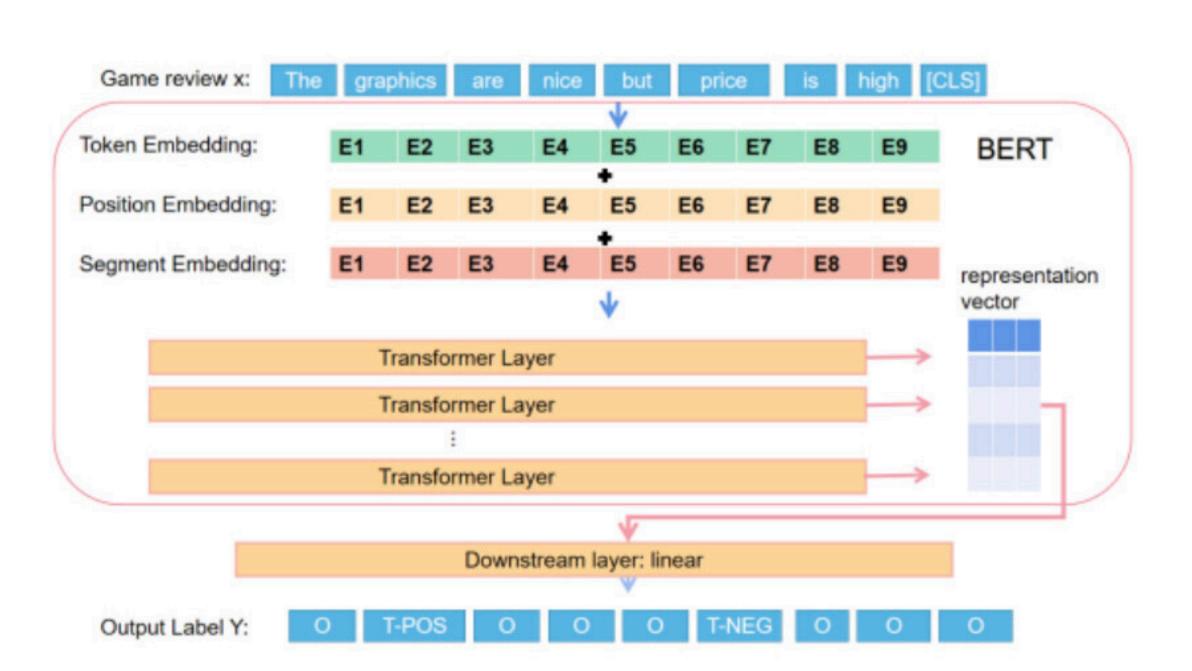
- Collect and process game reviews dataset for the task.
- Use crossing-domian data generation method to train a neural net work model of ABSA task.
- Design an interface for users to use the ABSA system.
- A series of experiments are done to verify the reliability of the model.



Cross domain review generation

-To label all the game reviews is too expensive. So I used another domain dataset with label to generate the game reviews and its label

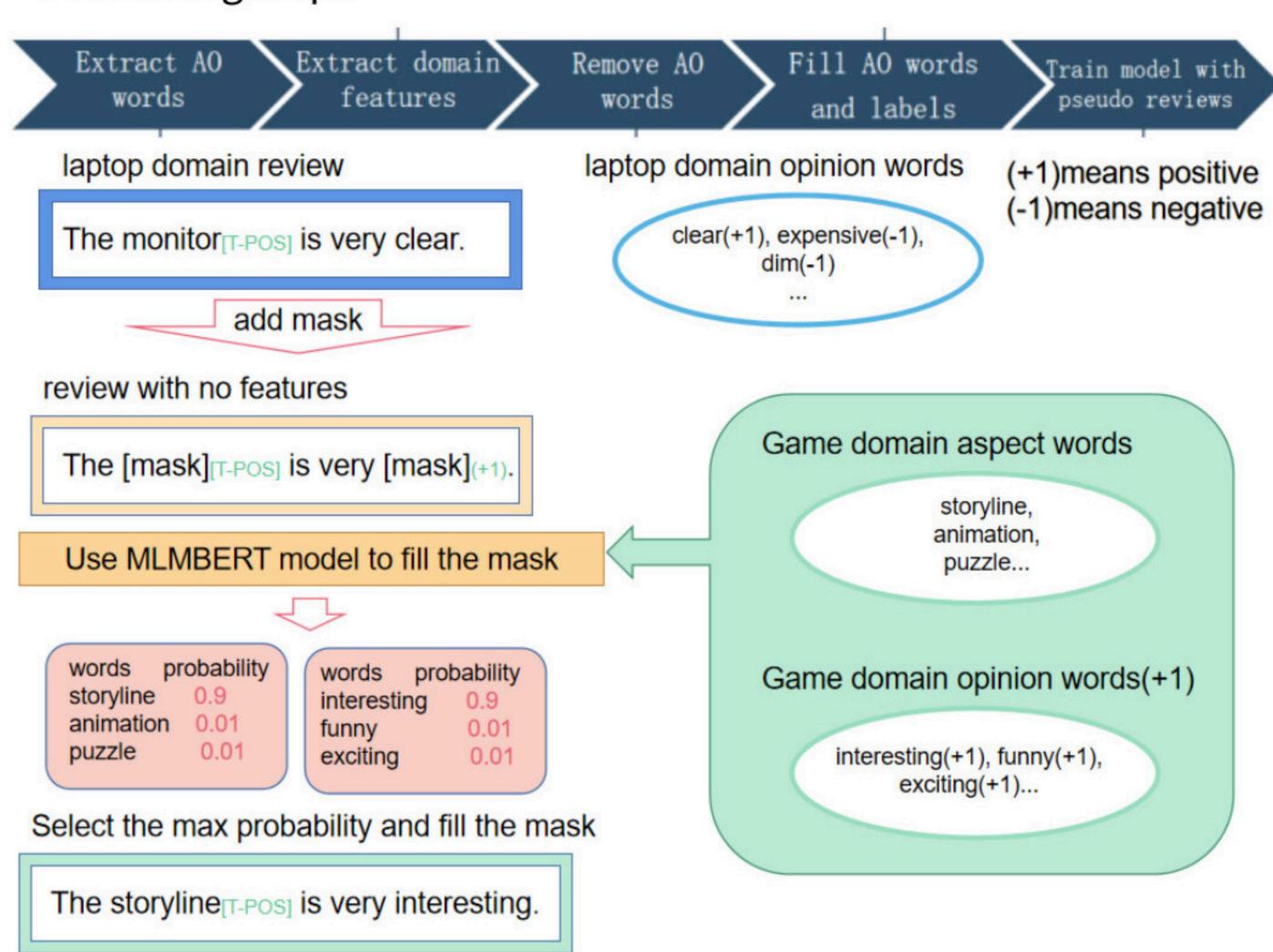
Neural Network



The structure of the neural network model. Model is designed based on BERT base model.

Methodology

Processing steps



Experiments

Performance of BERT fine-tune (NOT cross-domain)

Dataset	precision	recall	F1-score
Laptop	0.64	0.58	0.61
Restaurant	0.71	0.72	0.72
Device	0.61	0.58	0.6

Performance of the cross-domain reviews generating method in high-quality datasets' domain

Source domain	Target domain	precision	recall	F1-score
Laptop	Restaurant	0.53	0.5	0.52
Restaurant	Device	0.28	0.32	0.3
Device	Restaurant	0.58	0.51	0.54
Rest	Laptop	0.43	0.37	0.4

Performance of the cross-domain reviews generating method in game domain. (red:best perfomance)

Source domain	Target domain	precision	recall	F1-score
Laptop	Game	0.31	0.28	0.29
Rest	Game	0.37	0.31	0.33
Device	Game	0.41	0.44	0.42
Laptop+Game	Game	0.33	0.29	0.31
Restaurant+Game	Game	0.34	0.38	0.36
Device+Game	Game	0.45	0.48	0.46

Performance of the GPT compare with the Best model

	precision	recall	F1-score
OpenAl-Davinci	0. 31	0.87	0. 45
Cross-domain Best performance	0.45	0.48	0.46





Eye tracking data analysis and visualisation software

Han Di

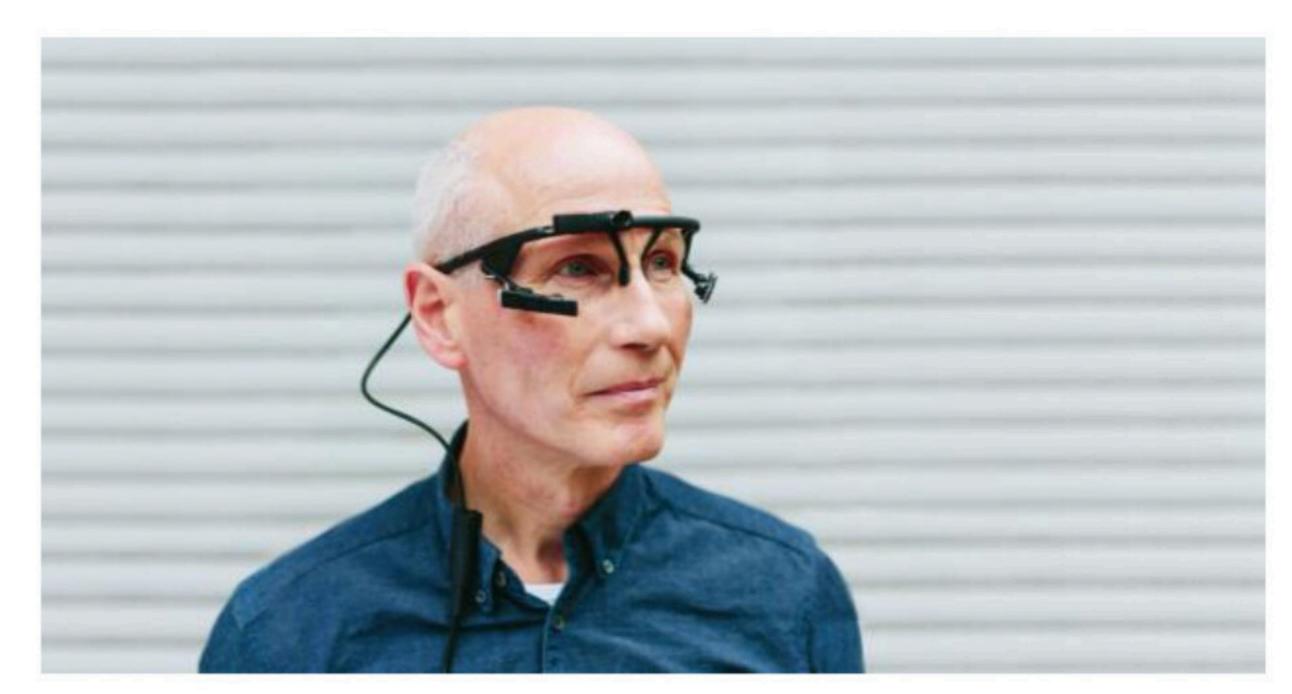
Project Supervisor: Dr Marie-Luce Bourguet



Abstract

Eye tracking is the process of measuring and recording the movement and gaze position of a person's eyes as they look at visual stimuli. The project aims to design software that can:

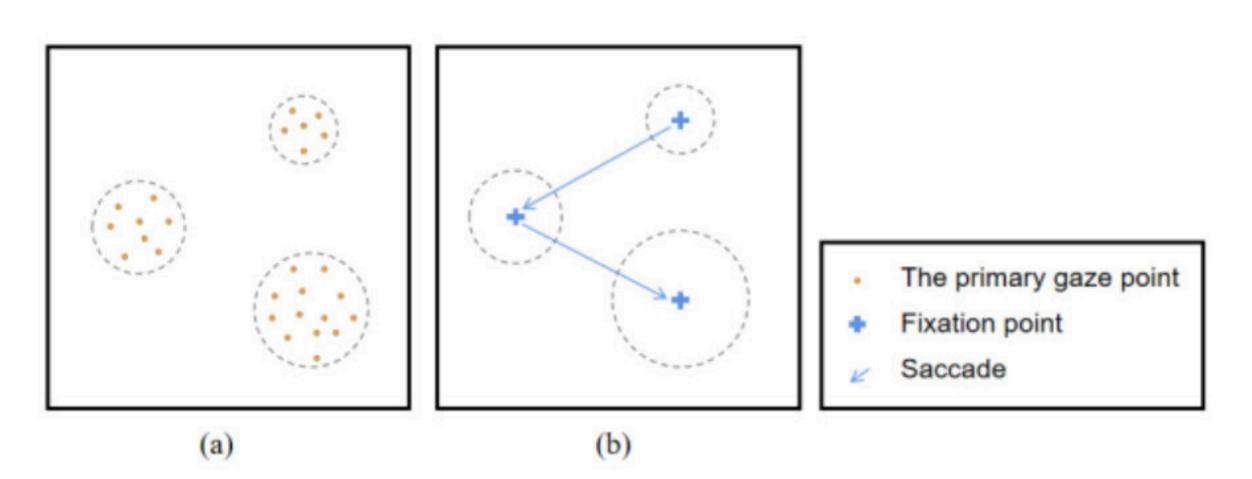
- Capture and record gaze data in real time
- Perform data analysis
- Create data visualisations



Eye tracker used to record eye movement (Device from Pupil Core)

Eye movement classification

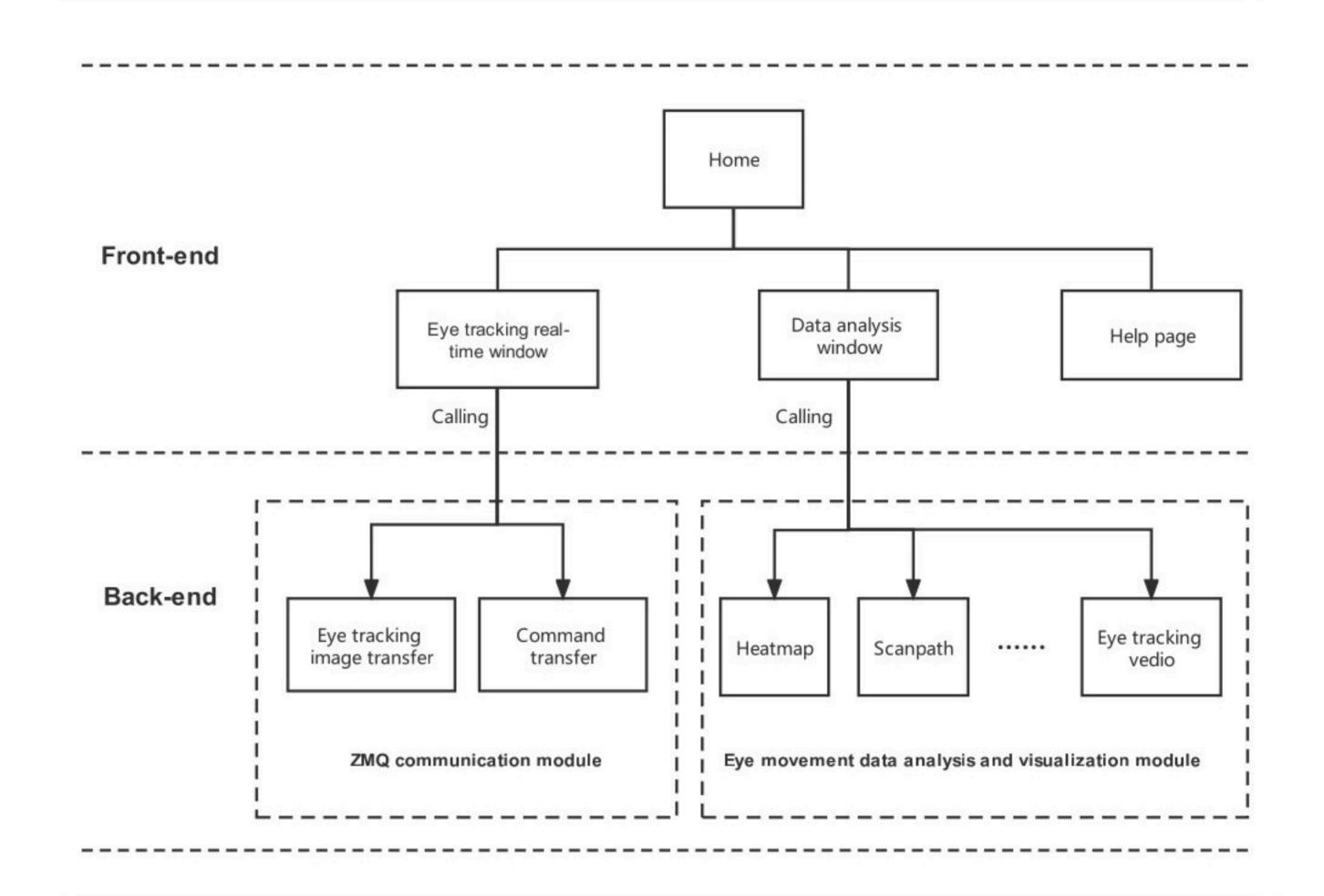
- Fixation (a): the gaze stays on the area of interest (AOI) for a certain amount of time.
- Saccade (b): the gaze moves from one AOI to another AOI.



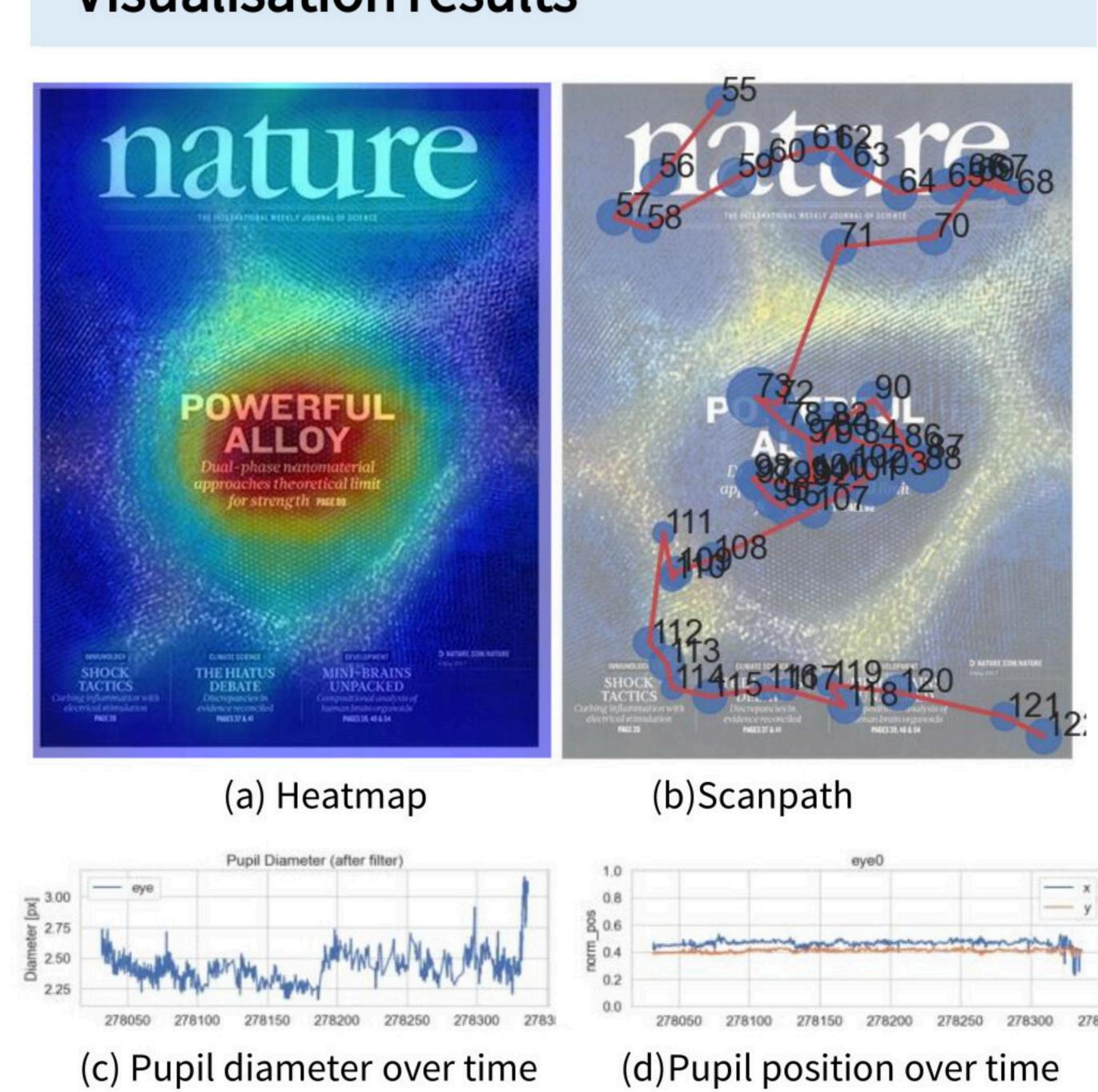
Algorithms

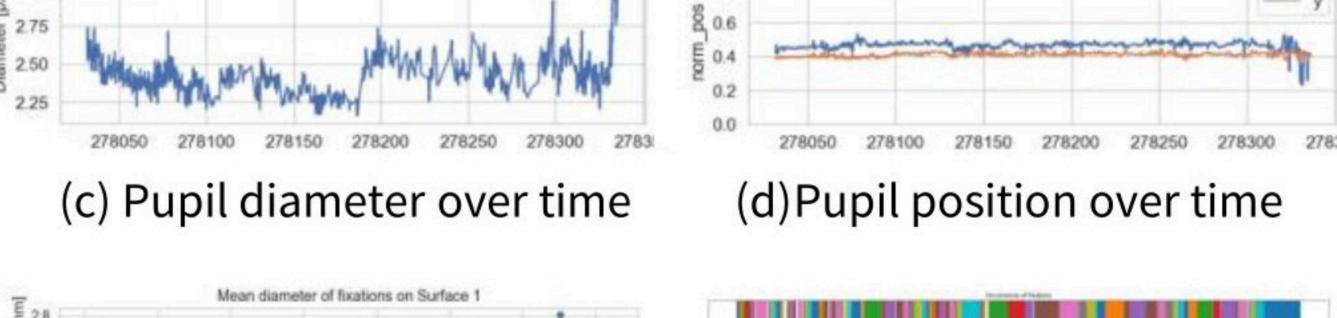
- Fixation detector: dispersion threshold identification (I-DT) method.
- Heatmap generator: histogram statistics method, and Gaussian filtering

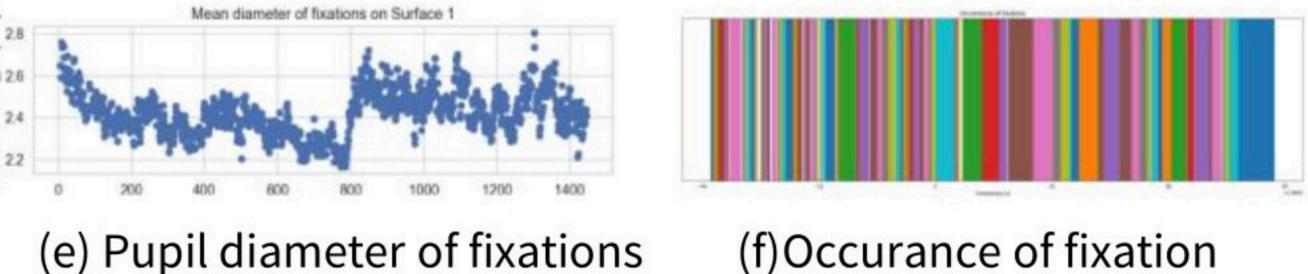
Software Design



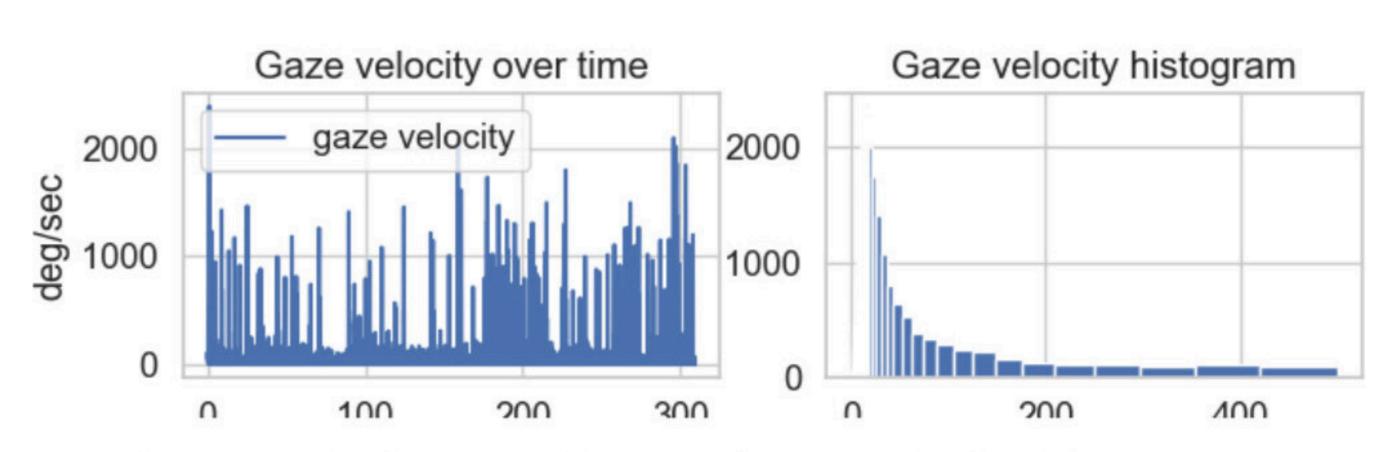
Visualisation results







(f)Occurance of fixation



(g) Gaze velocity over time (h)Gaze velocity histogram



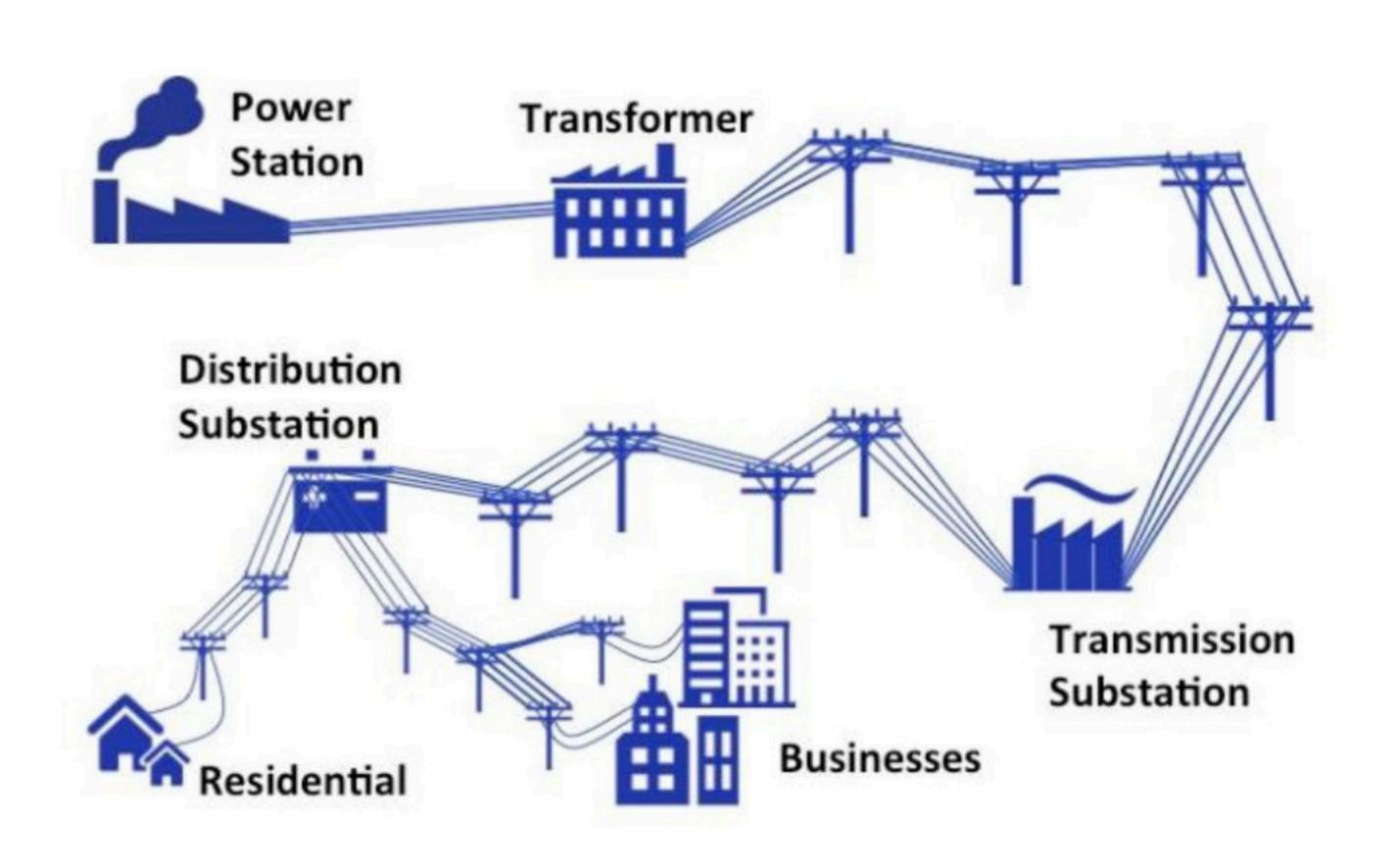
Intelligent-based Prediction Model for the Smart Electricity Grid

Bay of Mariance

Yulin Song Project Leader: Ethan Lau

Objective & Background

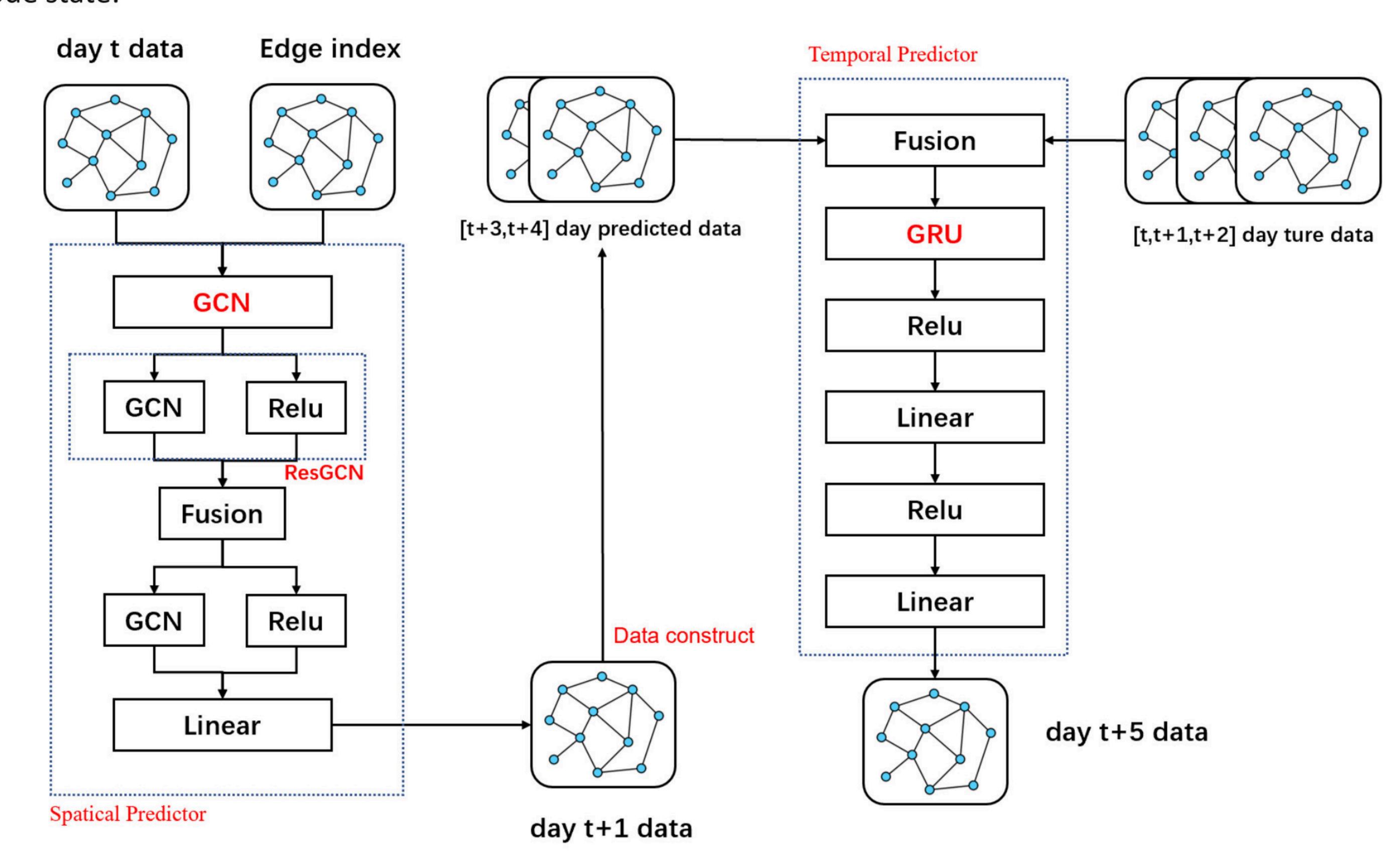
Traditional methods cannot fully capture the dynamic characteristics of multiscale energy systems due to the excessive unused renewable energy, uncertain energy consumption, and insufficient amount of energy storage facilities in general power systems, which leads to inaccurate forecasting and inefficient system operation. To tackle these issues, this paper proposes a deep learning approach to accurately predict the fundamental states of a classic electric grid with the consideration of power network spatial topology and potential temporal relations.



Power Grid Structure

Model Structure

we propose a spatial and temporal deep learning model called STNet to accurately predict the system's node state.



STNet Structure

Study Result

Simulation results show that the proposed deep learning approach outperforms other basic forecasting tools when predicting the state of a typical power system. These promising results provide significant benefits in power grid operation.

Method	MSE	RMSE	MAE	MAPE (%)
MLR	$2.749 * 10^{-4}$	$1.658 * 10^{-2}$	$8.414 * 10^{-3}$	61.7
AR	$1.6 * 10^{-3}$	$4 * 10^{-2}$	$5.12 * 10^{-3}$	91.7
SVR	$1.75 * 10^{-5}$	$4.18 * 10^{-3}$	$2.178 * 10^{-3}$	29.46
CNN	$3.994 * 10^{-5}$	$6.32 * 10^{-3}$	$3.3 * 10^{-4}$	507524
KNR	$1.21 * 10^{-5}$	$3.48 * 10^{-3}$	$1.648 * 10^{-3}$	30.48
RNN	$2.98 * 10^{-6}$	$1.72 * 10^{-3}$	$6.2 * 10^{-4}$	27.22
LSTM	$3.78 * 10^{-2}$	$1.95 * 10^{-1}$	$9.74 * 10^{-2}$	108
STNet	$3.69 * 10^{-9}$	$6.07 * 10^{-5}$	$4.65 * 10^{-5}$	31.3



Iterative Development of Market-Compatible Mobile Apps for Local Insurance Company



Xuanyu Chen, Qianhang Feng, Hantang Zhang Project Leader: Dr Xianhui Che

Abstract

Mobile technology has made mobile apps crucial for enterprise competitiveness. This project combines mobile apps and cloud to explore the practical use on Android and iOS platforms to create impressive UI that will spark interest in customers, while also examining potential security risks and network communication processes with Firebase and Stripe for online transactions.

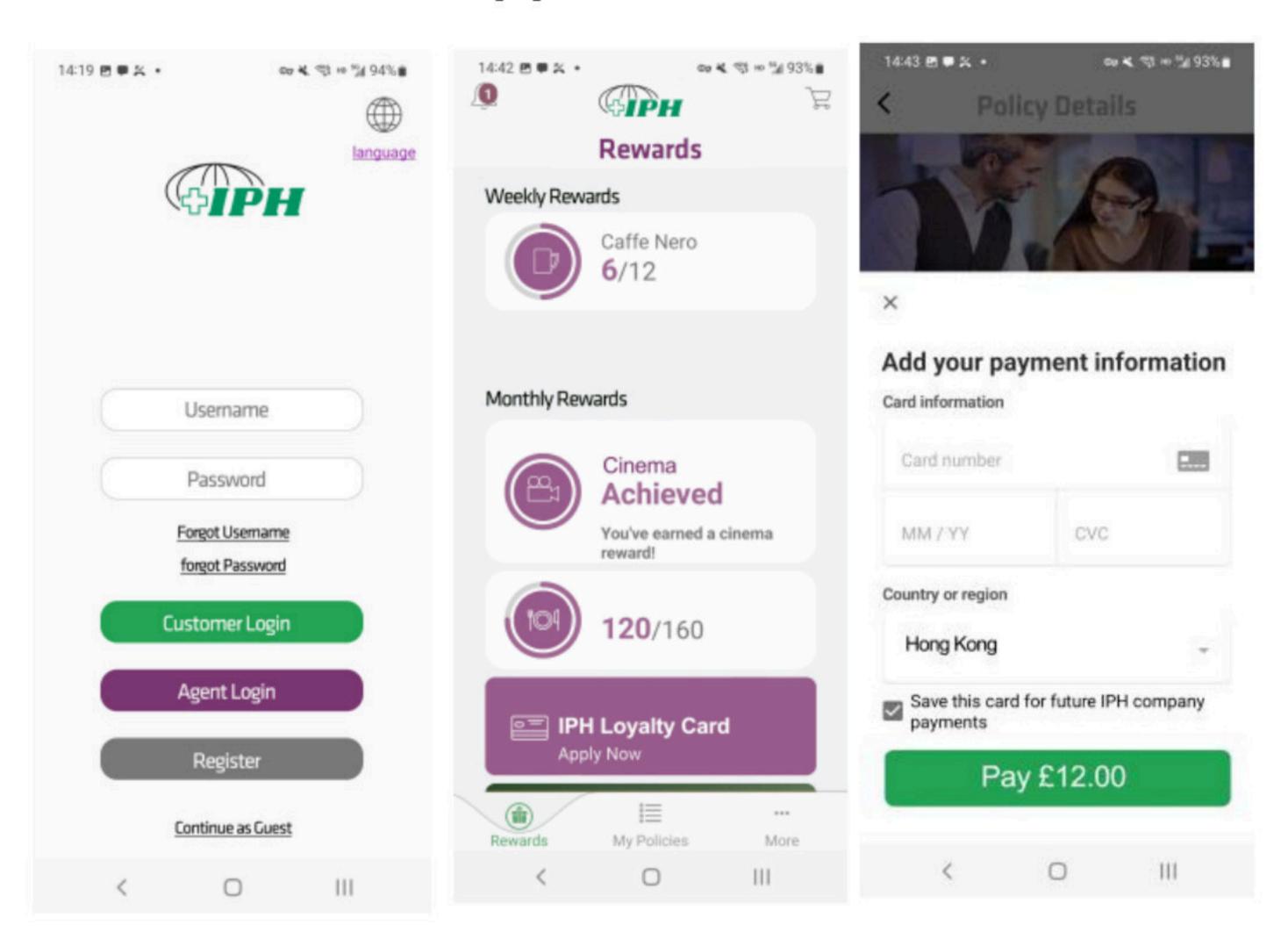
Difficulties

- Make pages informative and consistent
- Implement design patterns, including MVP and MVVM
- Explores the components' lifecycle in detail
- Learn and master the mobile app development environment
- Relevant resource searching in object customisation
- Visual impact design and implement
- Remote database construction and real-time network communication

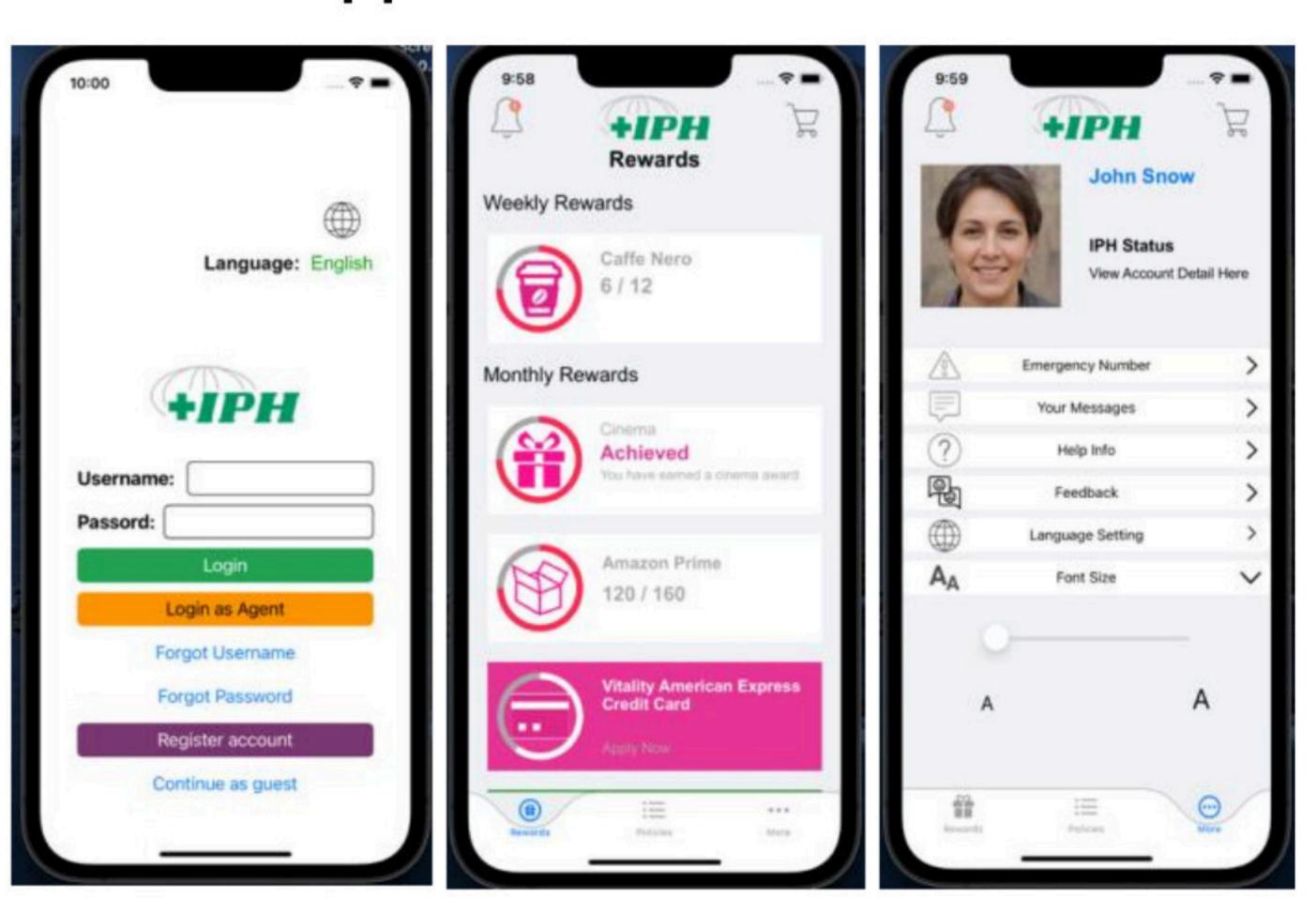
Results

- Develop two identical insurance sales mobile apps on Android and iOS
- Customized user interface
- Build remote server and database
- Make network communication with remote server
- User authentication and management with Firebase
- Stripe online payment function

Android Mobile App



iOS Mobile App



Future Work

- UI optimization. It is a continuous process after the app is put on the shelf according to the customer's feedback
- Improve functionality. Add more app features is in line with the company's business expansion and market demand
- Optimize integration and usage with remote database





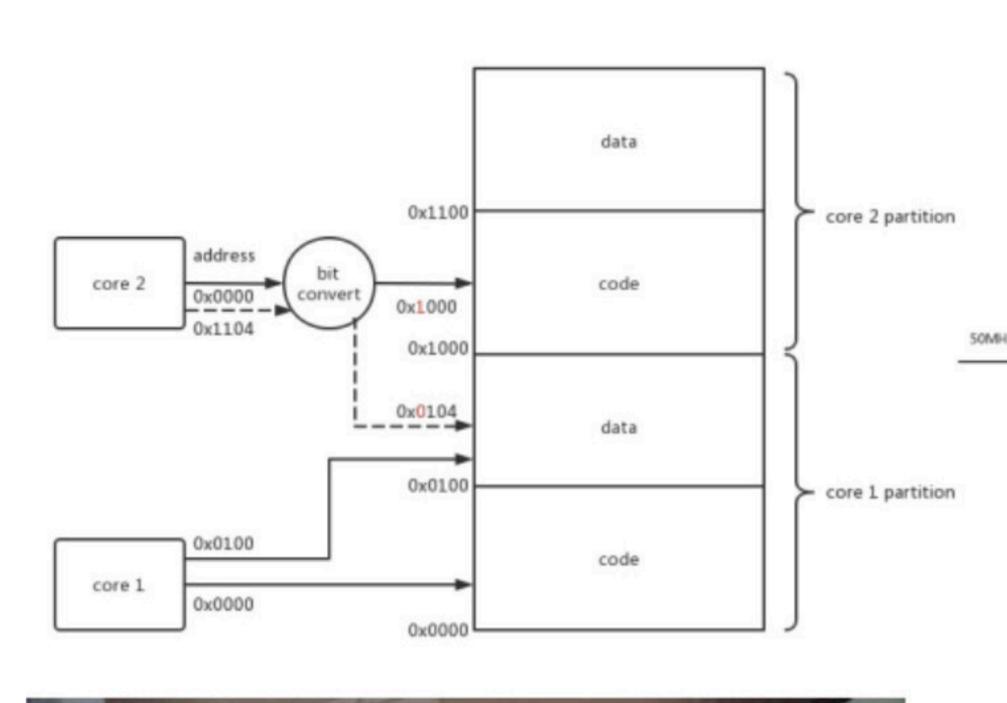
Minimal RISC-V Microprocessor Design

Pengdao Jiang, Haotian Liao Project Leader: Dr. Matthew Tang

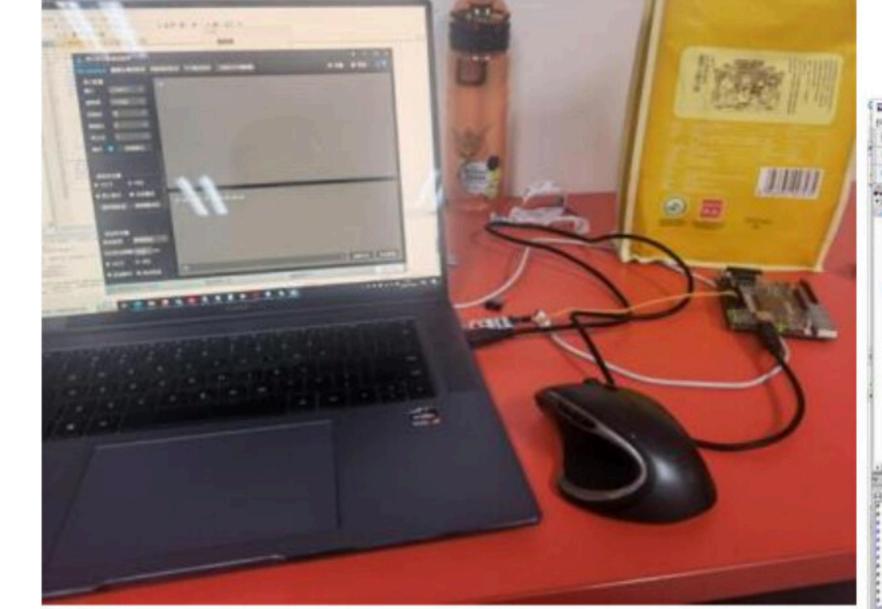


Build single-core system-onchip(SOC)

- Study the characteristics of the RISC-V instruction set and computer architecture, and design a SOC that can be implemented on FPGA.
- Use the hardware description language to implement the system and verify the system on the development board.



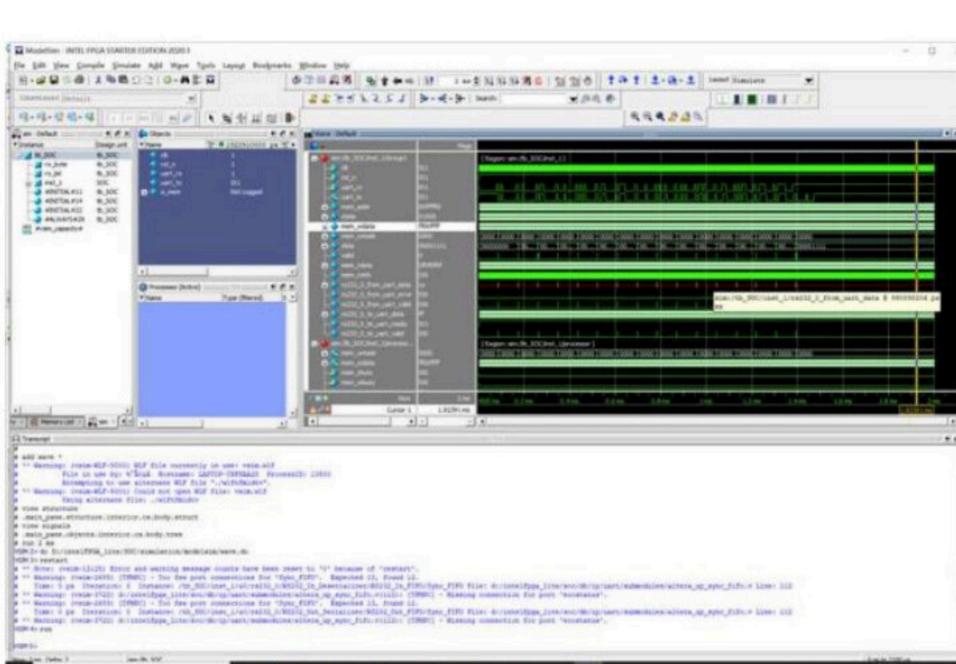




Core 2

150MHz

Core 1

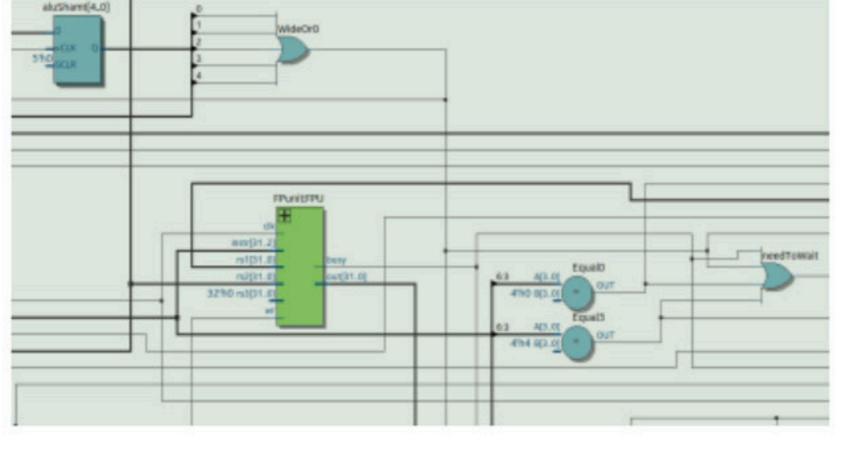


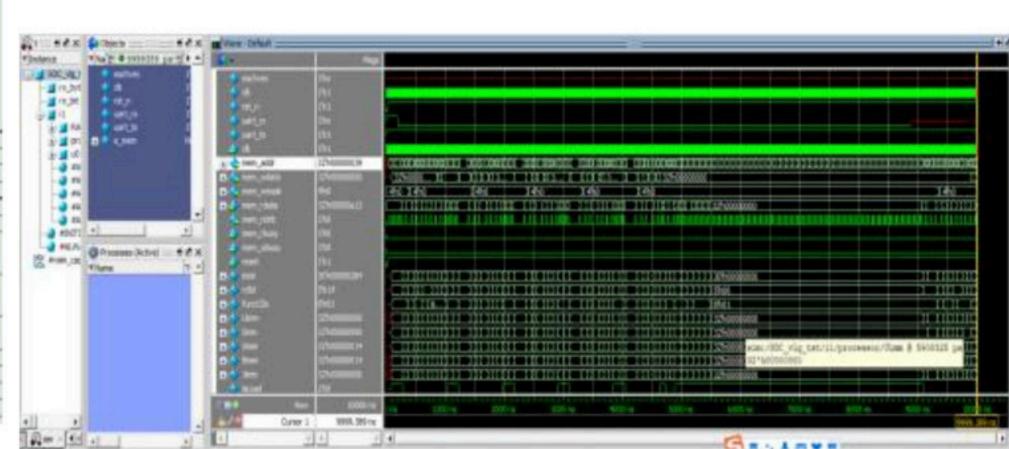
Build multicore SOC

- Delve into the core timing properties and explore specific multicore system design options.
- Verify the stability of the multicore system.
- Design the benchmark firmware to verify the speed-up compared to the single-core system.

Add Floating Point Unit

- Design the floating point unit to support the RV32F instruction set.
- Implement the FP-unit to the base processor system.
- Compare execution cycles and power consumption. Disscuss about the application of our approach.





Processor	Code size	Execution cycles	Power dissipation
Without FP-unit	61	29575	10.95mW
With FP-unit	20	4621	11.13mW





Quantifying and Supporting Students' Learning Behaviour and Engagements

Wenrui Li

Project Leader: Dr Ethan Lau



Summary

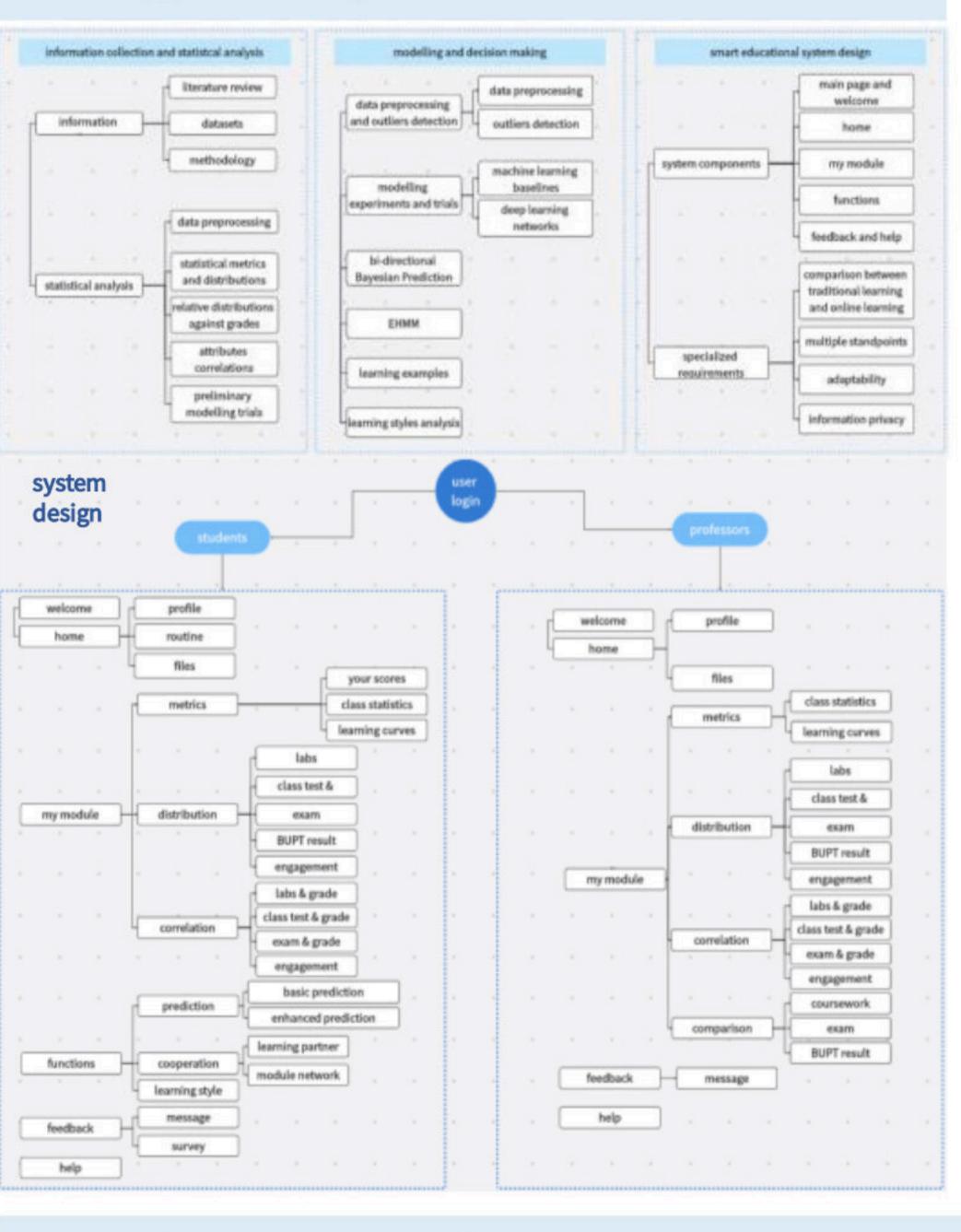
In 2019, COVID transformed traditional into online learning, learning observations limited resulted students' behaviour, high drop-out rate and insufficient interventions The project teachers. quantitatively model students' learning behaviour and performance and provide solutions generalized driven ΑI DS/ML/DL.

The contributions are:

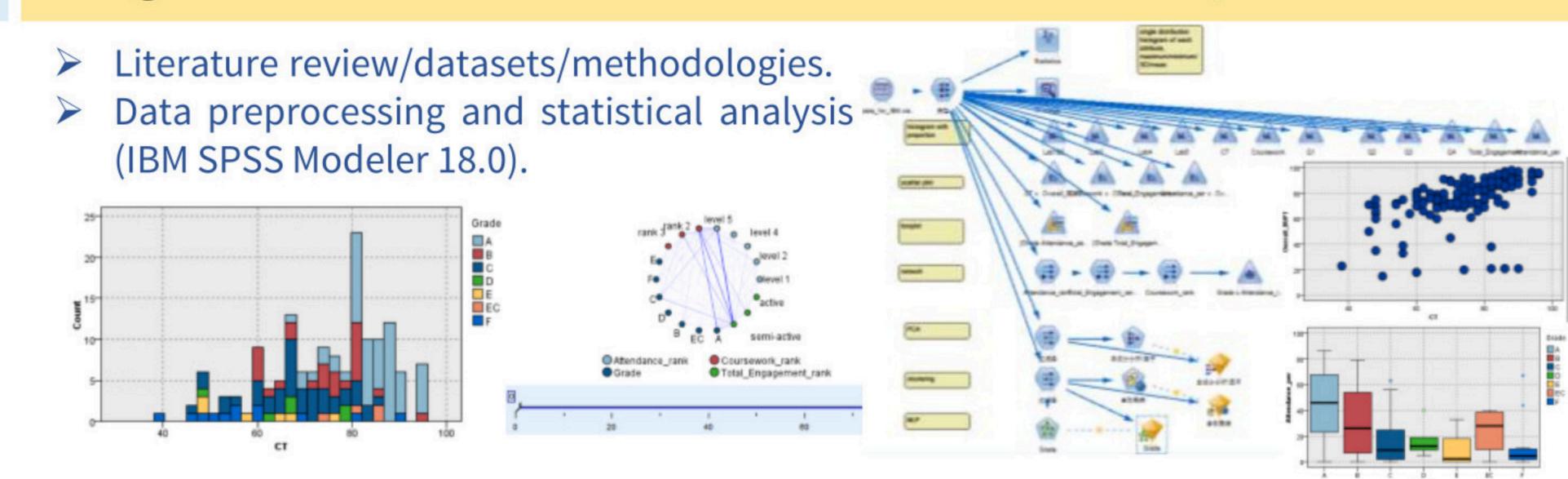
- Compare DL methods and ML baselines (91.39% uniclass, 70.2% multiclass, 87.24% regression).
- Model students' performance diversely with Bi-directional Bayesian Prediction, learning example, learning styles, probability learning curves, etc.
- ➤ Utilize in-course dataset and consider learning as an envolving process with RNN and EHMM.
- Design a smart interactive system (SPEES) with educational insights.

(OF ELO) WITH Calacational mon

Design & Implementation

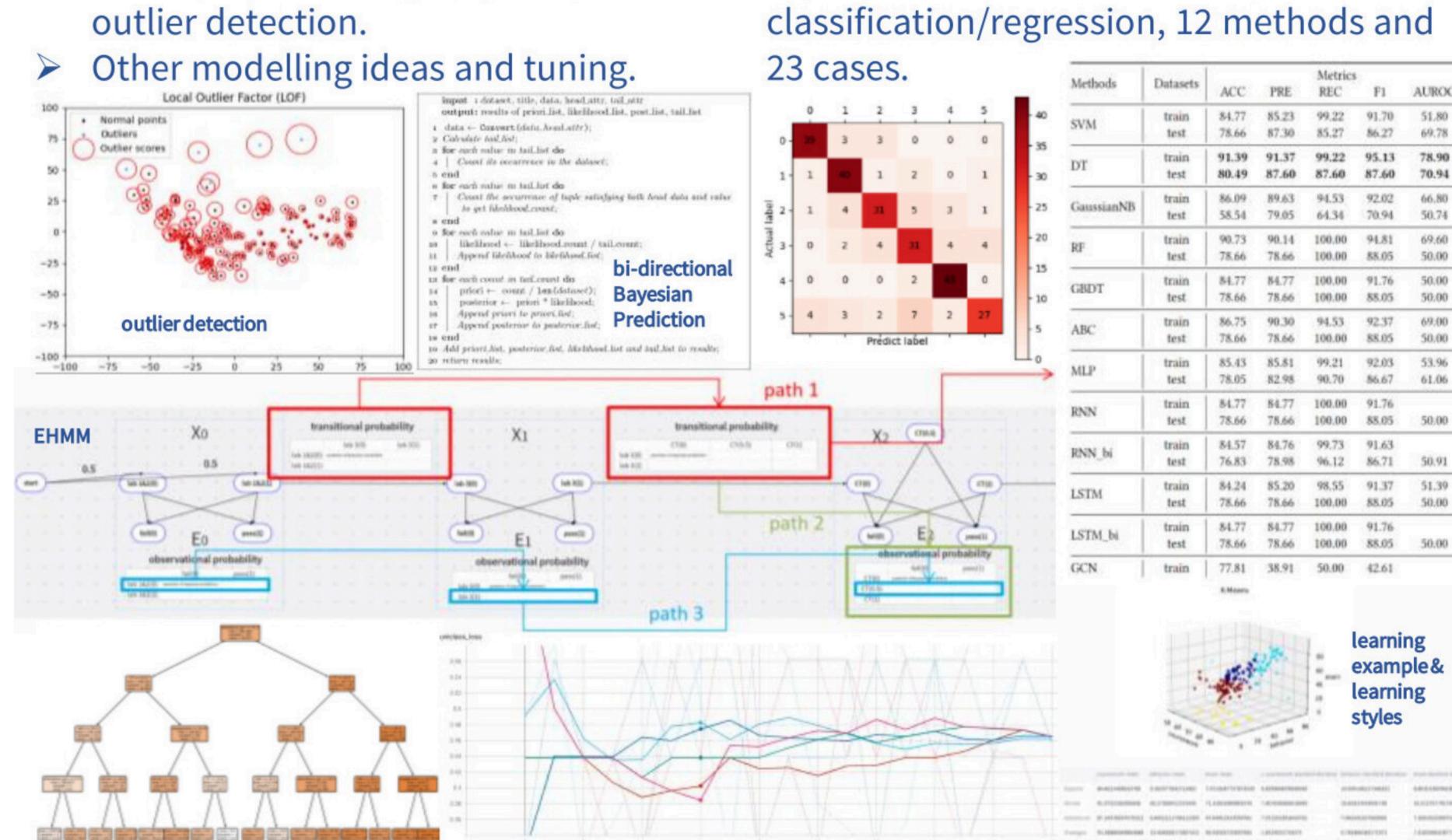


Stage 1: Information Collection & Statistical Analysis

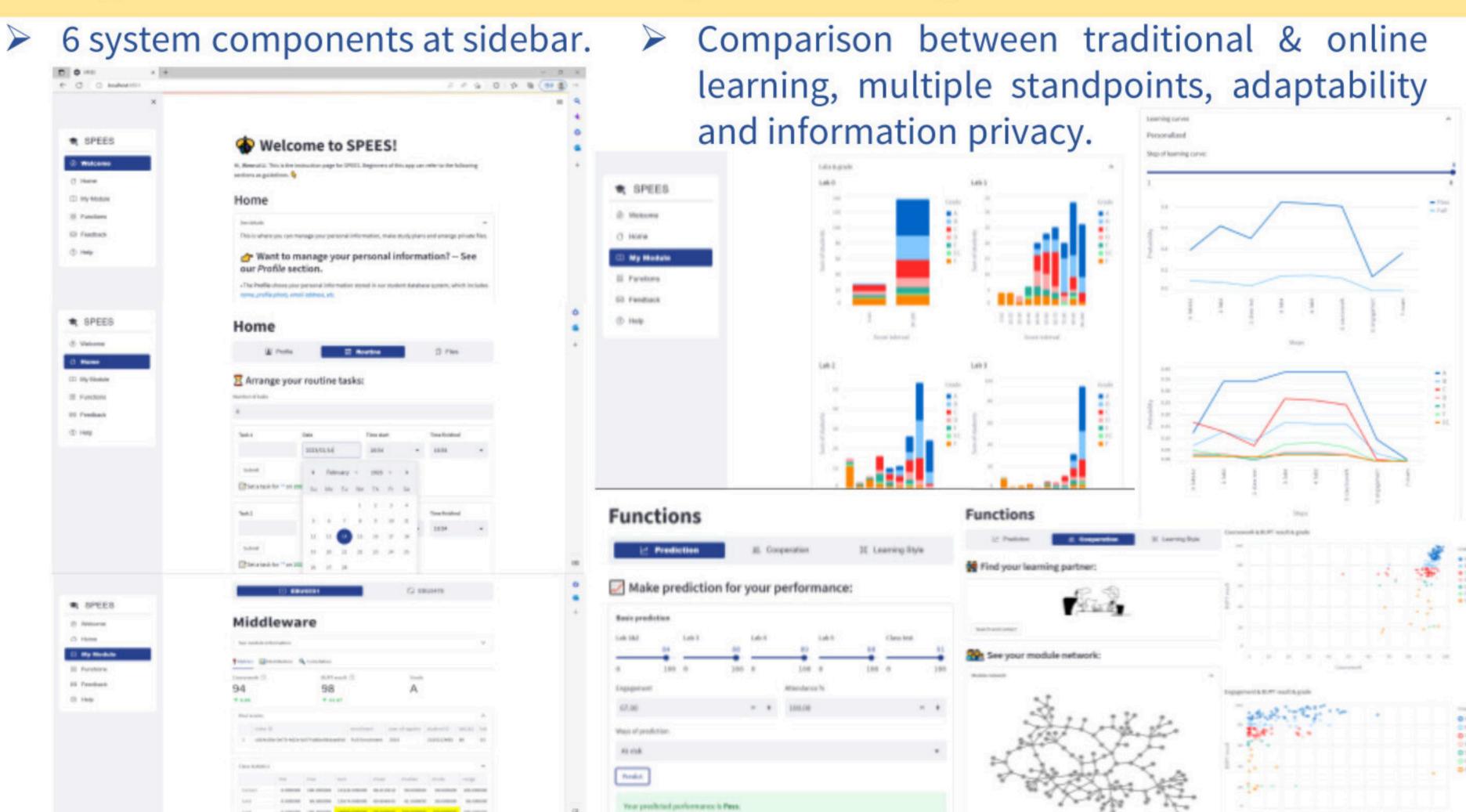


Stage 2: Modelling & Decision Making

Data preprocessing (Python) and > Experiments for uniclass/multiclass outlier detection. classification/regression, 12 methods and



Stage 3: Smart Educational System Design (SPEES)



Problems, Conclusion & Future Work

- > Problems: Multipage design & small dataset (cross-validation/ensemble learning/data augmentation with SMOTE).
- > Conclusion: Students' behavior and ability influence performance. Learning patterns of various courses are different.
- Future: Online model with increments; more potential of ML/DL with temporal information; user-friendly system.



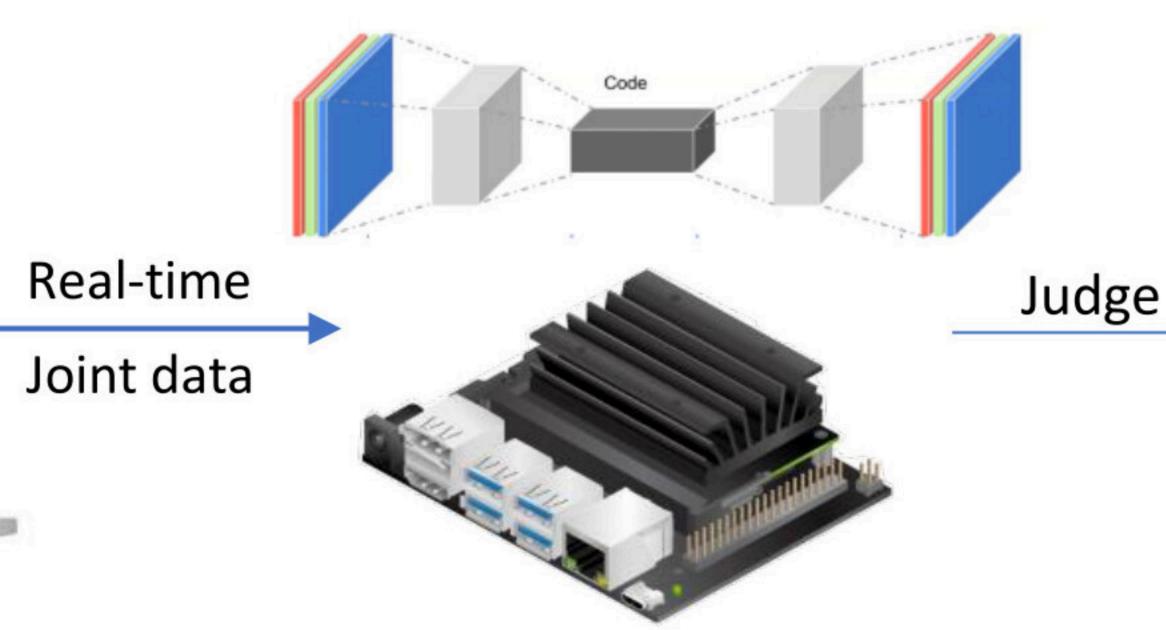
Real-time LSTM-Autoencoder Behaviour Anomaly Detection for Industrial Robot Arm on Nvidia Jetson Nano

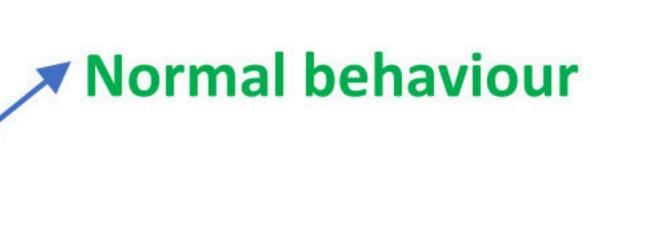
Box AMON AND SAME

Ruiqi Wan

Project Leader: Prof. Jonathan Loo







Abnormal behaviour

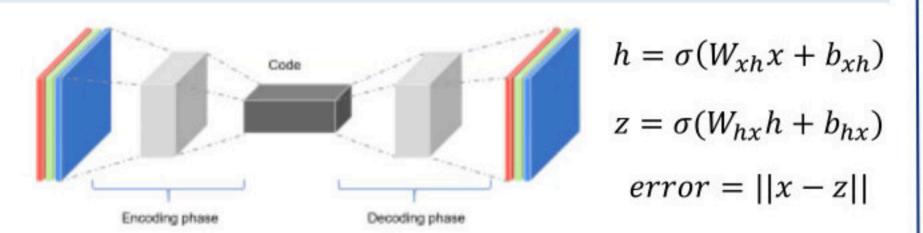
Problem Definition

The action control and monitoring of industrial robot arm need to be accurate, and it is difficult to capture extremely subtle errors.

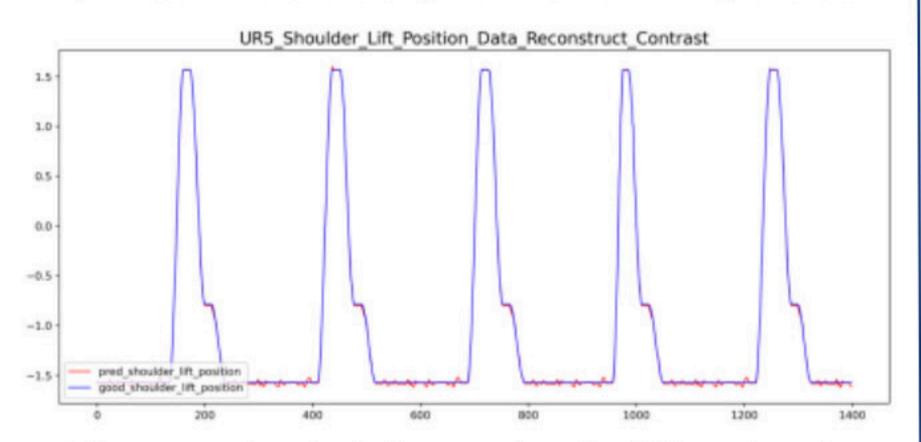
Purpose of the Project

Develop LSTM-Autoencoder model to efficiently and effectively detect abnormal actions of robotic arm

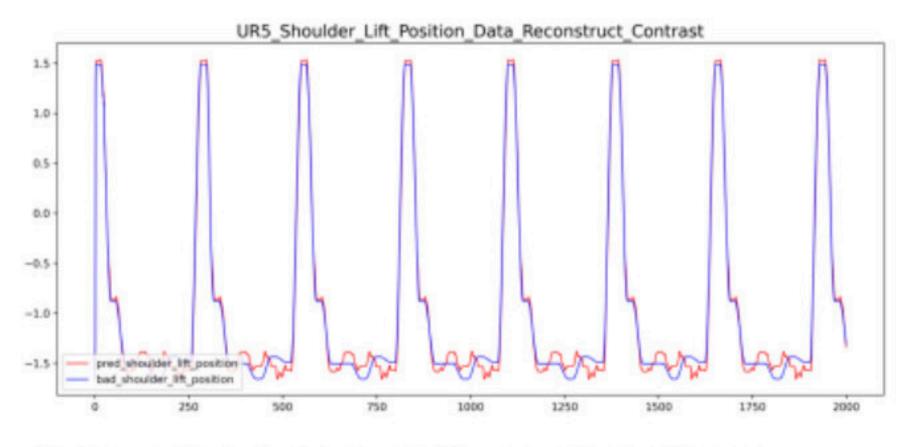
Principle



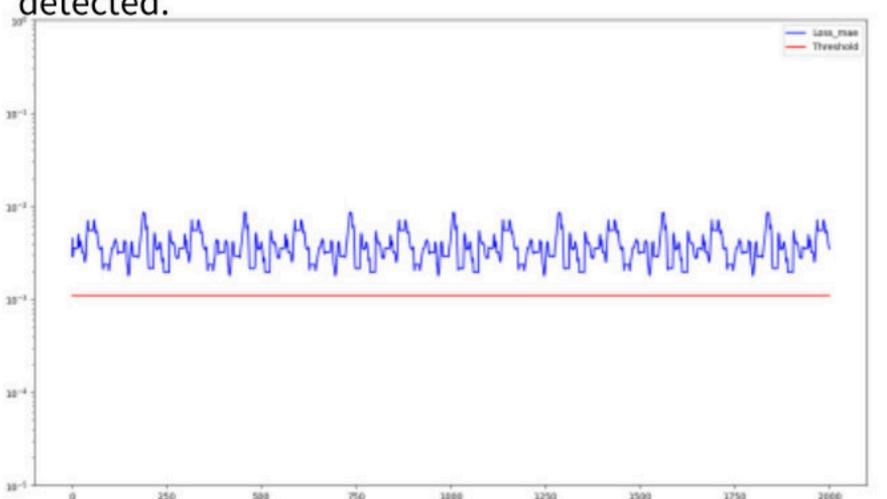
The well-trained autoencoder could reconstruct pattern which is nearly closed to normal pattern.



The reconstruct of abnormal quite different and cause the reconstruct error exceed the threshold.



Set up a threshold above the max loss of good pattern and input the bad data. The reconstruct loss are far beyond threshold and abnormal are detected.



Demo video

Scan the Blue or Red QR code to watch a voice-over demo video with subtitles, which might take up to two and a half minutes.

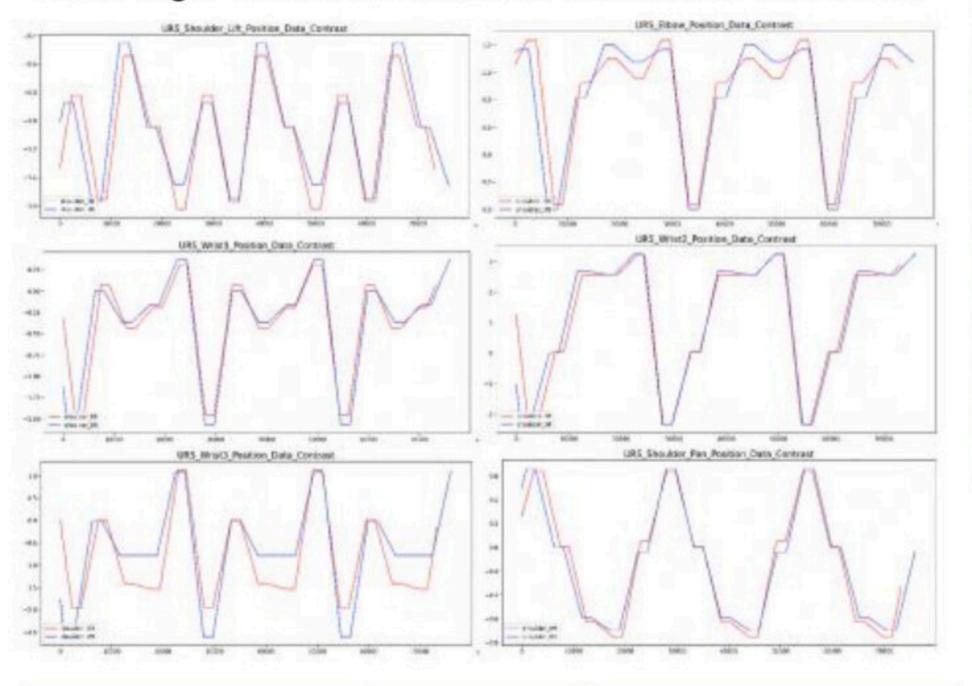
Scan the Green QR code to explore the experimental record



Data

These data both normalized to [-1,1].

Some slight differences between normal and abnormal.



$\mu = 0.5$, $3\sigma = 0.5$	Good Pattern	Anomalies (in degree)	Anomalies (in radian)	Bad Pattern
shoulder_pan _joint	0.785	0.458475508	0.008001907	0.7930
shoulder_lift_ joint	-1.57	0.38297492	0.006684173	-1.5633
elbow_joint	0.785	0.735591428	0.012838492	0.7978
wrist_1_joint	0.785	-0.442592894	-0.007724703	0.7773
wrist_2_joint	0.785	0.606553478	0.010586355	0.7956
wrist_3_joint	0.785	0.45056705	0.007863879	0.7929

 σ is standard deviation and satisfies 3σ less or equal than μ and the area within is 99.730020%. This limitation was set to make nearly none of distribution of anomalies cross the zero point, then the distribution of anomalies would be approximately considered as symmetric about the zero point.

$$P_{b,i}(radian) = P_{g,i}(radian) + A_i(radian)$$

 $A_i(radian) \approx 57.3248 \times a_i(degree)$
 $a_i(degree) = Sign \times \frac{1}{\sqrt{2\pi}\sigma} \exp(-\frac{(x-\mu)^2}{2\sigma^2})$
 $3\sigma \le \mu$
 $P(Sign = x) = 0.5 \ (x = -1.1)$

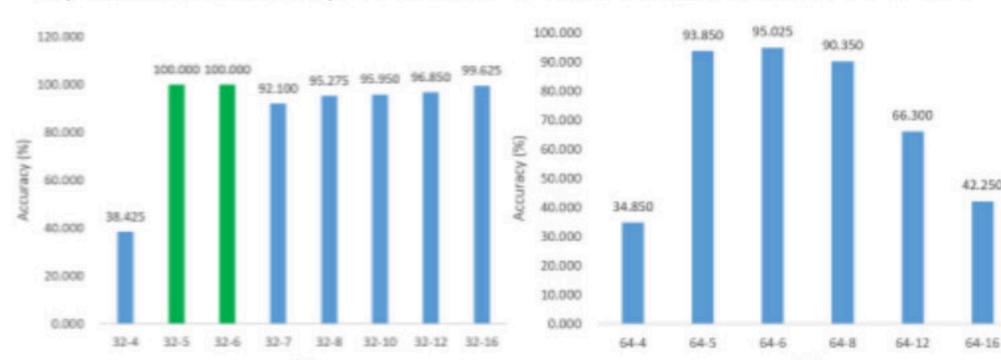
Acknowledgements

I want to express my most sincere gratitude to Prof. Jonathan Loo who ignited the idea inspiration of this project (also this poster). Your useful and detailed guidance documents sharing, your constant support and your unwearyingly enlighten.

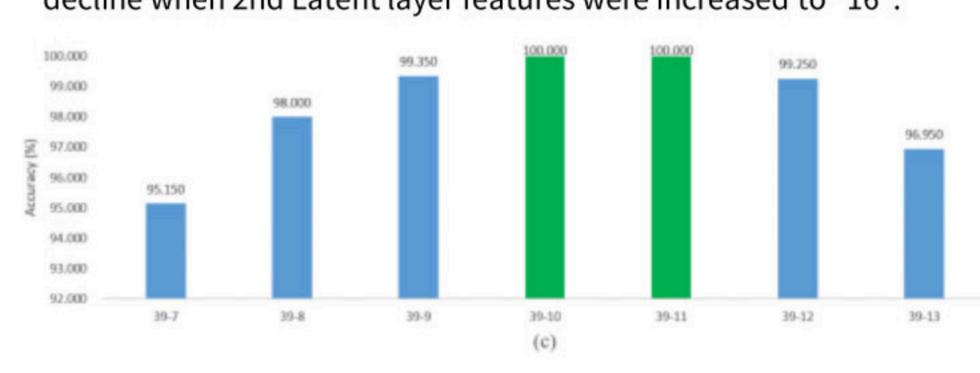
I would like to express my great thanks to Ms. Maggie Li, Ms. Alice Zhao and Ms. Gina of Administration QM-BUPT JP/JEI (Beijing) for device support of Nvidia Jetson Nano.

Evaluation

Within the "32" 1st Latent layer group, models with 2nd Latent layer feature numbers of "5" and "6" exhibited excellent performance, but it experienced some of performance decline when increased to "8-16".



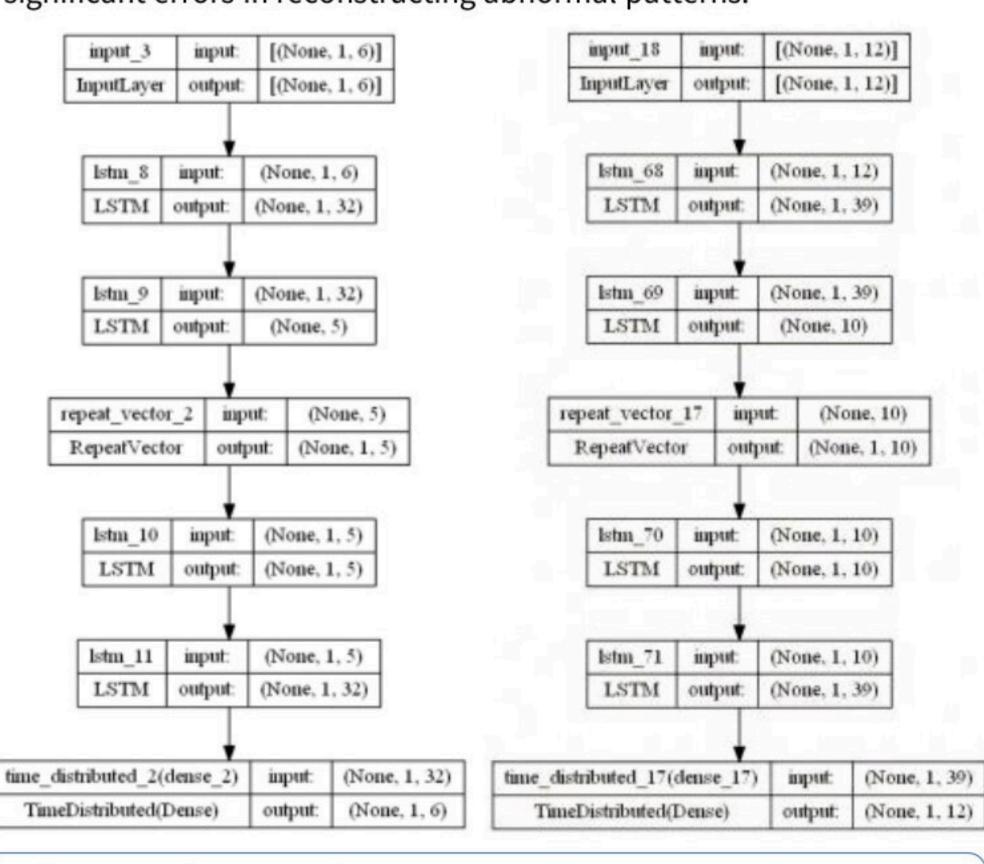
Similarly, in the "64" 1st Latent layer group, significant performance decline when 2nd Latent layer features were increased to "16".



Architecture

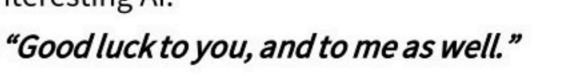
One possible explanation is that, if the number of neurons in the latent layer exceeds that of the input layer, the neural network may be given too much capacity to learn the data. In extreme cases, it may simply copy the input values to the output values, including noise, without extracting any basic information.

Complex network structures may have excessive reconstruction and generalization capabilities, which lead to the failure to demonstrate significant errors in reconstructing abnormal patterns.



About the author

Ruiqi Wan is an undergraduate student about to graduate at JP programme QMUL with BUPT with research interests in machine learning and interesting AI.







Research on Brain White Matter Dynamic Functional Connectivity in Patients with Brain Arteriovenous Malformations (AVM)

Student: Qiji Shi Project Leader: Dr Fangrong Zong



Introduction

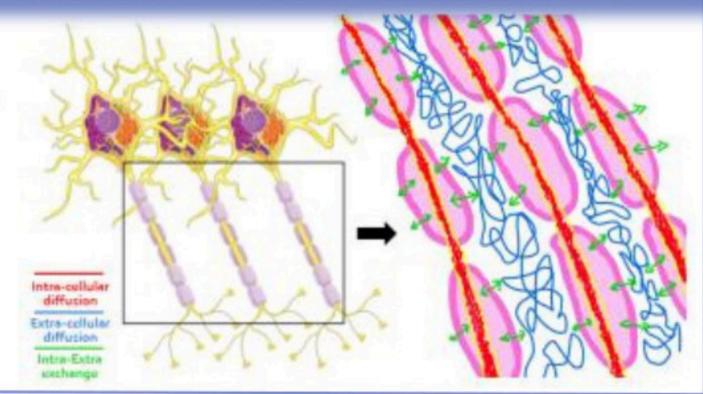
Brain arteriovenous Malformations (AVM) belongs to a rare congenital lesion, which may involve language areas but the patients usually have no language barriers. AVM thus becomes a unique model to study the cognitive function mechanism.

Aim

The purpose of this research is to explore reorganisation patterns of AVM patients in terms of white matter functional connectivity, which is a quantitative parameter obtained from diffusion MRI and functional MRI (fMRI) datasets.

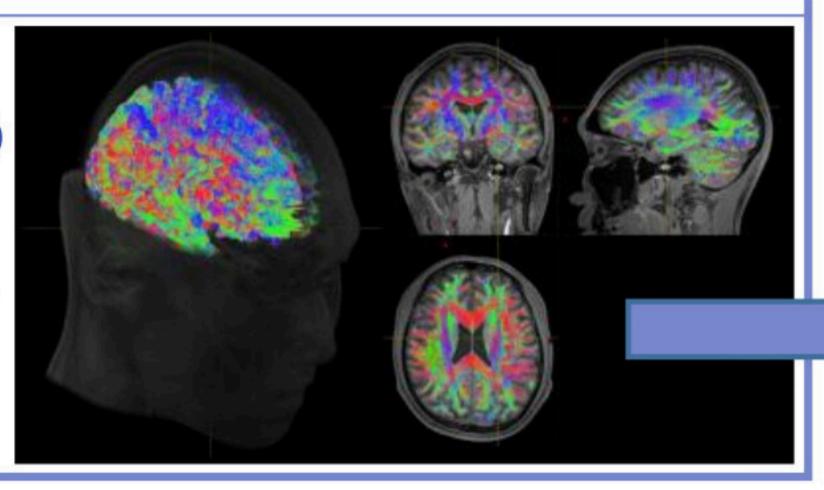
Background

Diffusion MRI: Modeling the white matter pathways (neurite) by measuring the water molecule diffusion.



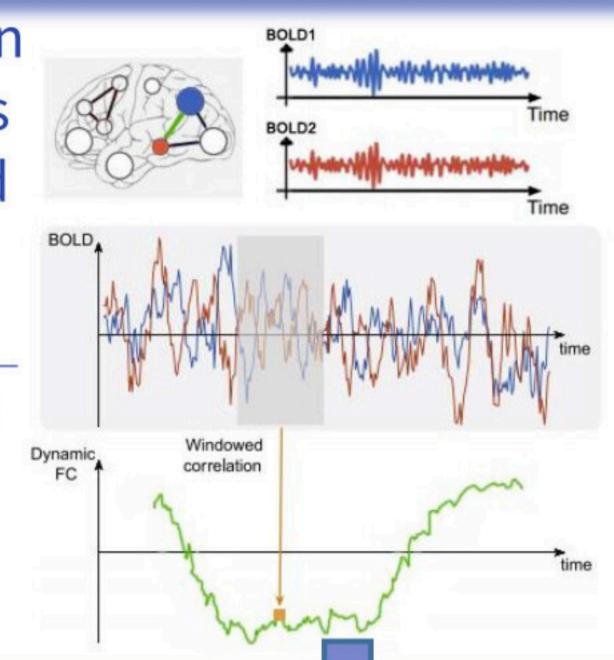
Diffusion tensor imaging (DTI): 3D ellipsoid model characterize the diffusion of water molecules with 3 orthogonal eigenvectors [1].

Tractography (Fiber tracking): Generating 3D representations of white matter pathways based on the primary diffusion directions.



Functional MRI: measure brain activity by detecting changes in oxygen in the blood: blood oxygen level dependency (BOLD) signals.

Functional Connectivity (FC):
Temporal correlation of the
BOLD signals between
distinct brain regions.

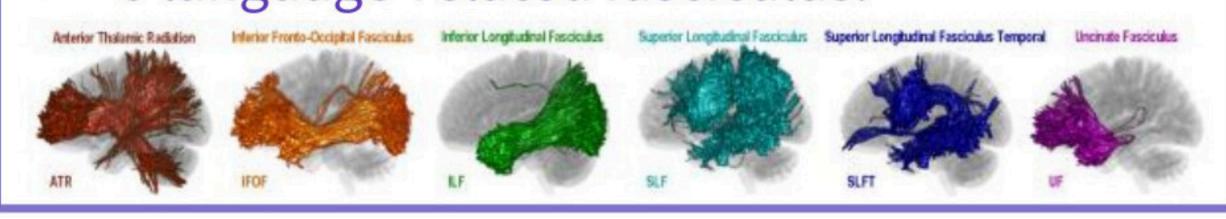


Track-weighted dynamic Functional
Connectivity (TW-dFC): mapping the FC to
corresponding white matter pathways

 $TWdFC(v,t) = \frac{1}{N_v} \sum_{i=1}^{N_v} FC_i(t)$, where N_v is the number of tracts traversing a specific voxel ν [2].

Methods

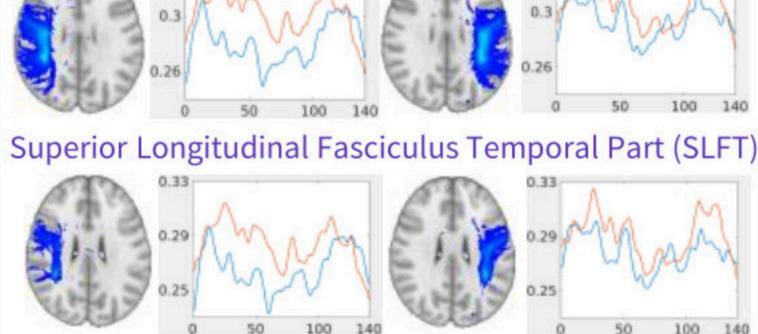
- Subjects: 34 left hemisphere AVM patients
 VS 32 healthy controls (HCs).
- 3T fMRI scanning while performing visual synonym judgment, oral word reading and auditory sentence comprehension tasks.
- DTI images: b = 0, 1000 s/mm² with 64 diffusion directions.
- Tractography: calculated by constrained spherical deconvolution (CSD) [3].
- Regional-average within each group.
- Two sample t-test to detect the specific reorganization area of AVMs.
- 6 language-related fasciculus:



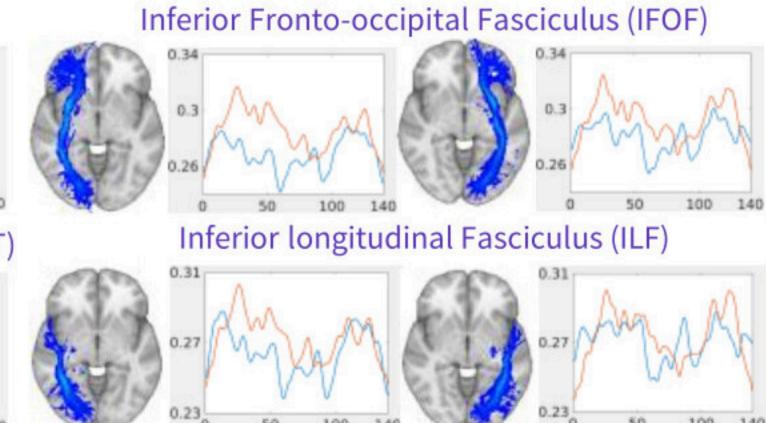
Results

HC ______ t (seconds)

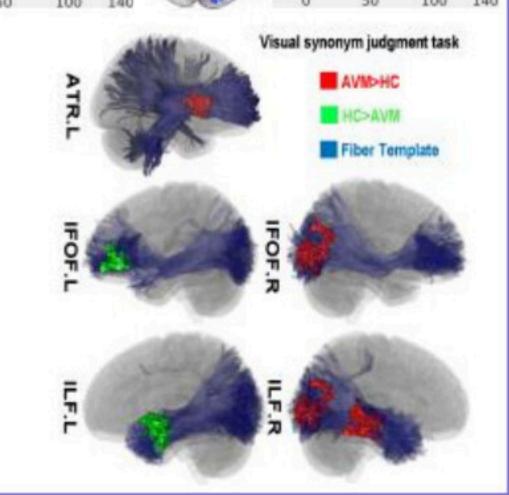
In visual synonym judgement task, TW-dFC intensity of AVM patients (blue lines) increase in right hemisphere fasciculus.



Superior Longitudinal Fasciculus (SLF)



In visual synonym judgment task, the TW-dFC intensity of AVM was higher than that of HCs in the left ATR, IFOF and ILF. While in the left hemisphere fasciculus, the TW-dFC value of HCs is significantly higher than that of AVM.



Conclusion

It is the first study to compare the TW-dFC intensity and found AVM patients reorganize their language function mainly in the right hemisphere fasciculus in visual synonym judgment task.

Reference

- [1] Basser, P.J et al. J. Magn. Reson. Ser. B. (1994),
- [2] Calamante, F. et al., Brain Struct Funct. (2017),
- [3] Tournier, J.D. et al, NEUROIMAGE. (2007).

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Synthetic-to-Realistic Object Rendering for 6D Object Pose Estimation

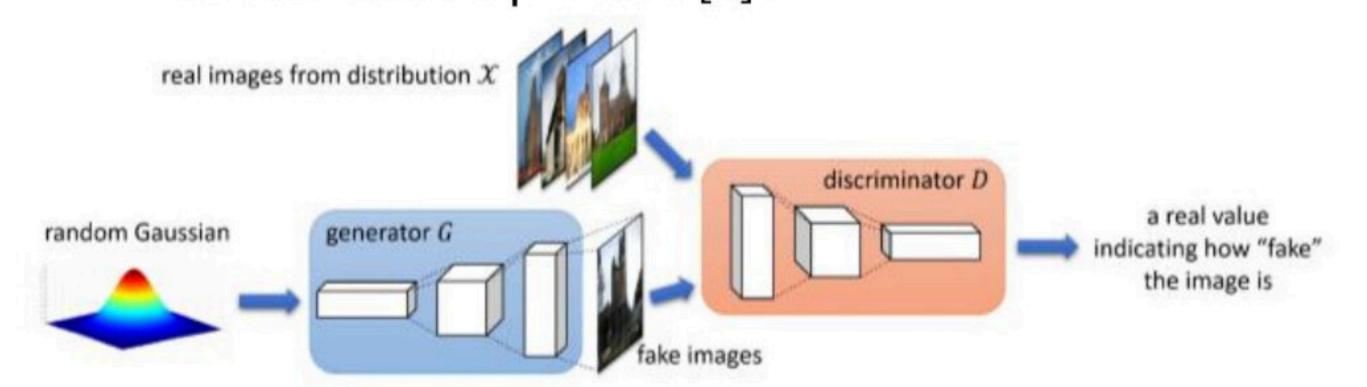


Zhiyang Chen

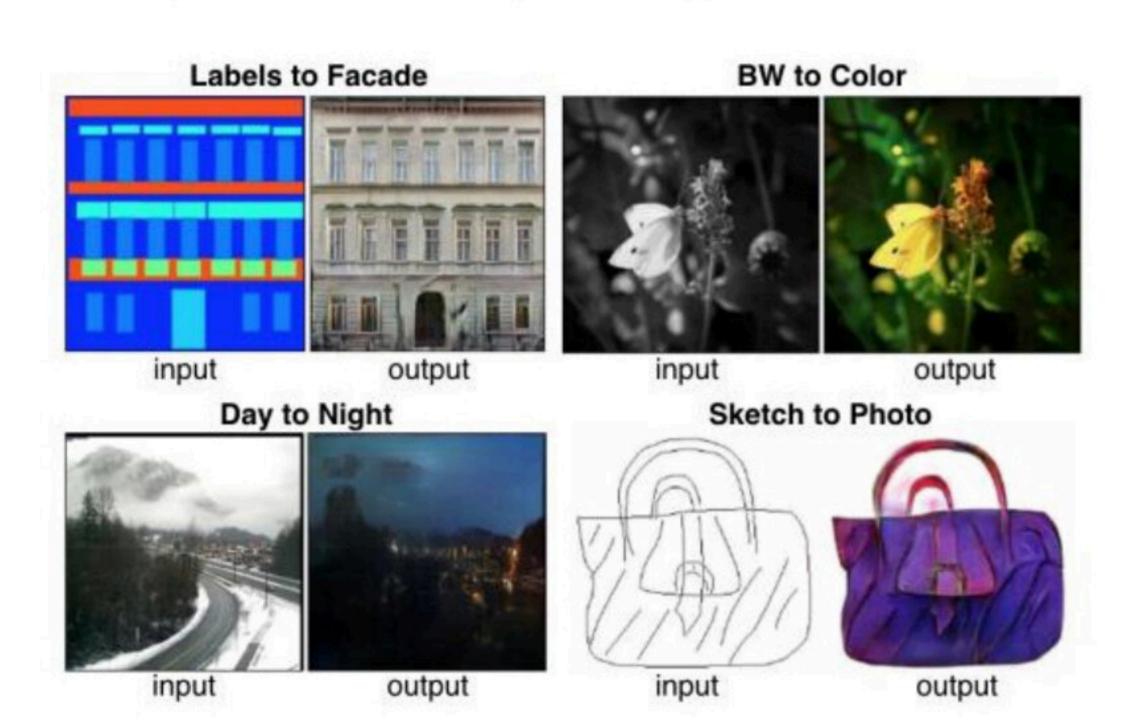
Supervisor: Dr Changjae Oh

GAN based Image2Image Translation

- Generative Adversarial Networks (GANs):
 - Two neural networks (A generator and a discriminator) simultaneously trained via an adversarial process [1].

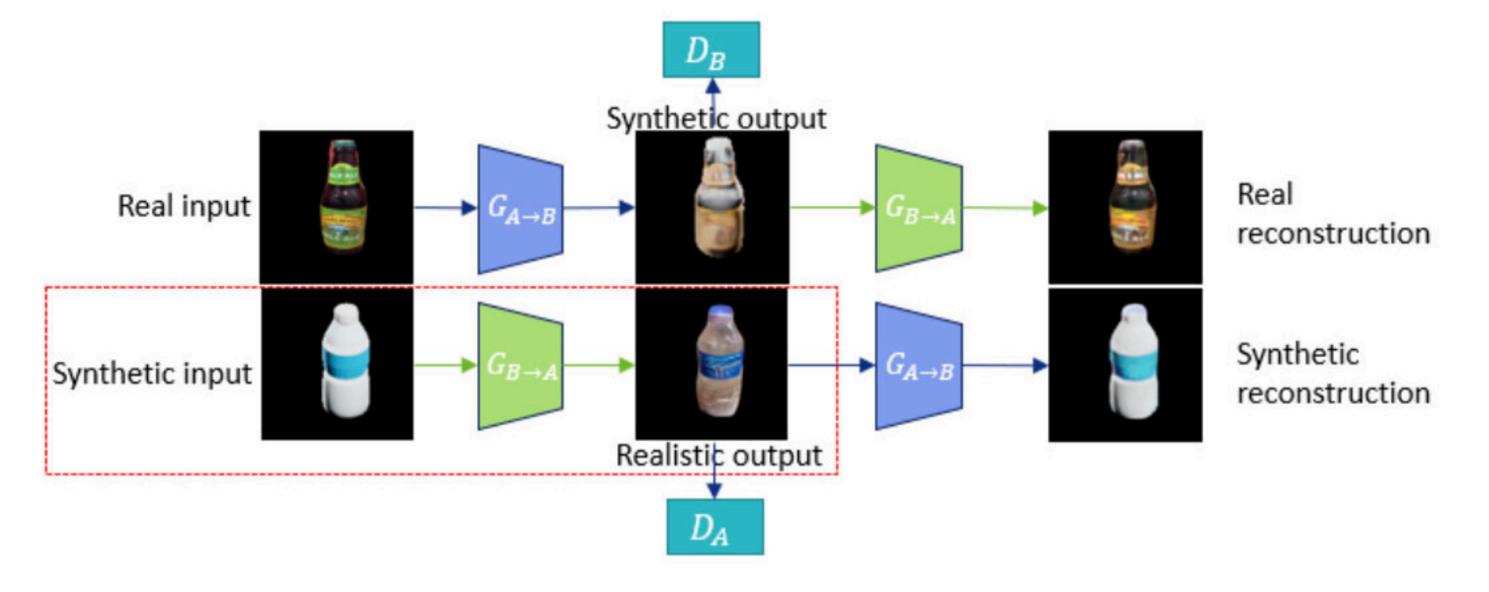


- Image-to-Image Translation:
 - Generating an image by transferring the sourceimage style to a target image [2,3].



Synthetic-to-Realistic Object Rendering

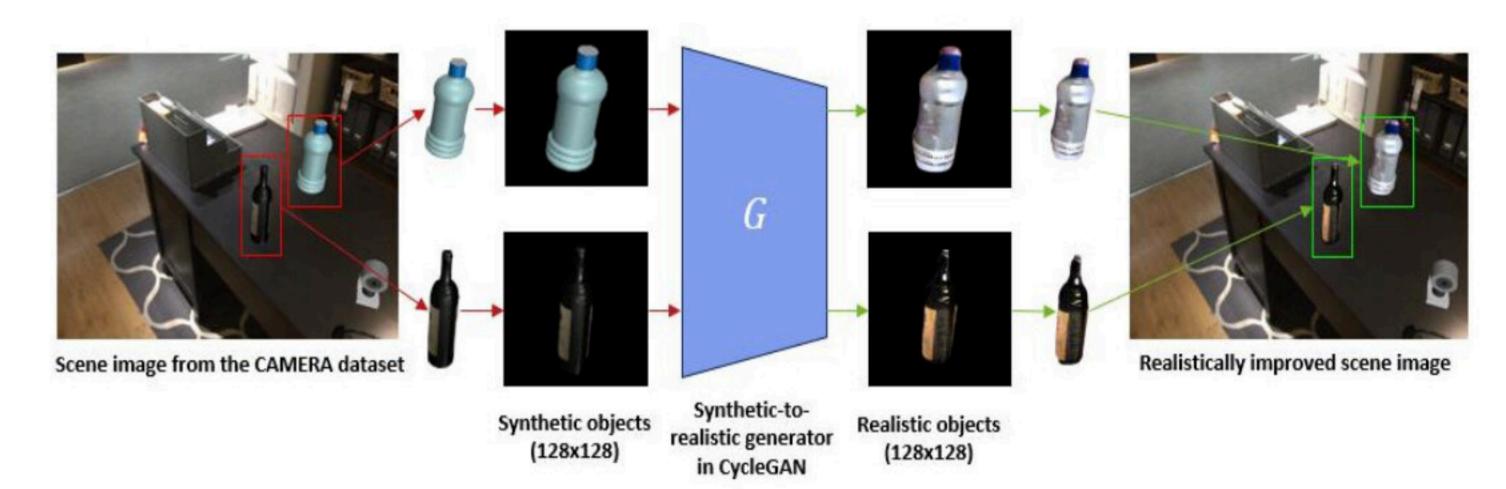
- CycleGAN for Object Rendering:
 - We use 4K real and 4K synthetic images to train a CycleGAN model for 200 epochs with a learning rate of 0.0002 and a batch size of 1.



• We set domain A as a real domain, and domain B as a synthetic domain. The generator we want is $G_{B\to A}$, applying test process on $G_{B\to A}$ to achieve synthetic-to-realistic rendering.

6D Object Pose and Size Estimation

- Normalized Object Coordinate Space (NOCS) method:
 - Estimating the 6D pose and dimensions of unseen object instances in an RGB-D image [4].
- The training dataset in NOCS is a mixed reality dataset (called CAMERA).
 - The domain gap exists in the CAMERA dataset
 - We train CycleGAN to render synthetic objects in the CAMERA dataset to realistic.



- Retrain the NOCS model and Make Comparison:
 - We prepare a 10K CAMERA dataset and 10K realistically rendered CAMERA++ dataset, then use them each to train a new NOCS model, evaluate them and make a comparison. (Improved on BOTTLE category)

Dataset		mean Average Precision (%)								
For			5°	5°	10°	10°	15°	15°		
Training	BD_{IoU25}	BD_{IoU50}	5	10	5	10	5	10		
			cm	cm	cm	cm	cm	cm		
CAMERA 300K	84.4	76.9	9.8	10.8	24.0	24.5	34.7	36.8		
CAMERA 10K	68.5	61.1	8.5	9.0	21.3	21.7	30.6	33.8		
CAMERA++ 10K	71.1	63.9	8.6	9.6	22.0	22.3	32.3	35.3		



References

- [1] I. Goodfellow et al., Generative adversarial networks, NIPS 2014.
- [2] P. Isola et al., Image-to-image translation with cGAN, CVPR 2017.
- [3] Zhu et al., Unpaired image-to-image translation using CycleGAN, ICCV 2017.
- [4] He Wang et al., Normalized Object Coordinate Space for Category-Level 6D Object Pose and Size Estimation, *CVPR* 2019.



Technology Policy Text Analysis Based on Latent Dirichlet Allocation Topic Model

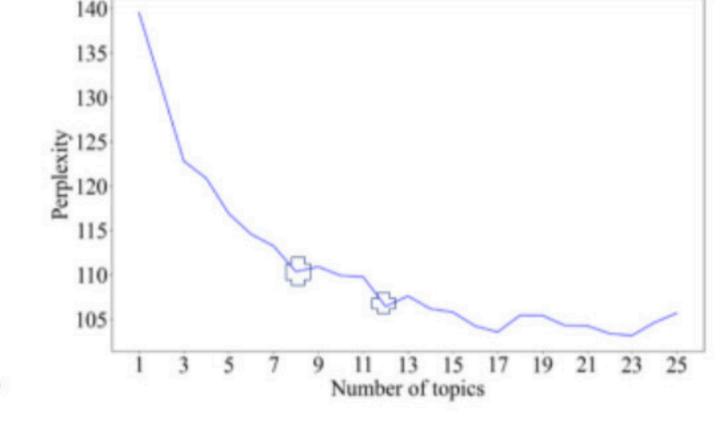
Siyuan Hu Supervisor: Richard Clegg

Bay AMO AND S

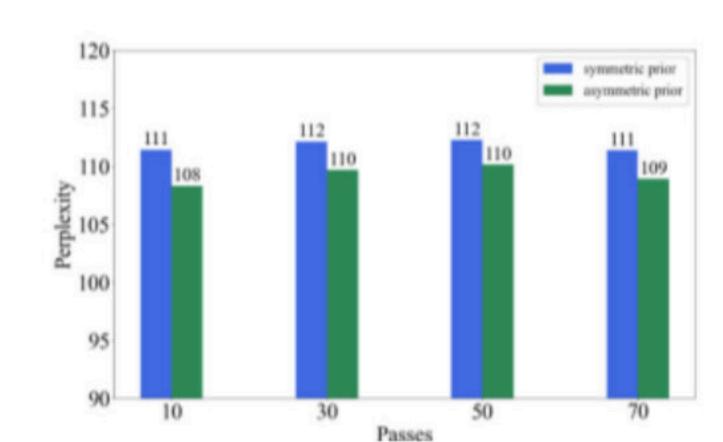
Introduction

Technology policy has become increasingly significant in national security and economic development. The number of policies is surging rapidly. However, quantitative methods are underutilised. Therefore, this study uses the Latent Dirichlet Allocation Topic model to discover latent topics in different periods of technology policy in the UK and the US from 2015 to 2022.

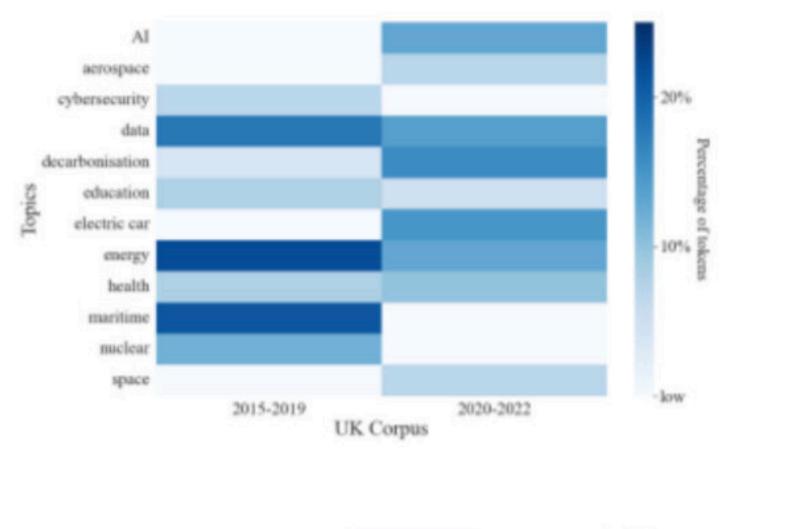
Acquire data Tune parameters Visualise the results Build the LDA model Build 5 corpora Get the results Analyse and compare Corpus building Results interpretation

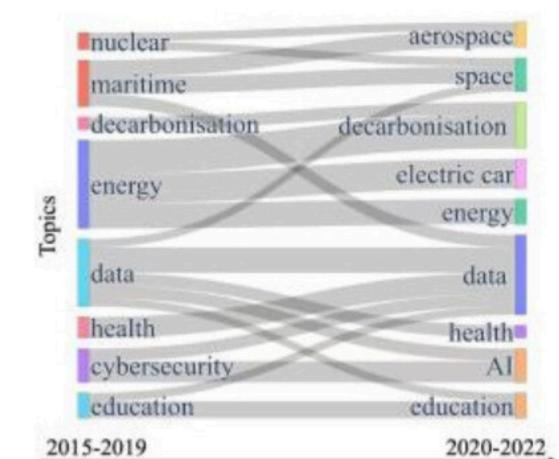


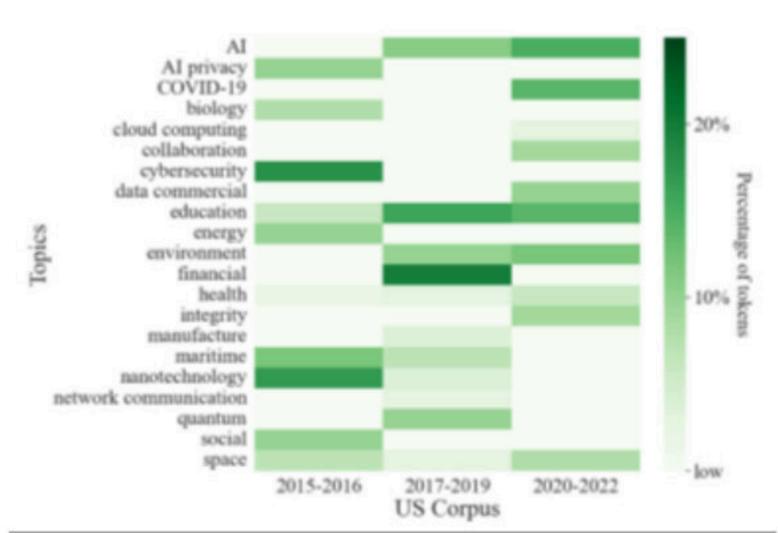
LDA model building

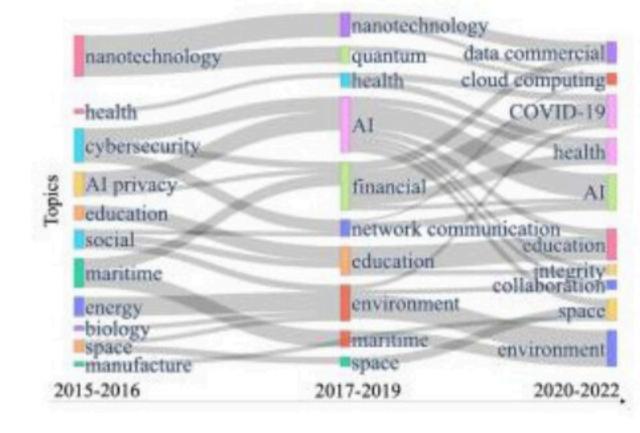


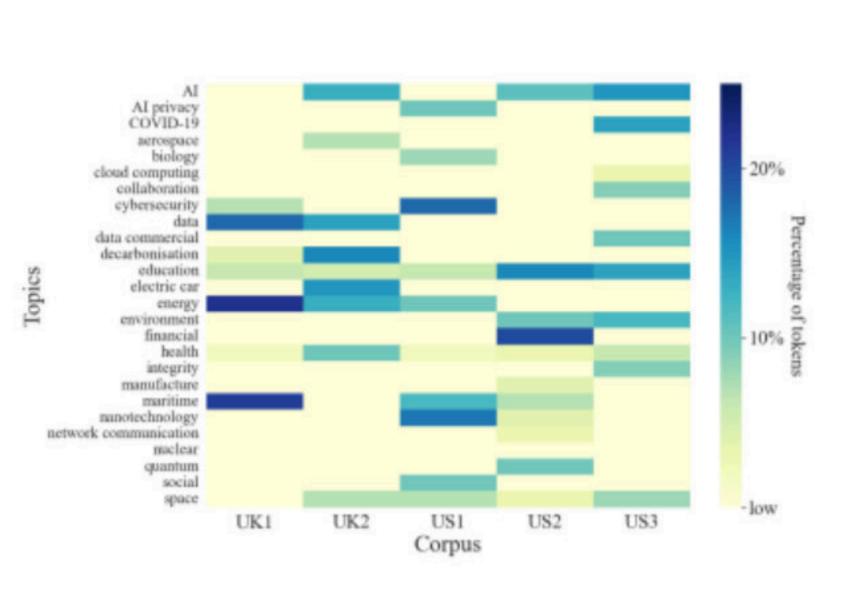
Results

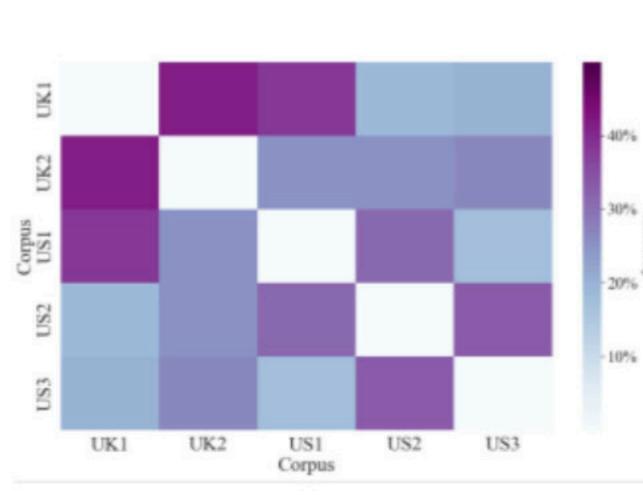




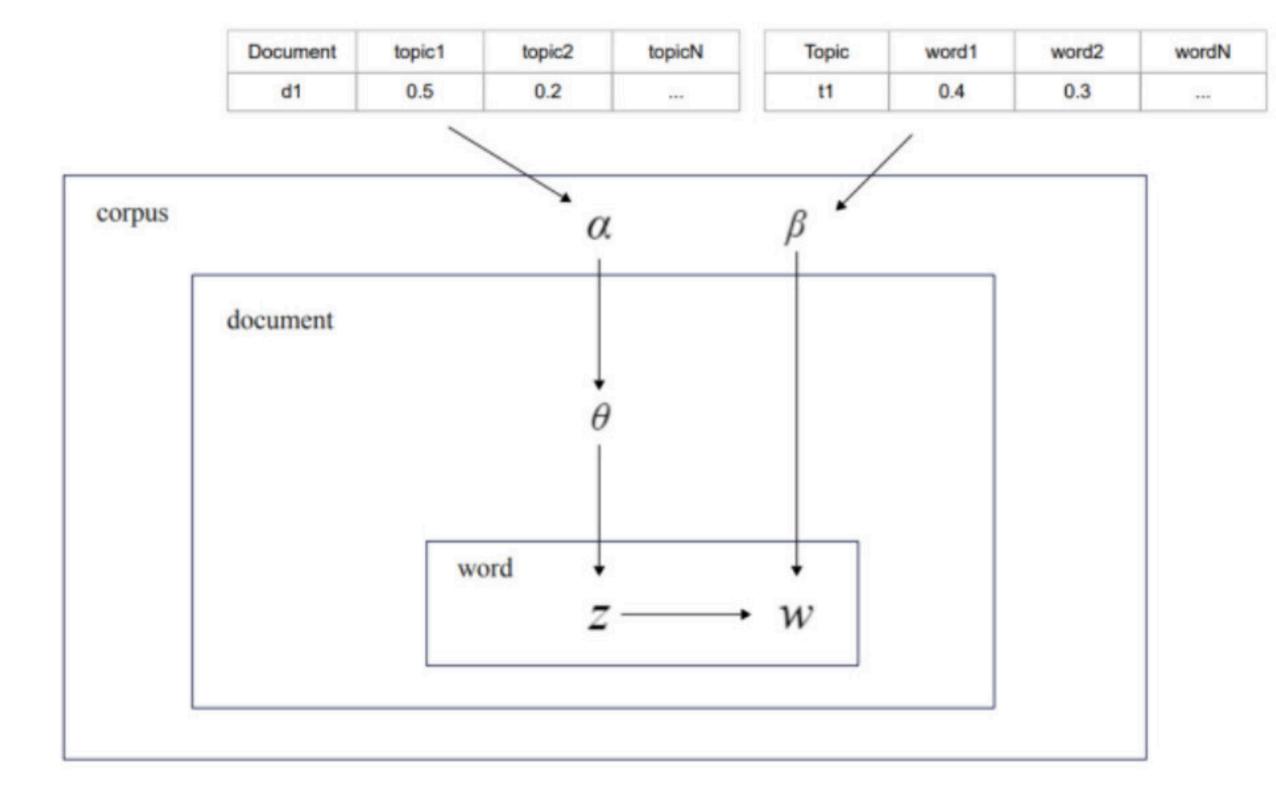








Latent Dirichlet Allocation Topic model



Discussion

- Topics of technology policies develop rapidly, but with continuous trends.
- Comparison between UK and US technology policy. Similarities: Highlight security issues in cyber and AI, social aspects, digital intelligent, and global collaboration. Differences: Energy (UK) or environment (US). The US highlights more on the fundamental research and COVID-19.

Conclusion

- The LDA topic model discovers topics in the UK and US technology policy from 2015 to 2022.
- Data visulisation: the heatmap compares topics in different time windows and the Sankey diagram shows the evolution of topics. The similarity diagram shows the evolution pace and comparison.
- Further research: smaller time windows, more model evaluations.



Tool for Planning and Visualising Traffic Movements

Yida Tao

Project Leader: Dr Alan Wong



Background & Objective

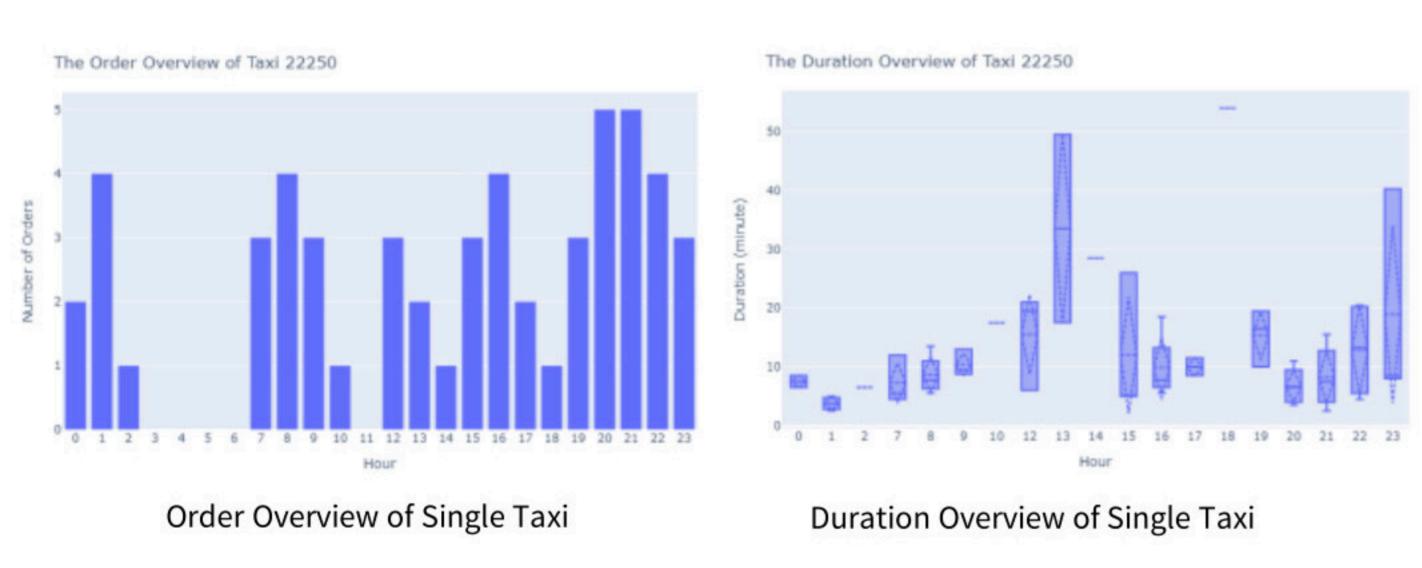
Blended user demand:

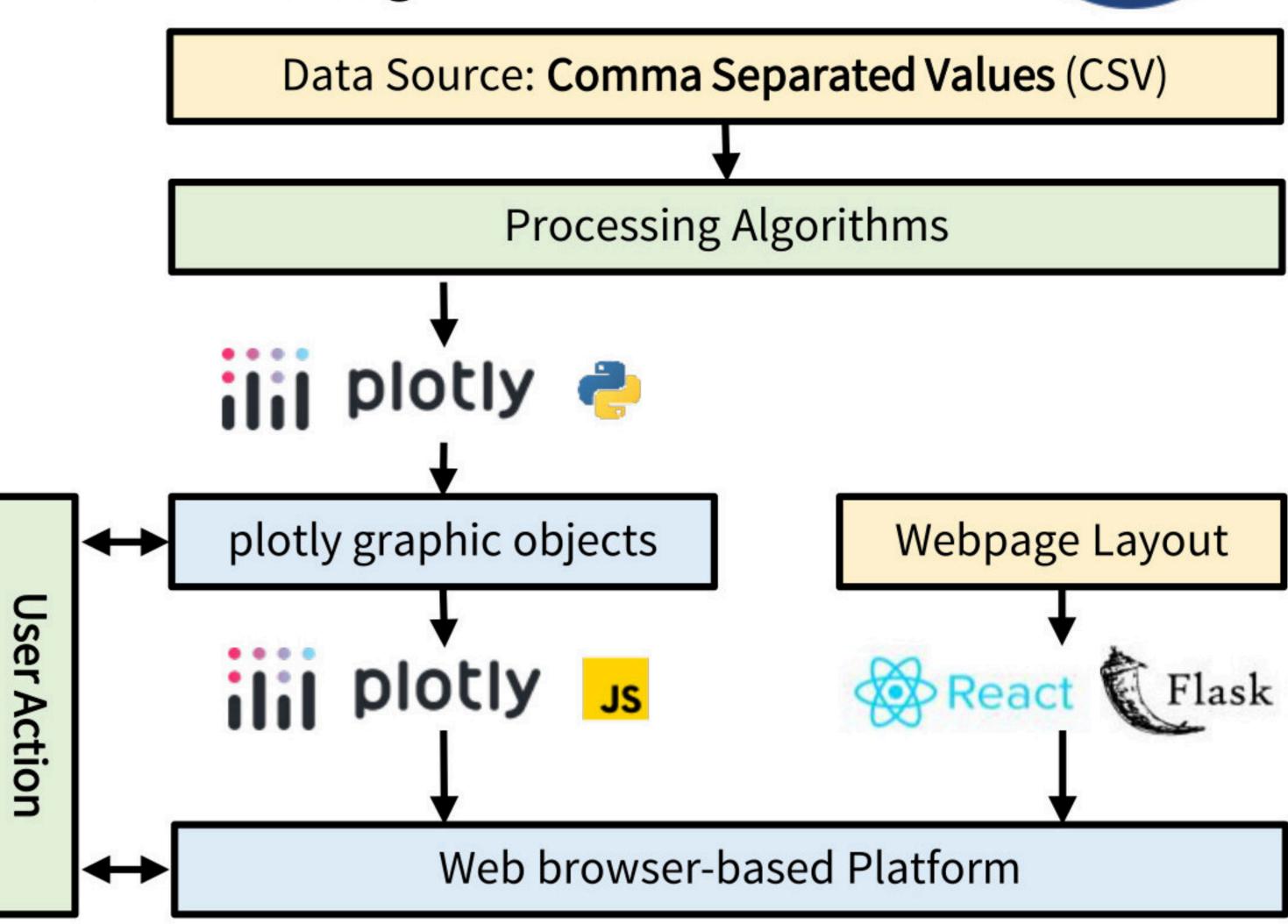
- Individual traveller: planning most efficient routes
- Traffic administrator: Analysing large scale of traffic flow data for traffic network optimisation

This project uses the traffic flow data collected by Local Authorities of Shenzhen City, China, aiming implement an integrated and lightweight solution for analysing and visualising traffic movements, as well as assisting route planning, which is also accessible to various user groups. Multiple statistical modeling techniques and machine learning models are employed. The results are visualised in web browsers with interactivity.

Functionalities

- Taxi Operation Analysis
- Metro Station Card Analysis
- Point of Interest Discovery
- Route Planning





Human-Computer Interaction

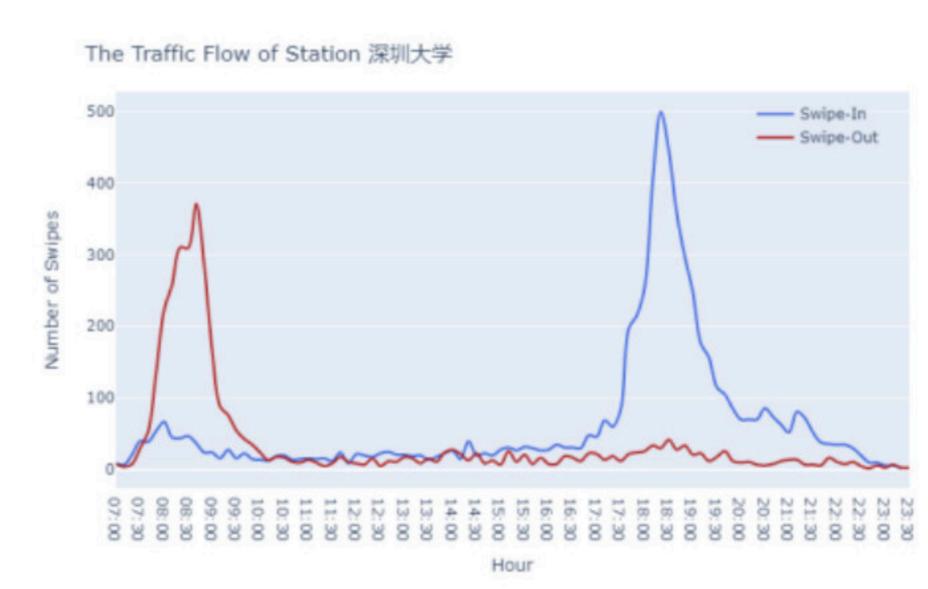
- Achieved by Callback Functions
- Supports dropdown selecting, text input and camera operation
- Mouse-hovering panel displaying detailed information of data entities

Taxi Operation Analysis

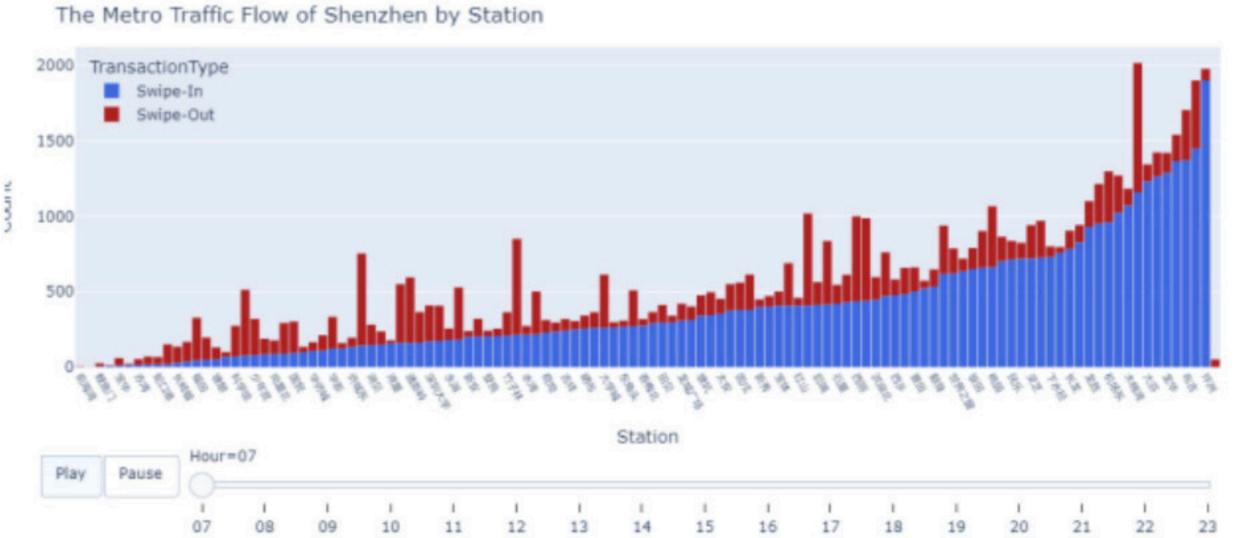
- Origin-Destination (OD) Extraction
- Order / Duration Overview of all taxis and selected object
- Pick-up and drop-off block
- Speed status / geospatial trace with occupation status

Metro Station Card Analysis

- Metro Traffic Flow (By station or administrative division)
- Traffic Flow of Selected Metro Station
- Sunburst of passenger flow in morning and evening peaks



Metro Traffic Flow of St. Shenzhen University



Metro Traffic Flow of Shenzhen by Station



Metro Route Planning (from St. Xiasha 下沙 to St. Buji 布吉)

Route Planning

- Enabling origins and destinations selected by user
- Supports road network and metro network
- One optimal solution based on Dijkstra routing Algorithm



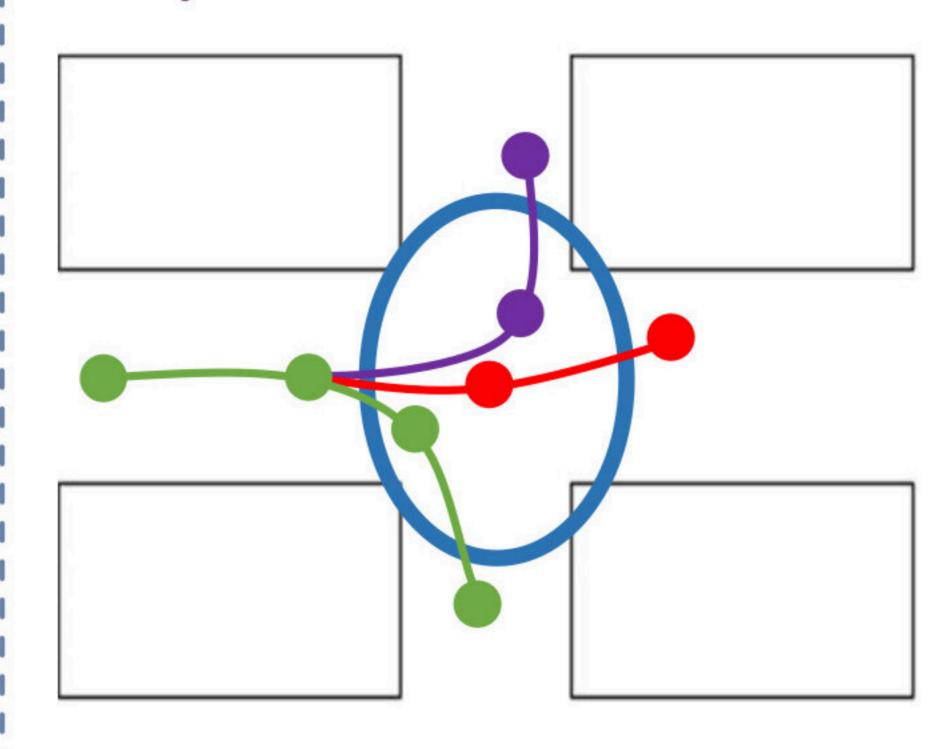
Trajectory prediction mechanism in VANET for privacy protection

Honglin Li

Project Leader: Dr Yan Sun

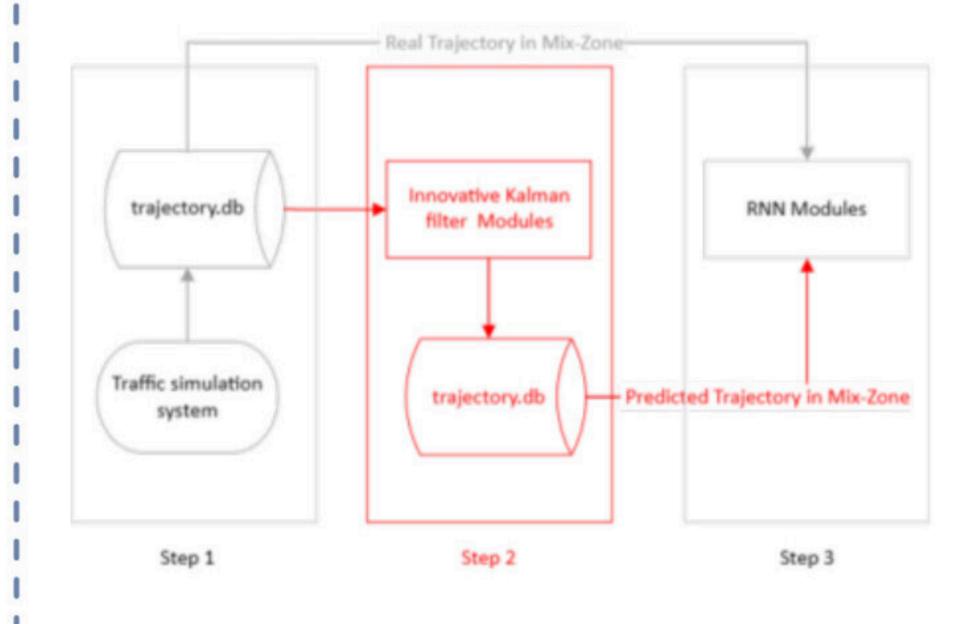
Propose Privacy protection solutions

Develop a trajectory prediction mechanism for generating fake trajectories to deceive attackers



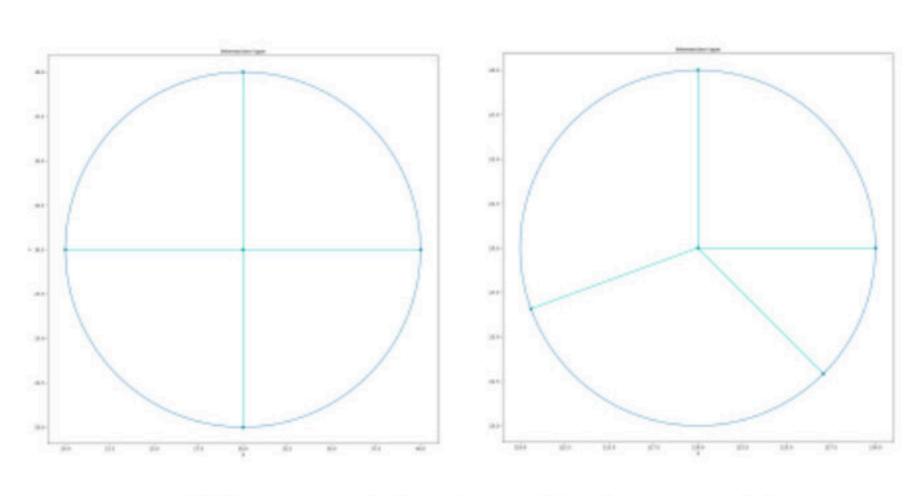
- • Real trajectory in the mix-zone
- • Predicted trajectory in the mix-zone
- • Fake trajectories in the mix-zone

Solution Structure



✓ Outcome 1: Traffic Simulation system

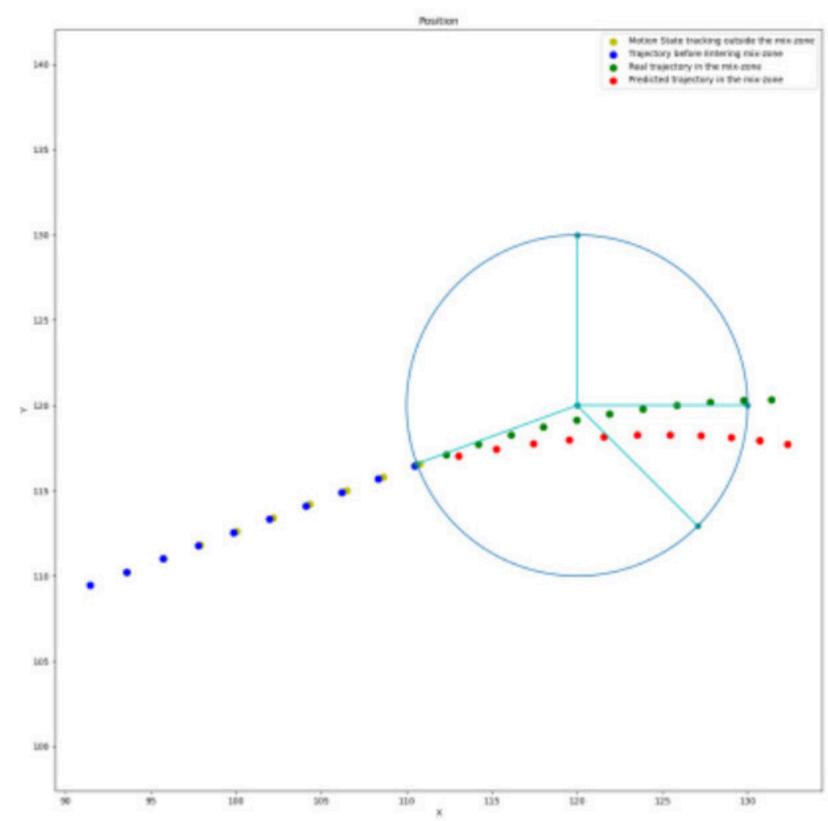
- The simulation system generates simulated data according to different intersections and vehicles
- The data is stored in the supporting database



Different kinds of intersections

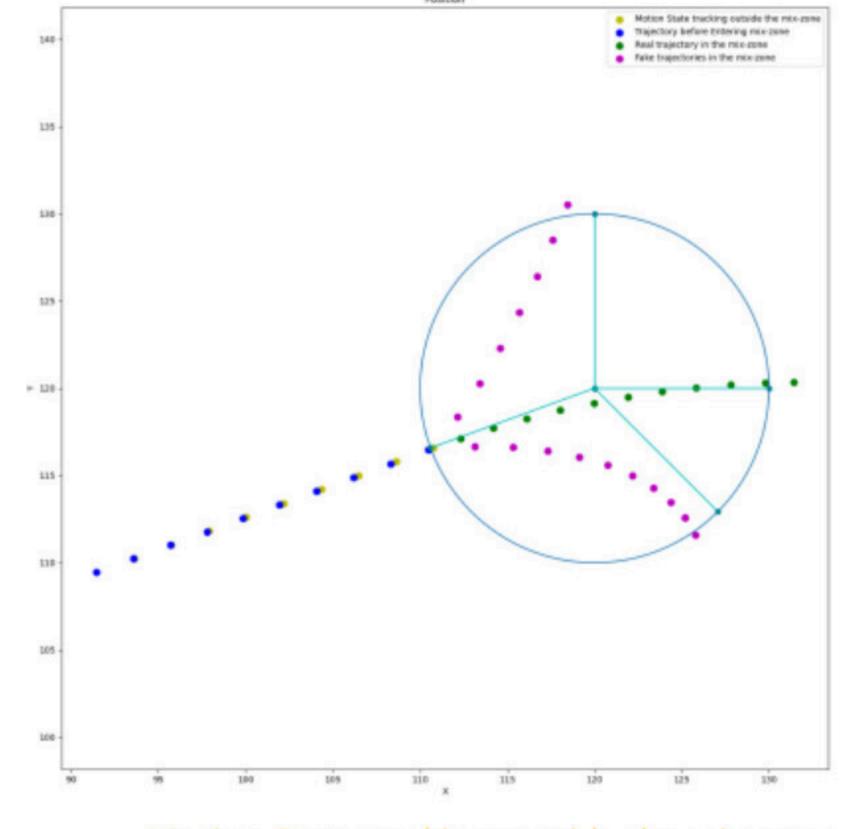
✓ Outcome 2: Innovative Kalman Filter Algorithm • • • Vehicle trajectory prediction

In Mix-zone, the red predicted trajectory is very close to the green real trajectory. And exit the Mix-zone from the same intersection.



Fake trajectory generation

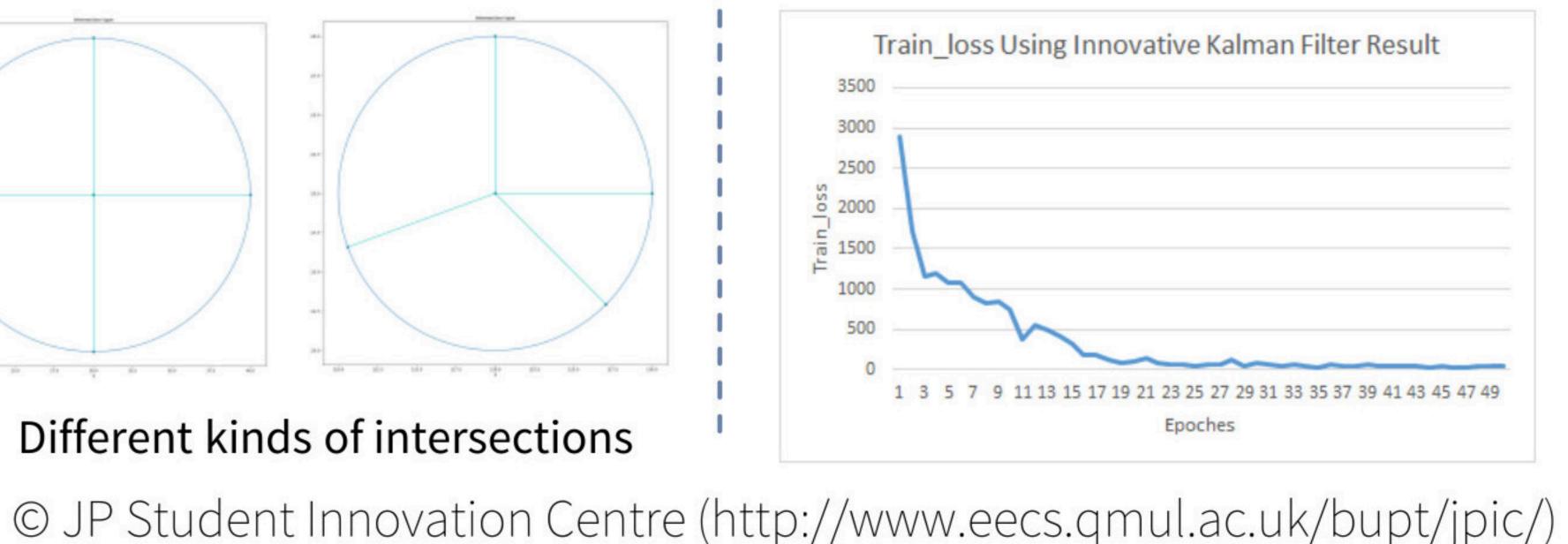
In Mix-zone, the algorithm generates two purple fake trajectories, which leave the Mixzone from other two intersections.



- • Motion State tracking outside the mix-zone
- • Trajectory before Entering mix-zone
- • Real trajectory in the mix-zone

✓ Outcome 3: RNN Optimization

- Goals: make the predicted trajectory closer to the real trajectory
- Input: real trajectory & predicted trajectory (two time series)



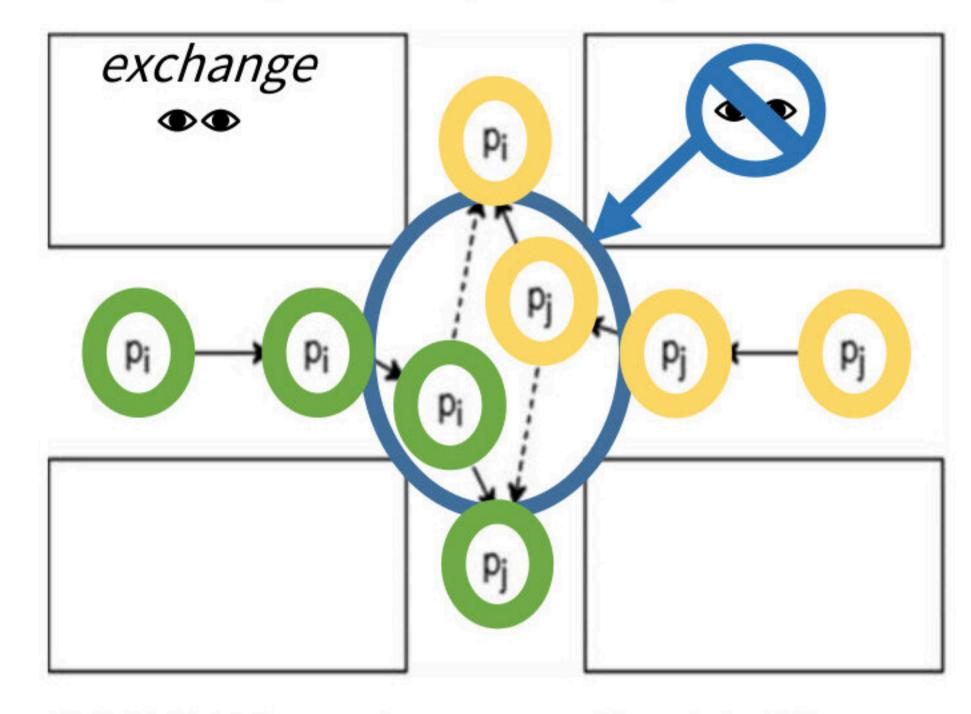
Project Objective

Research the security threats and propose privacy protection solutions

Background

Privacy protection in VANET

- Pseudonym exchange mechanism: Vehicles exchange their VANET index with each other
- Mix-zone mechanism: Set a specific area to perform pseudonym



Pj & Pi: Vehicle pseudonyms O: Yellow car

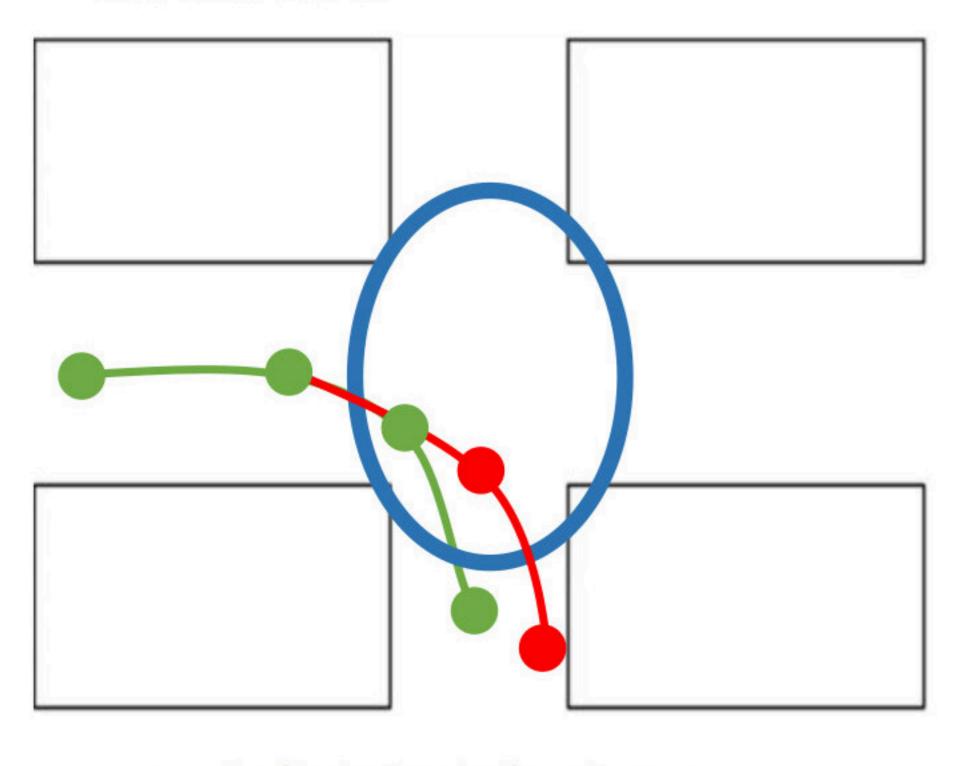
Blue circle: Mix-zone O: Green car

Aim of privacy protection:

✓ The attacker cannot trace the vehicle trajectory in the Mix-zone

Security threats

It is possible for attackers to use advanced trajectory prediction techniques to trace trajectories in the mix-zone



- Real trajectory in the mix-zone
- • Predicted trajectory in the mix-zone